

BOOST-R-BOTS™

Educational Robot Kit



Instructions – Model #: MRT3

- The Boost-R-Bot curriculum is designed to help students learn essential STEAM concepts through robotics.
- Includes step-by-step and systematic building instructions.

Instructions – No. modèle : MRT3

- Le curriculum de Boost-R-Bot est conçu pour aider les élèves à apprendre les notions essentielles de STEAM par l'intermédiaire de la robotique.
- Inclut des instructions systématiques étape par étape.

Instrucciones – No de modelo: MRT3

- El currículo de Boost-R-Bot está diseñado para ayudar a los estudiantes a aprender conceptos esenciales de la madre a través de la robótica.
- Incluye instrucciones de construcción paso a paso y sistemática.

STEAM

Science | Technology
Engineering | Art | Math



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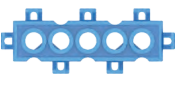
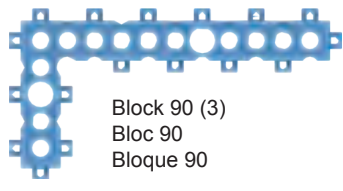
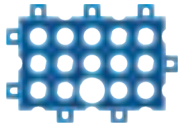
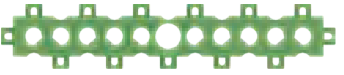
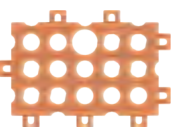
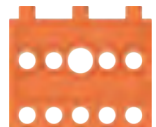

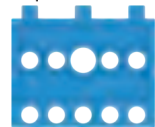
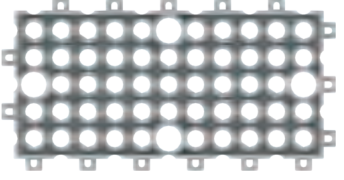
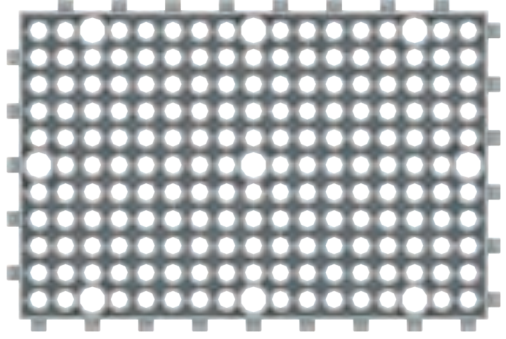

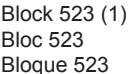
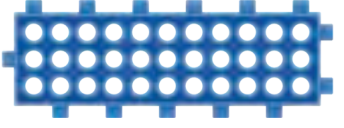


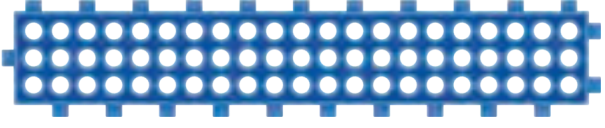




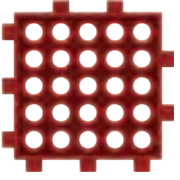

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Parts List:

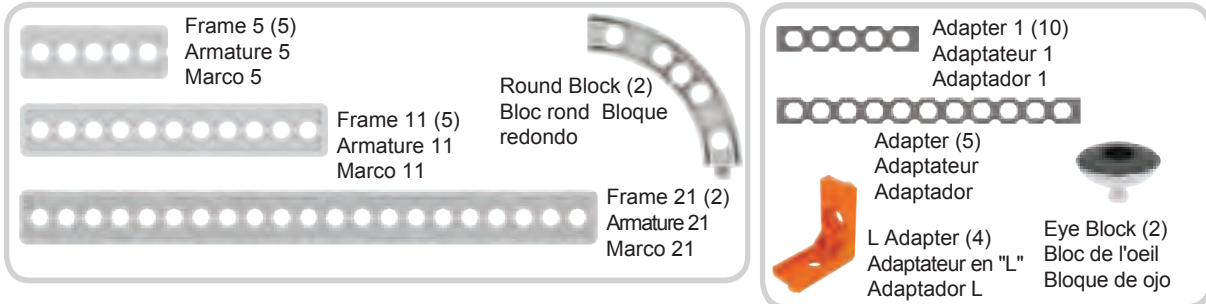
- * The form and color of some parts may be different when compared to actual parts due to continued improvement of product quality.
- * La forme et la couleur de certaines pièces peuvent être différentes par rapport aux pièces réelles en raison de l'amélioration continue de la qualité des produits.
- * La forma y el color de algunas partes pueden ser diferentes en comparación con piezas reales debido a la mejora continua de la calidad del producto.

Blocks • Blocs • Bloques

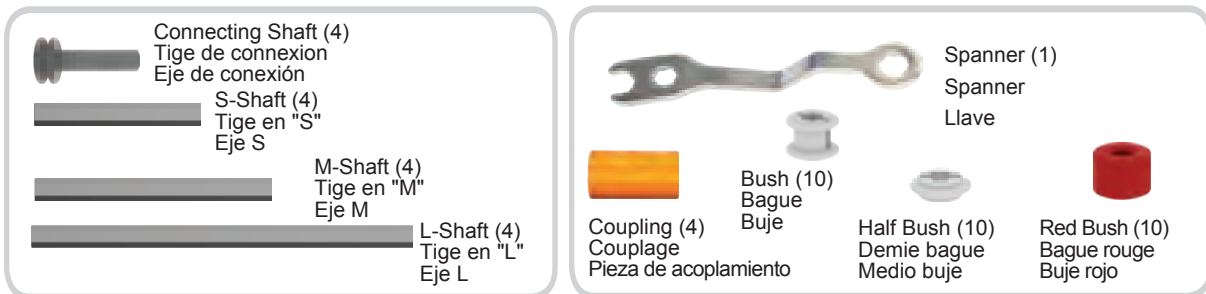
	Block 15 (5) Bloc 15 Bloque 15		Block 90 (3) Bloc 90 Bloque 90		Block 35 (3) Bloc 35 Bloque 35
	Block 111 (6) Bloc 111 Bloque 111		Block 35 (3) Bloc 35 Bloque 35		Motor Mount (2) Fixation du moteur Montaje del motor
	Block 135 (6) Bloc 135 Bloque 135		Motor Mount (2) Fixation du moteur Montaje del motor		
	Block 511 (3) Bloc 511 Bloque 511				
	Connect Block 2 (4) Connexion du bloc 2 Parte de conecta 2		Block 523 (1) Bloc 523 Bloque 523		
	Block 311 (4) Bloc 311 Bloque 311		Triangle Block (4) Bloc triangulaire Bloque de triángulo		Block 117 (1) Bloc 117 Bloque 117
	Block 321 (2) Bloc 321 Bloque 321		Shaft Block (4) Bloc de l'arbre Bloque eje		
	Connect Block 1 (6) Connexion du bloc 1 Parte de conecta 1		Gear Block (4) Bloc d'engrenage Bloques de engranaje		Crank Block (2) Bloc manivelle Bloque inestable
	Block 55 (2) Bloc 55 Bloque 55		Block 121 (2) Bloc 121 Bloque 121		

Parts List (continued)

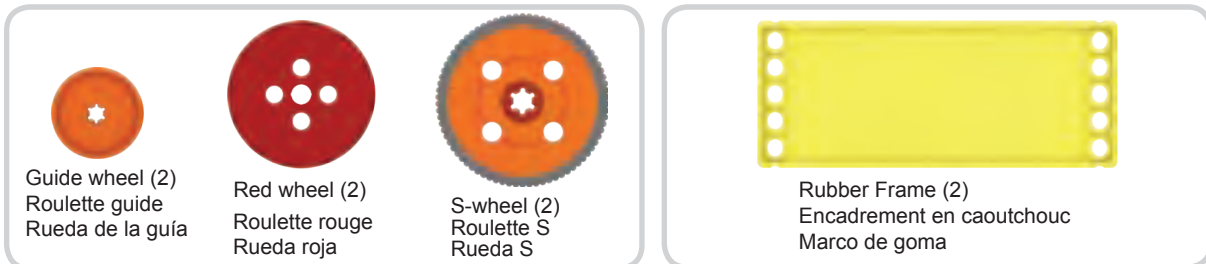
Frame/Adapter • Armature/Adaptateur • Marco / adaptador



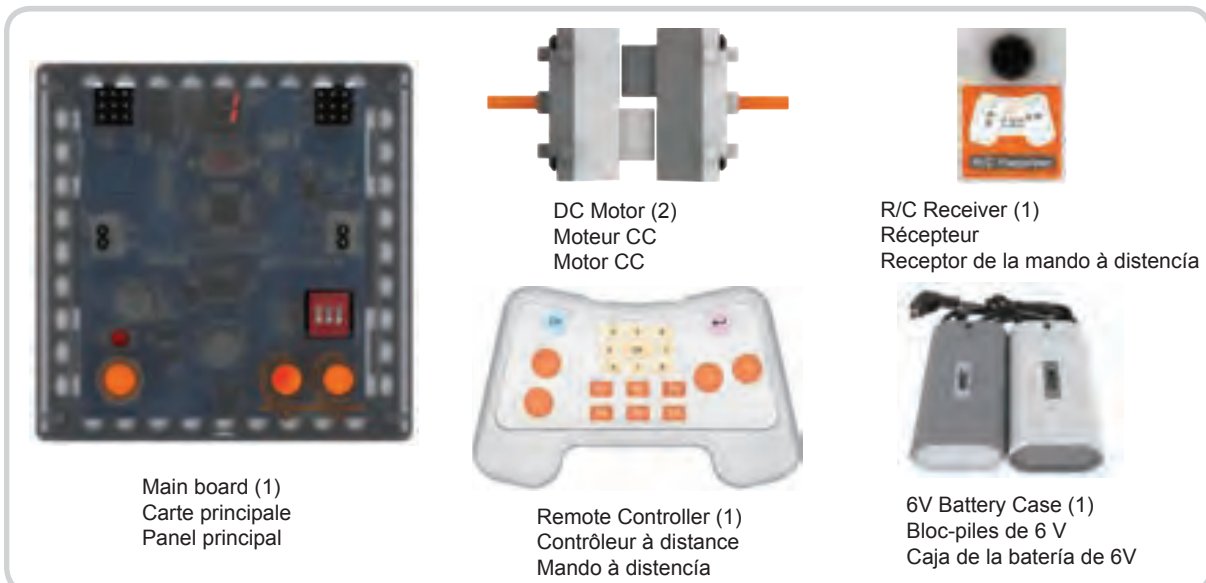
Shaft/Bush • Tige/Bague • Eje / buje



Gear / Wheel • Engrenage/roulette • Engranajes / ruedas

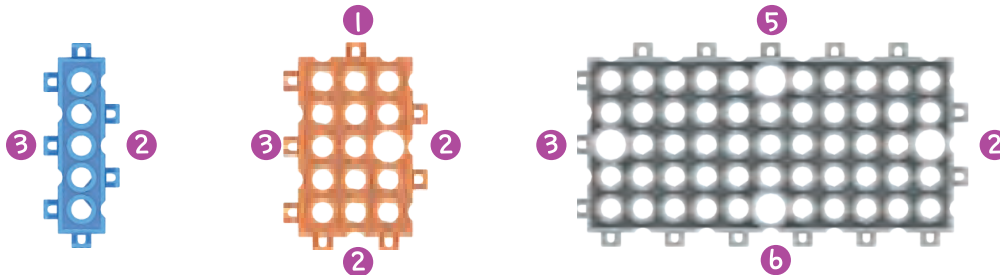


Electronic Parts • Pièces électroniques • Componentes electrónicos



Let's Learn How To Assemble Each Part and Its Function: Apprenons comment assembler chaque partie et sa fonction : Vamos a aprender a armar cada parte y su función:

Special point of blocks • Particularités des blocs • Punto especial de bloques

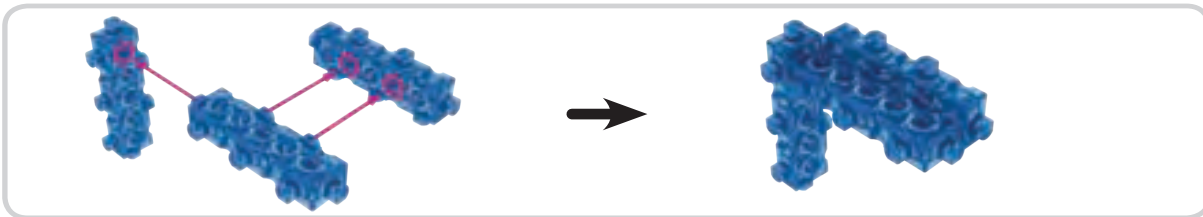


- ※ As shown above, different block structures have different number of studs. Be careful of direction when assembling.
- ※ Tel qu'indiqué ci-dessus, différentes structures de blocs ont un nombre différent de montants. Soyez attentifs à la direction lors de l'assemblage.
- ※ Como se muestra arriba, las estructuras de bloque diferentes tienen diferente número de columnas. Tenga cuidado de la dirección de montaje.

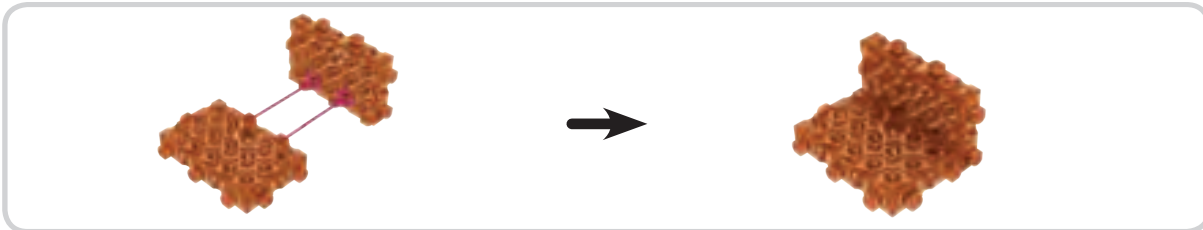
Assemble blocks • Assemblage des blocs • Reunir bloques

Blocks can be assembled in any structure. (The middle hole can be used to assemble the DC motor)
Les blocs peuvent être assemblés dans n'importe quelle structure. (Le trou central permet d'assembler le moteur à courant continu)
Bloques se pueden montar en cualquier estructura. (El orificio del medio puede utilizarse para montar el motor de la CC)

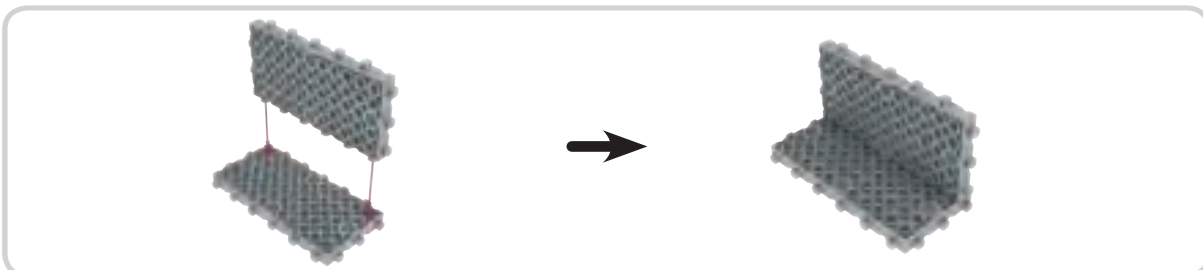
- ※ Block 15 means that it has 5 holes in a row, the left column side has 3 studs, the other side has 2 studs.
- ※ Bloc 15 signifie qu'il a 5 trous d'affilée, le côté de la colonne de gauche a 3 montants et 2 montants de l'autre côté.
- ※ Bloque 15 significa que tiene 5 agujeros en una fila, al lado de la columna de la izquierda tiene 3 postes, el otro lado tiene 2 pernos.



- ※ Block 35 means that it has 5 holes in three rows (total 15 holes), also block 35 has one side with 3 studs.
- ※ 35 bloc signifie qu'il a 5 trous en trois rangées (un total 15 trous), bloc 35 a aussi un côté avec 3 montants.
- ※ 35 bloque significa que tiene 5 agujeros en tres filas (total 15 agujeros), también bloque 35 tiene un lado con 3 tacos.



- ※ Block 511 means that it has 11 holes in five rows (total 55 holes), one side has 6 studs.
- ※ Bloc 511 signifie qu'il a 11 trous en cinq rangées (un total 55 trous), un côté a 6 montants.
- ※ 511 bloque significa que tiene 11 hoyos en filas five (total 55 orificios), un lado tiene 6 pernos prisioneros.



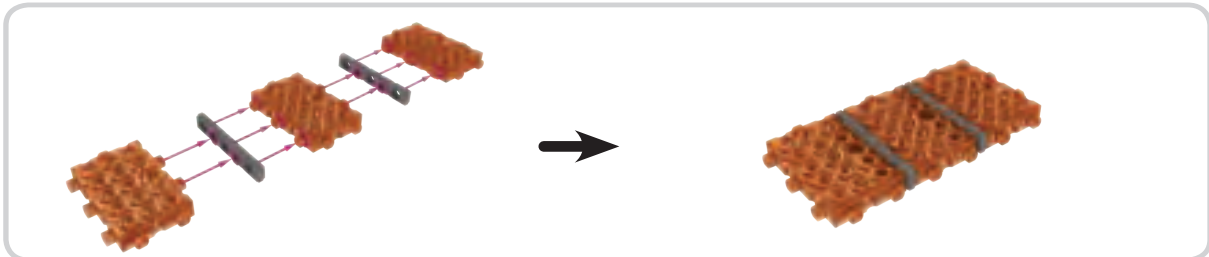
- ※ Block 90 means the block is "L" shaped with a 90 degree angle.
- ※ Bloc 90 signifie que le bloc est en forme de "L" avec un angle de 90 degrés.
- ※ 90 bloque significa que el bloque es "L" formada un ángulo de 90 grados.



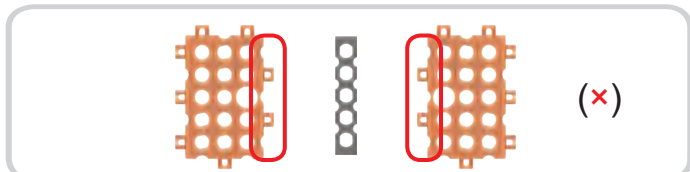
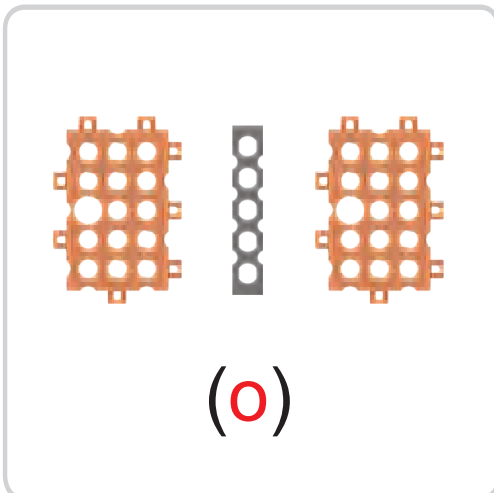
- ※ Block 135 means it has a 135 degree angle.
- ※ Bloc 135 signifie qu'il a un angle de 135 degrés.
- ※ 135 bloque significa que tiene un ángulo de 135 grados.



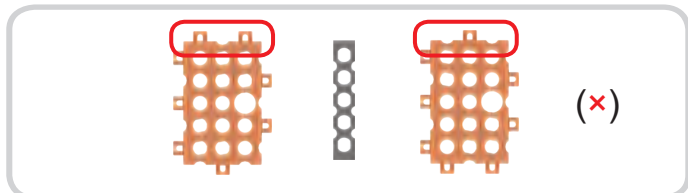
Assemble using an adapter • Assemblage à l'aide d'un adaptateur • Montar utilizando un adaptador



- ※ Some steps to note when using the adapter. • Certaines étapes à noter lorsque vous utilisez l'adaptateur. • Algunos pasos tener en cuenta cuando utilice el adaptador.



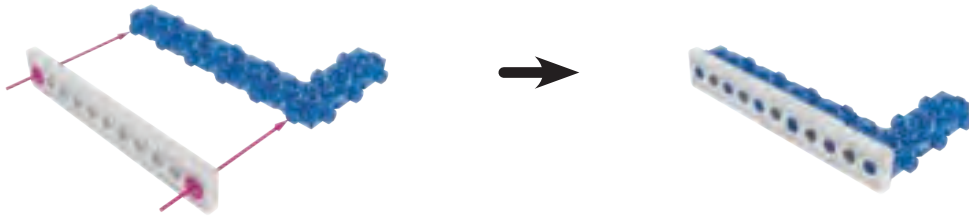
If both sides are odd or even, the block can't be assembled with adapter.
 Si les deux parties sont paires ou impaires, le bloc ne peut être assemblé avec adaptateur.
 Si ambos son pares o impares, el bloque no puede ensamblarse con adaptador.



Make sure that both upper and lower parts of the block have an equal number of studs, when assembling with adapter.
 Assurez-vous que les parties supérieures et inférieures du bloc ont un nombre égal de montants lors de l'assemblage avec adaptateur.
 Asegúrese de que las partes superiores e inferiores del bloque tienen igual número de postes, montaje con adaptador.

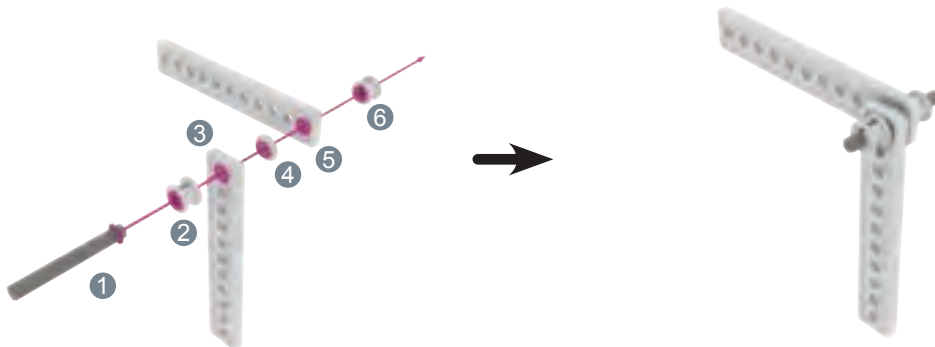
Assemble block and frame • Assemblage des blocs et du cadre • Montar el bloque y el marco

- ※ When assembling block and frame, make sure all the block studs are inserted into the frame holes.
- ※ Lors de l'assemblage des blocs et de l'armature, assurez-vous que tous les montants des blocs sont insérés dans les trous de l'armature.
- ※ Al montar el bloque y el marco, asegúrese de que todos los pernos del bloque se insertan en los agujeros del marco.



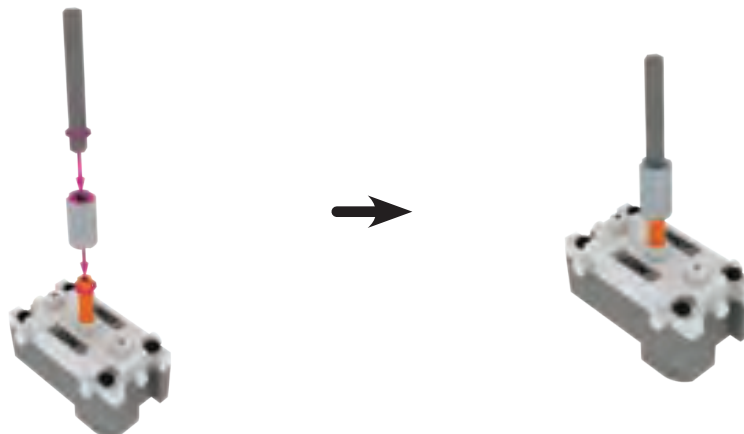
Assemble shaft and bush • Assemblage de la tige et de la bague • Montar eje y bush

- ※ Try to assemble in order • Essayez de procéder à l'assemblage dans l'ordre • Intentar montar en orden



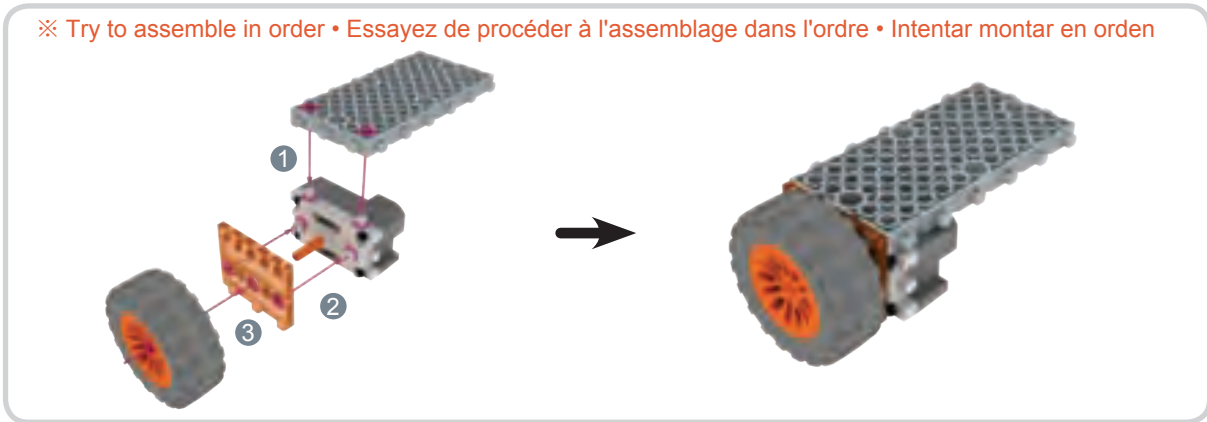
Assemble DC motor and coupling • Assemblage du moteur CC et du couplage • Montar el acoplamiento y el motor de la CC

- ※ The coupling is used to join the shaft to the motor and can be used to make the shaft longer.
- ※ Le couplage permet de joindre la tige du moteur et peut être utilisé pour allonger la tige.
- ※ El acoplamiento se utiliza para unir el eje del motor y puede ser utilizado para hacer el eje más largo.



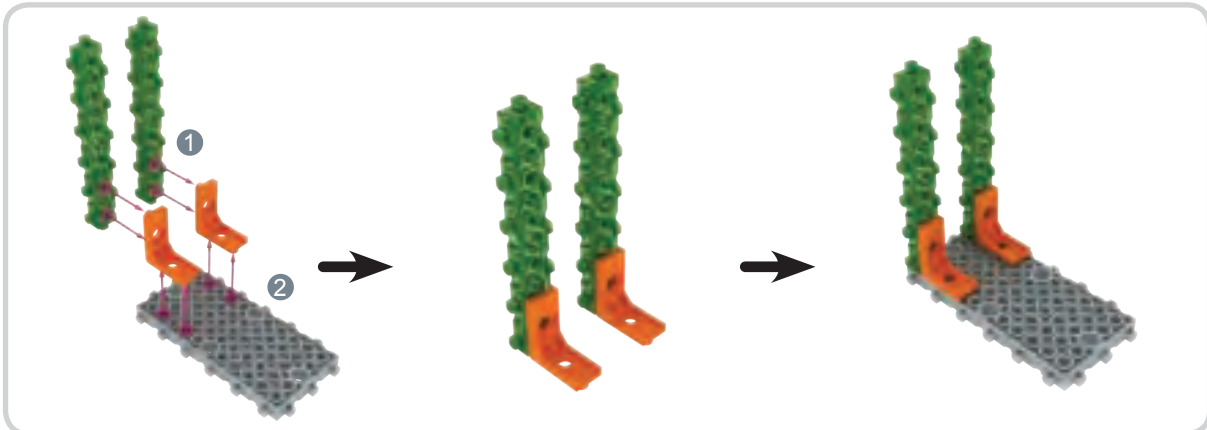
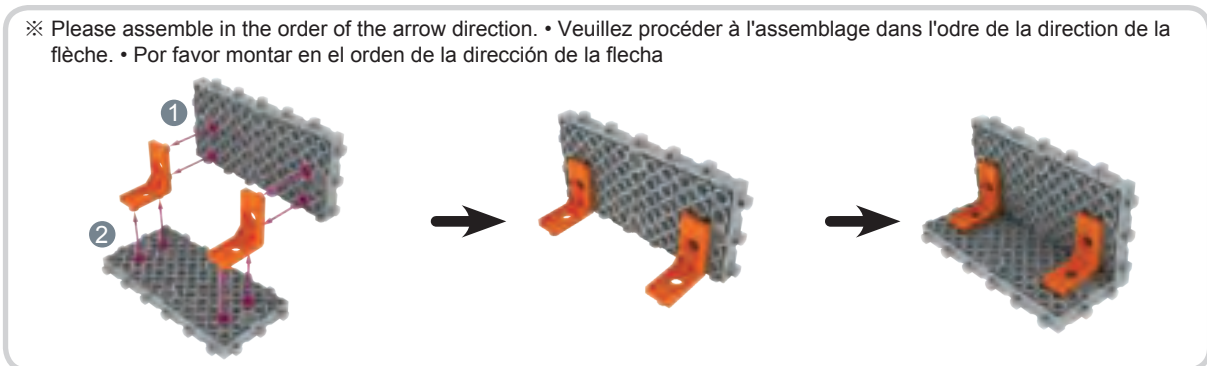
Assemble DC motor and wheel • Assemblage du moteur CC et de la roue • Ensamble rueda y motor de corriente continua

※ Try to assemble in order • Essayez de procéder à l'assemblage dans l'ordre • Intentar montar en orden

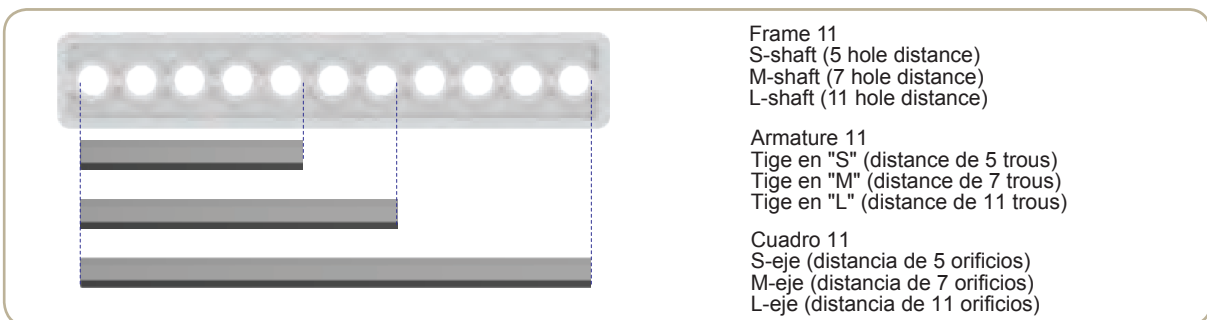


L Adapter • L'adaptateur en "L" • Adaptador L

※ Please assemble in the order of the arrow direction. • Veuillez procéder à l'assemblage dans l'ordre de la direction de la flèche. • Por favor montar en el orden de la dirección de la flecha



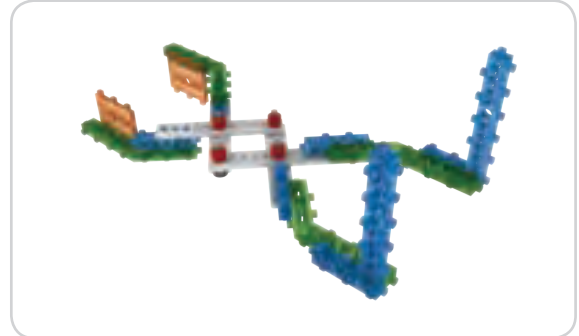
Shaft • Tige • Eje



What Robots Are We Going To Assemble? Quels robots allons-nous assembler? ¿Robots son qué vamos a montar?



1. Piglet • Porcinet • Cochinillo



2. Multiple Gadget Arms • Bras à gadgets multiples
• Múltiples brazos de Gadget



3. F-15 Fighter • Chasseur F-15 • F-15 Fighter



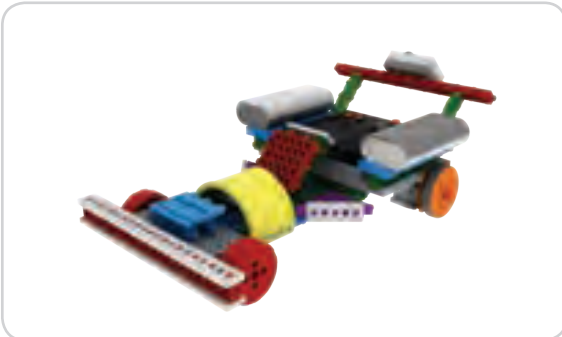
4. Three Wheeled Bicycle • Vélo à trois roues
• Tres ruedas de bicicleta



5. Apache Helicopter • Hélicoptère Apache • Helicóptero Apache



6. I am a Gymnast! • Je suis une/un gymnaste
• ¡Soy una gimnasta!



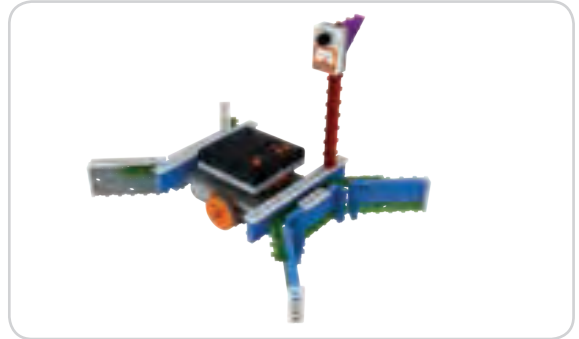
7. Mini Racing Car • Mini voiture de course
• Mini carreras de coches



8. Helicopter • Helicóptero • Helicóptero



9. Knight and Donkey • Le chevalier et l'âne • Caballero y burro



10. X-Soccer • Soccer X • X-fútbol



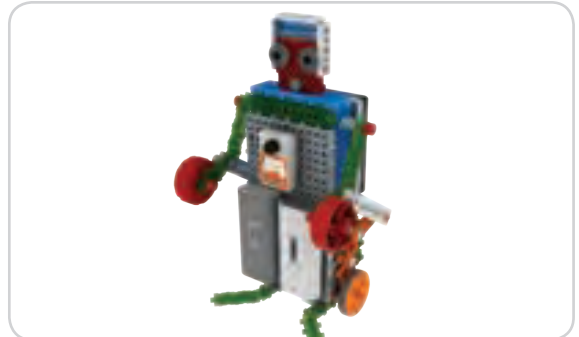
11. Drummer Baby Bear • Ourson batteur • Bebé oso baterista



12. Air Sing Sing Plane • Ton avion chantant • Avión de Sing Sing



13. Bumper Car • Auto tamponneuse • El coche de parachoques

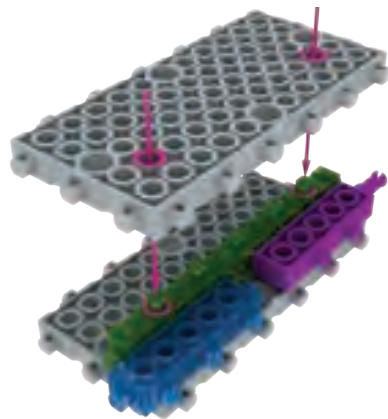
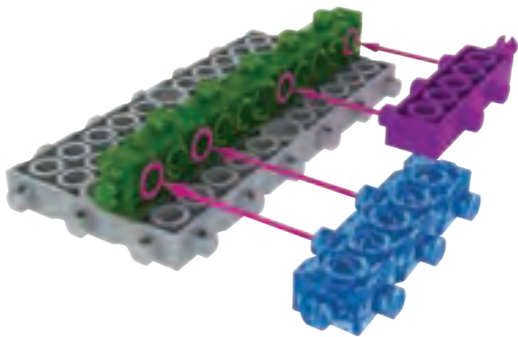


14. Boxing Robot • Robot boxeur • Robot de boxeo

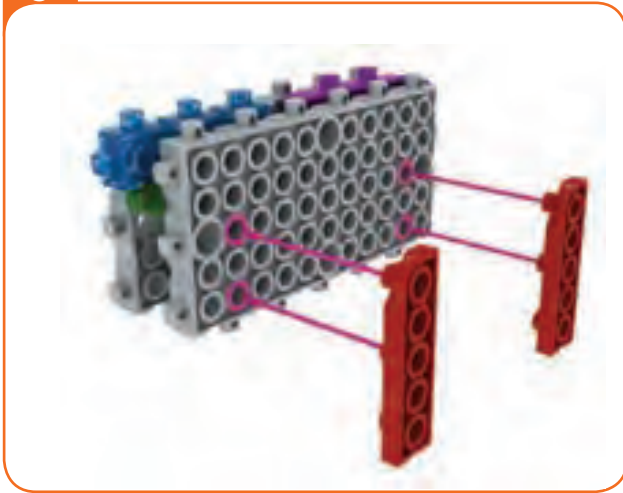


15. Battle Robot • Robot de combat • Robot de batalla

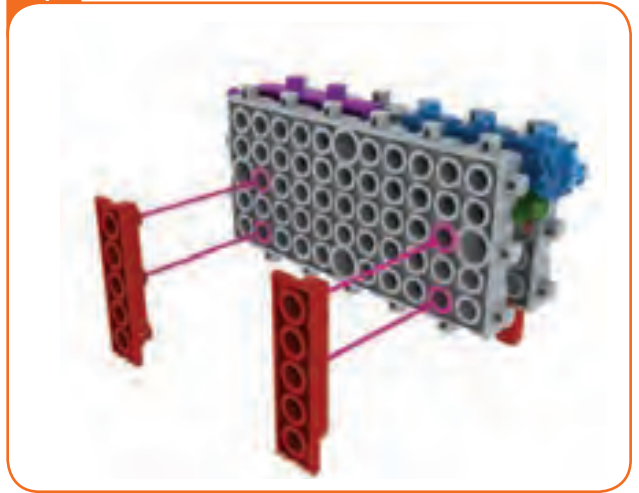
Robot 1: Piglet
Robot 1 : Porcinet
Robot 1: Cochinillo



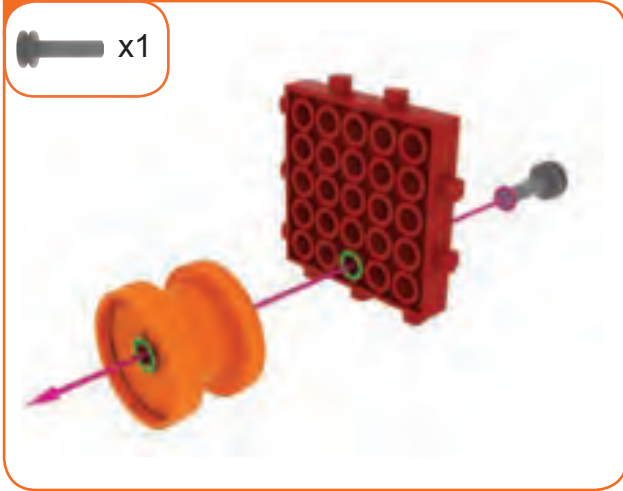
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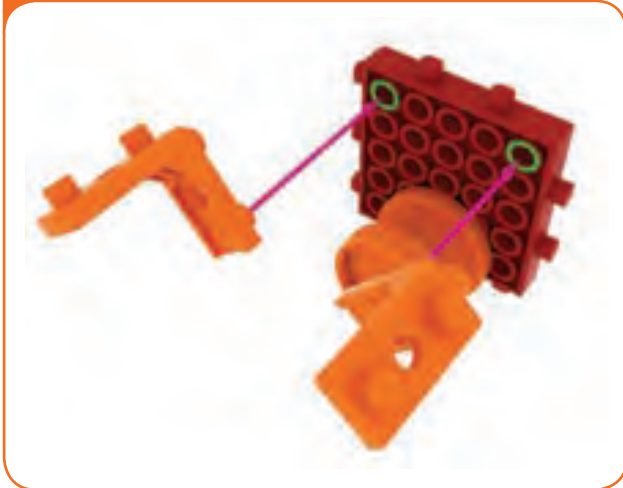
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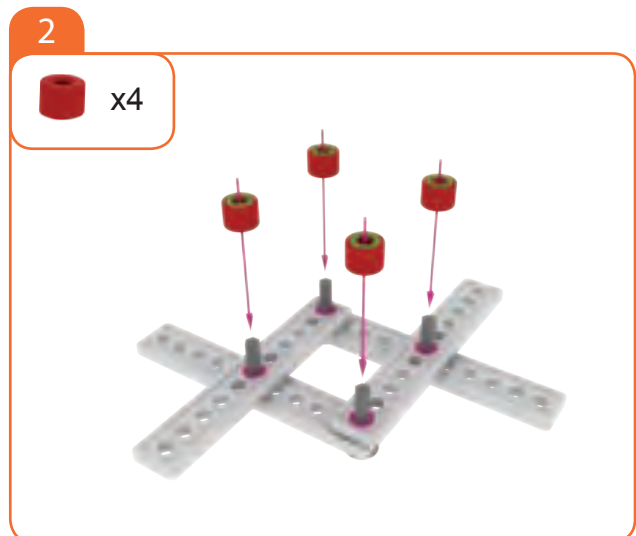
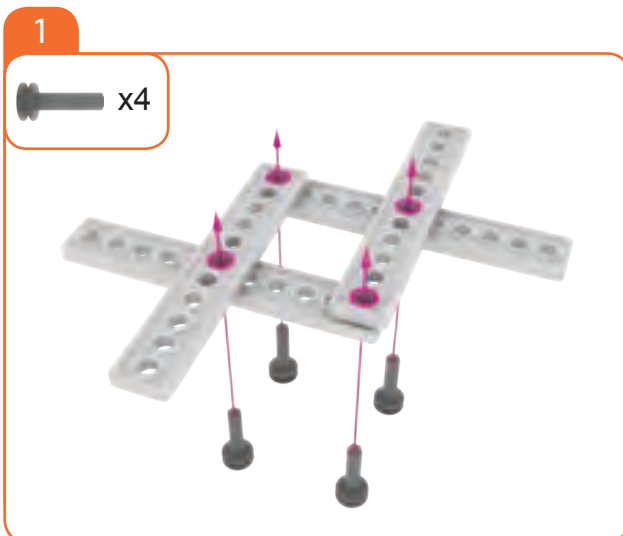
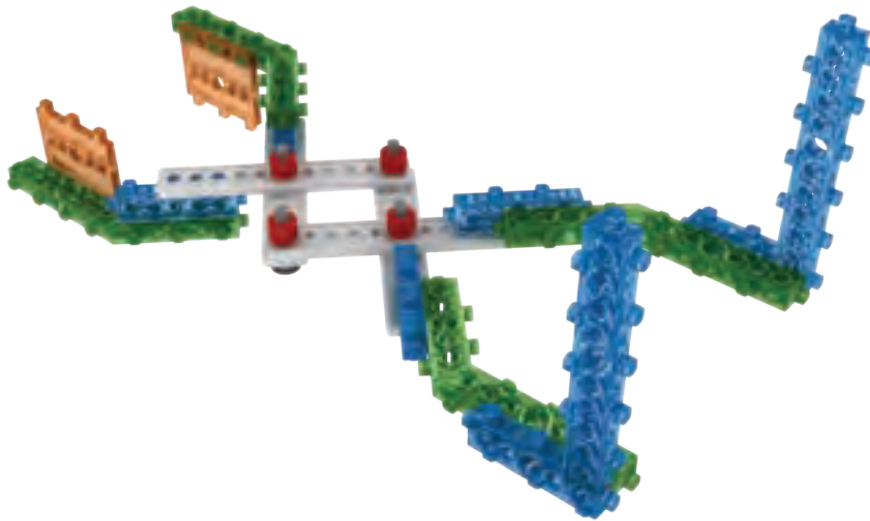
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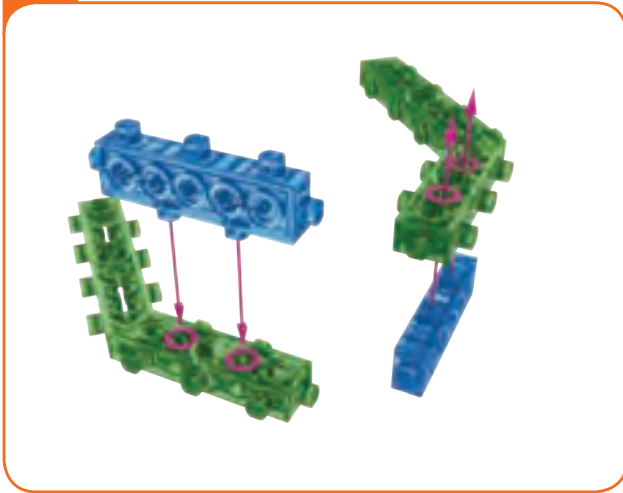
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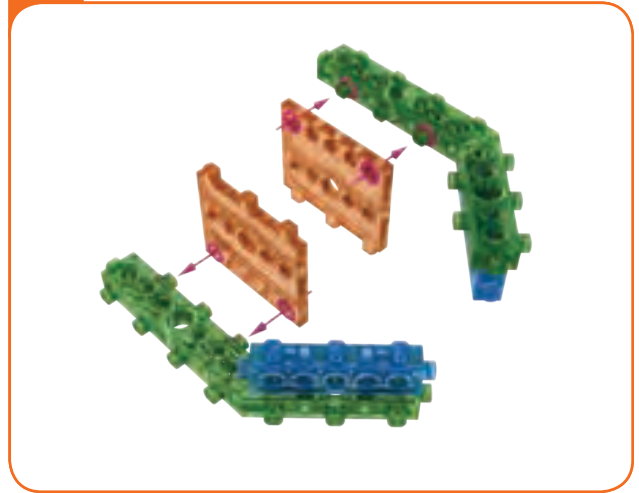
Robot 2: Multiple Gadget Arms
Robot 2 : Bras à gadgets multiples
Robot 2: Múltiples brazos de Gadget



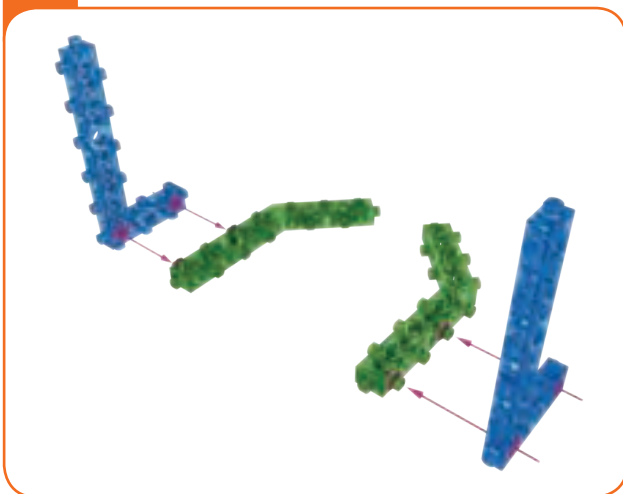
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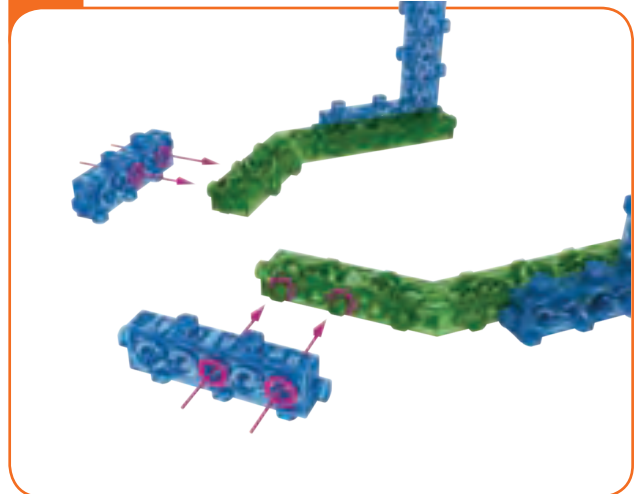
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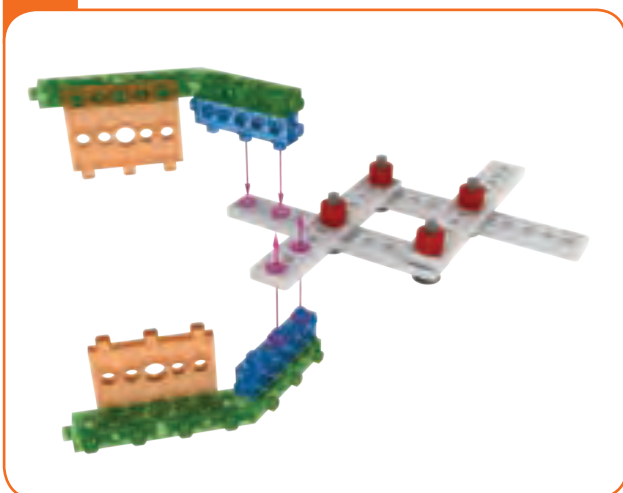
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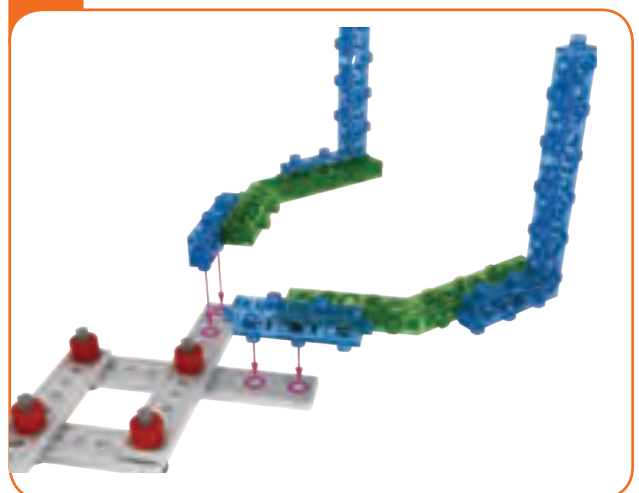
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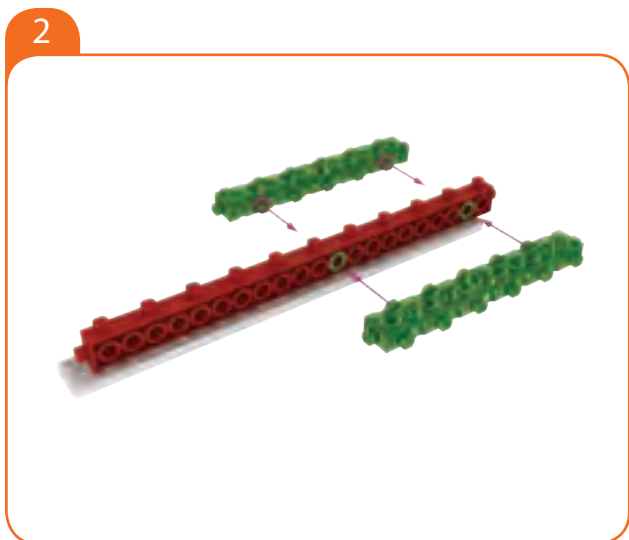
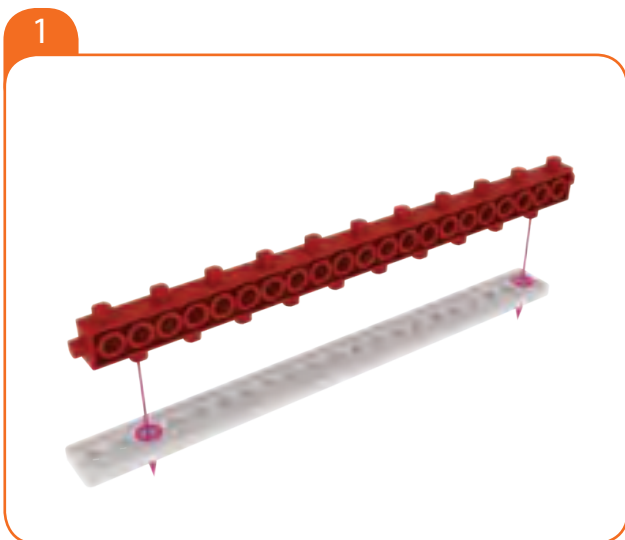
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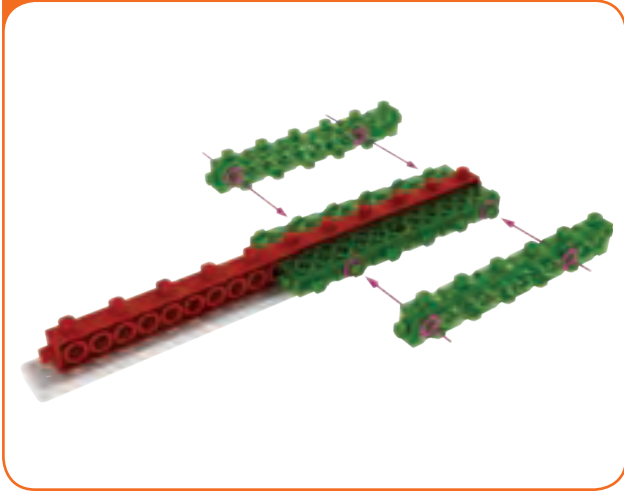
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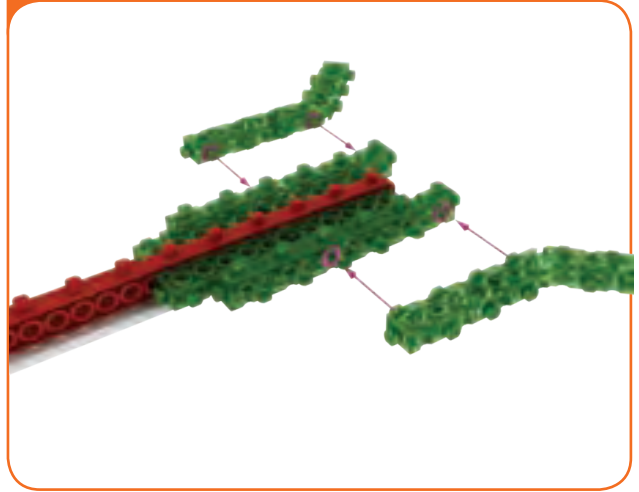
Robot 3: F15 Fighter
Robot 3 : Chasseur F-15
Robot 3: F-15 Fighter



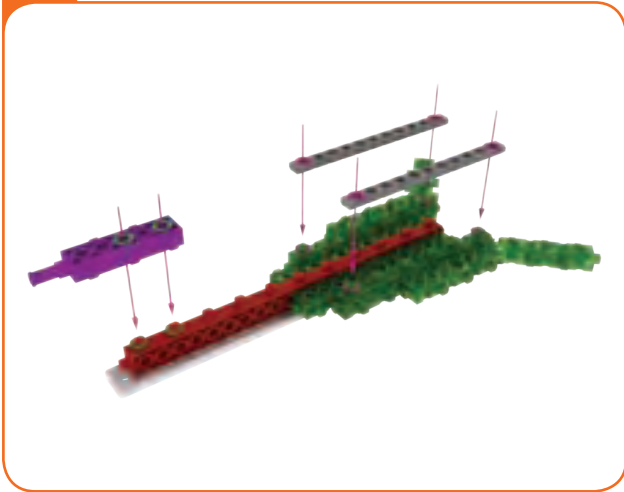
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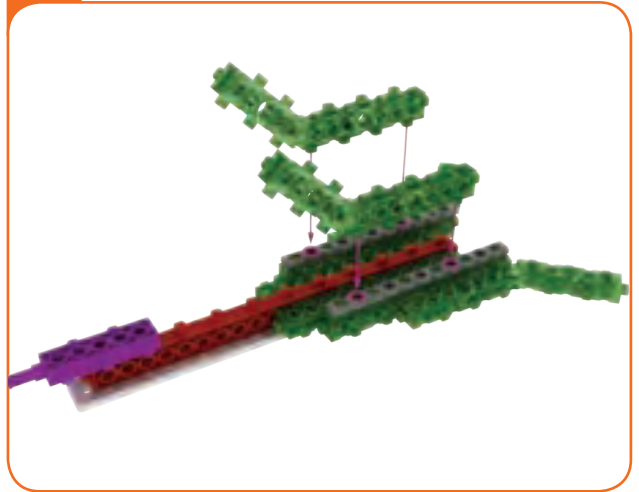
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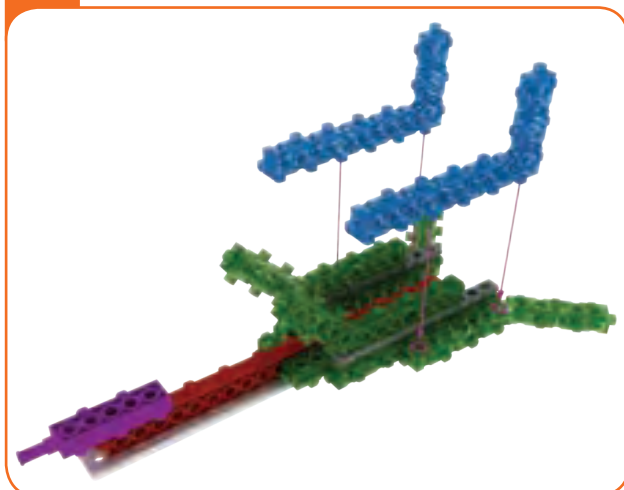
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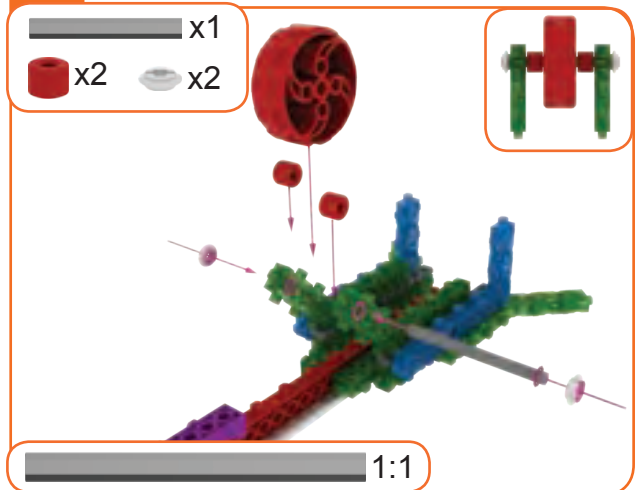
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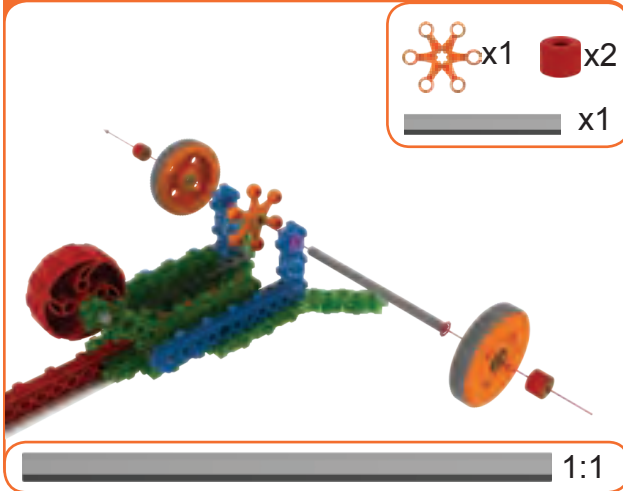
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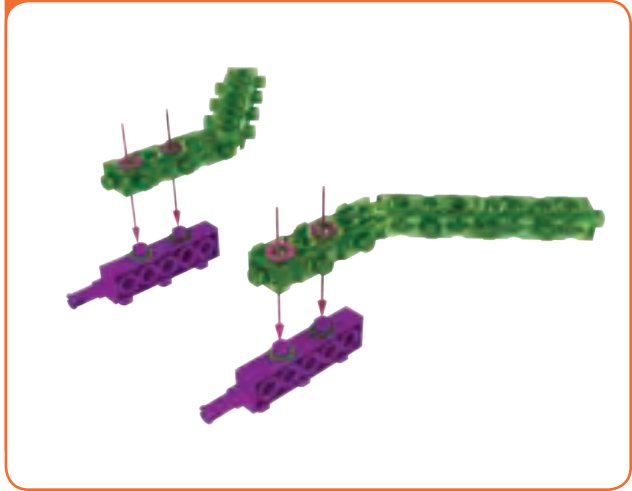
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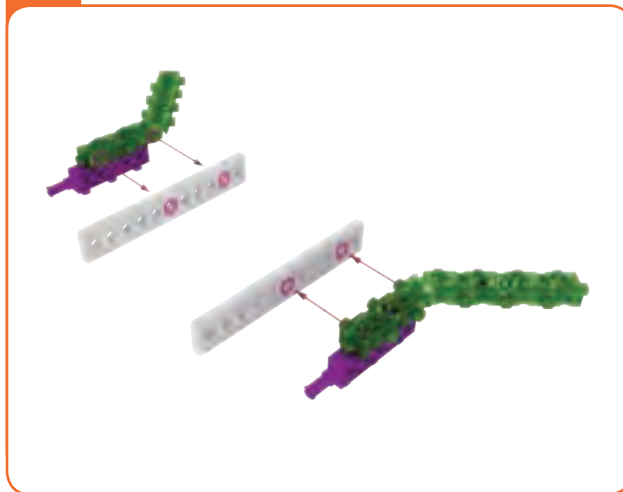
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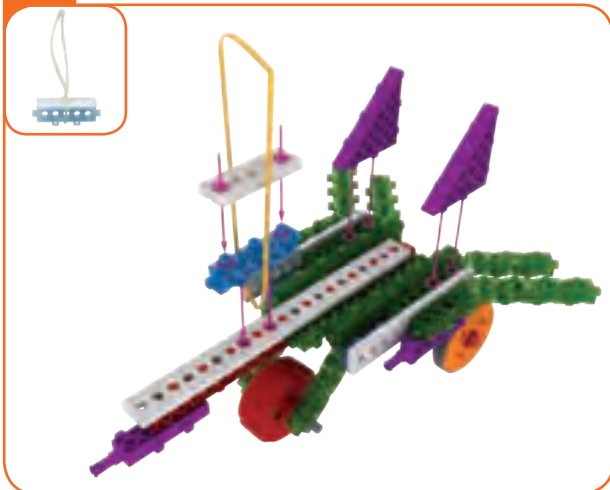
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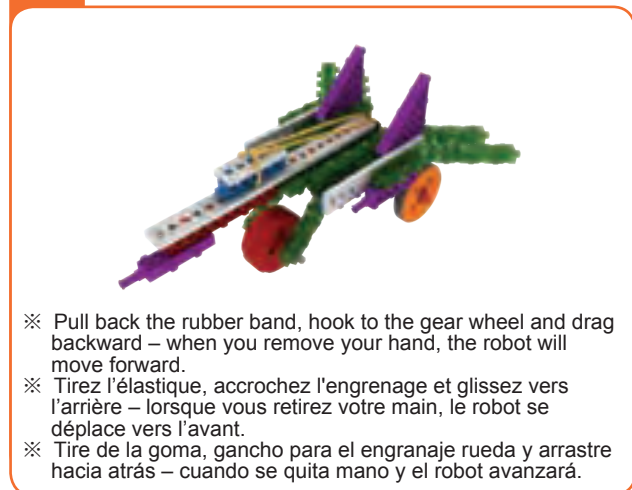
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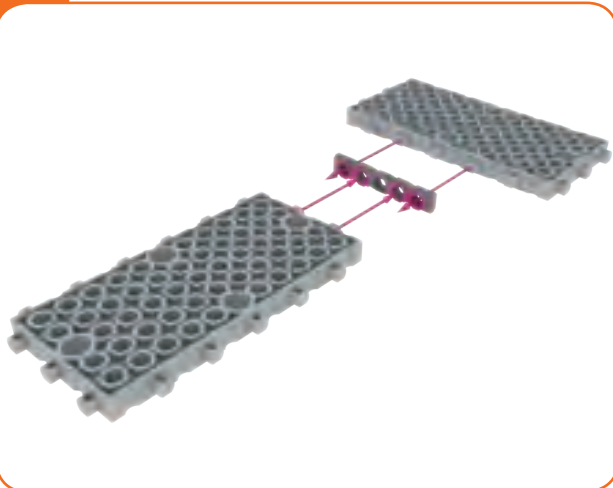


- ※ Pull back the rubber band, hook to the gear wheel and drag backward – when you remove your hand, the robot will move forward.
- ※ Tirez l'élastique, accrochez l'engrenage et glissez vers l'arrière – lorsque vous retirez votre main, le robot se déplace vers l'avant.
- ※ Tire de la goma, gancho para el engranaje rueda y arrastre hacia atrás – cuando se quita mano y el robot avanzará.

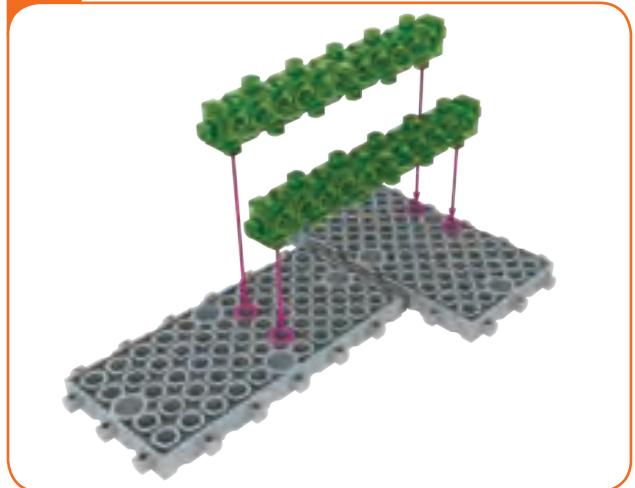
Robot 4: Three-Wheeled Bicycle
Robot 4 : Vélo à trois roues
Robot 4: Bicicletas de tres ruedas



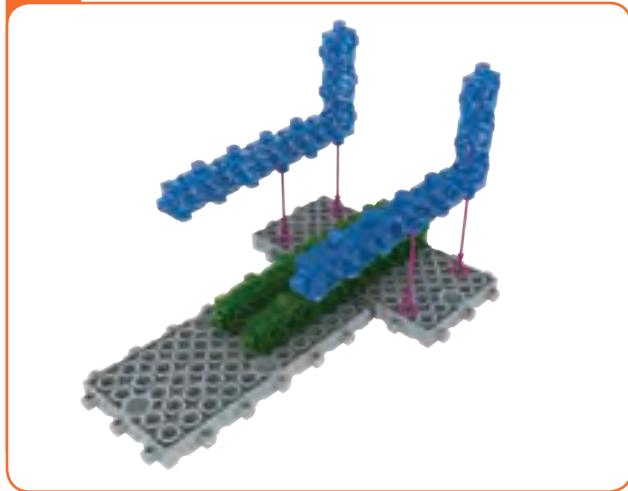
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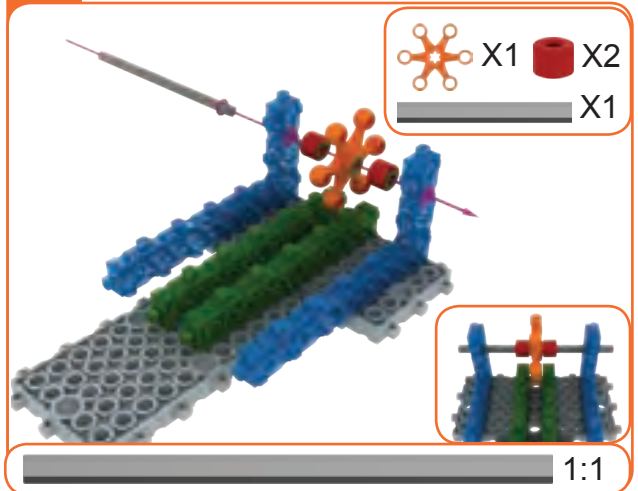
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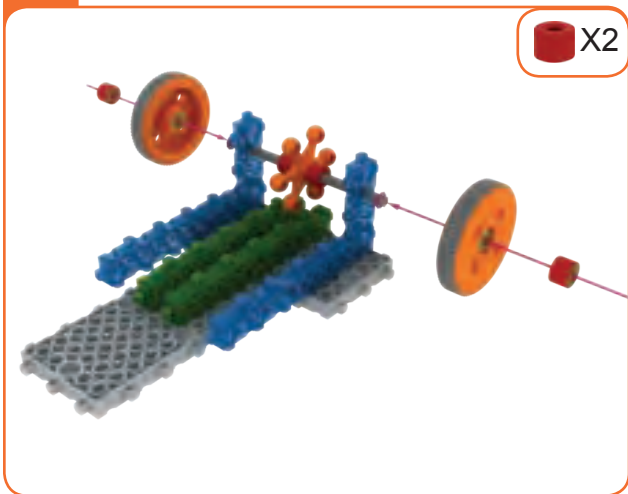
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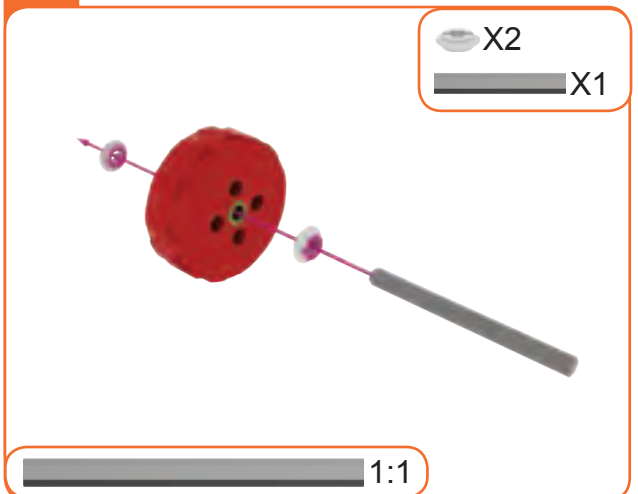
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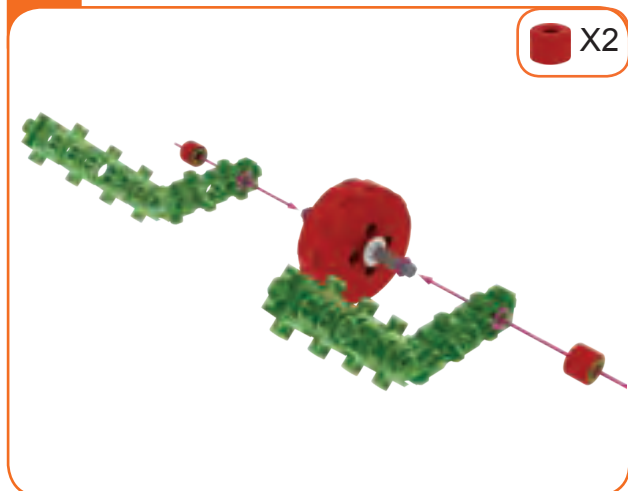
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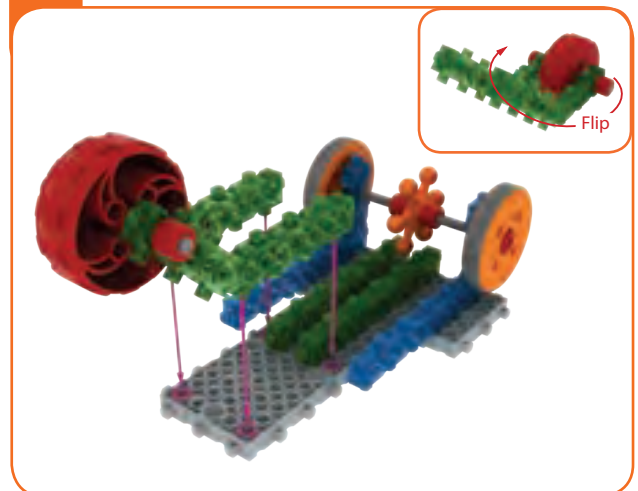
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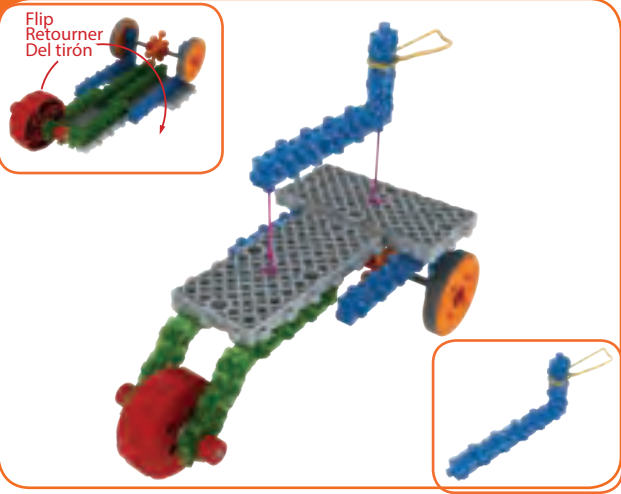
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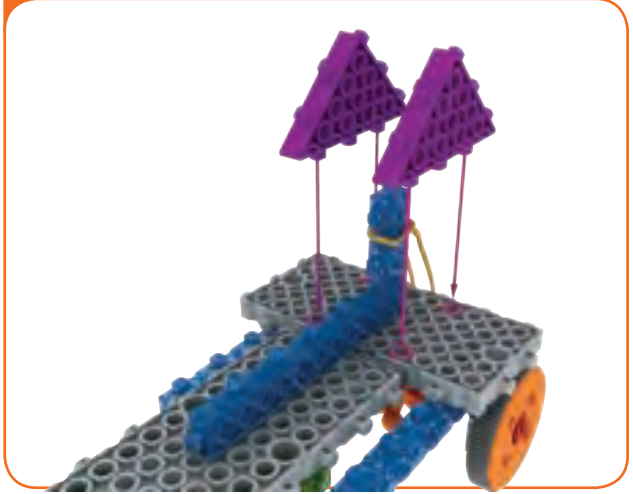
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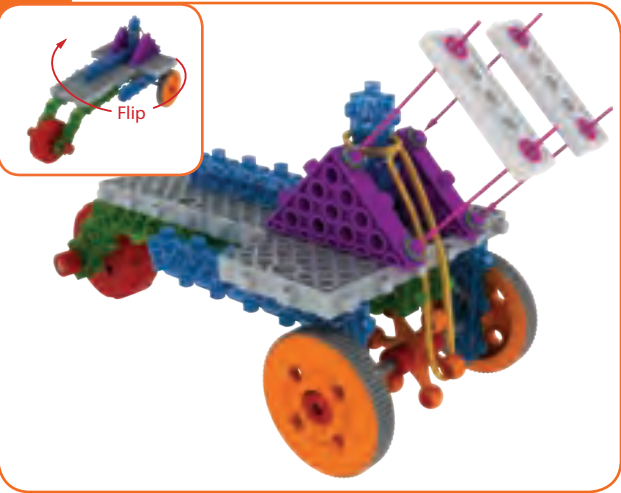
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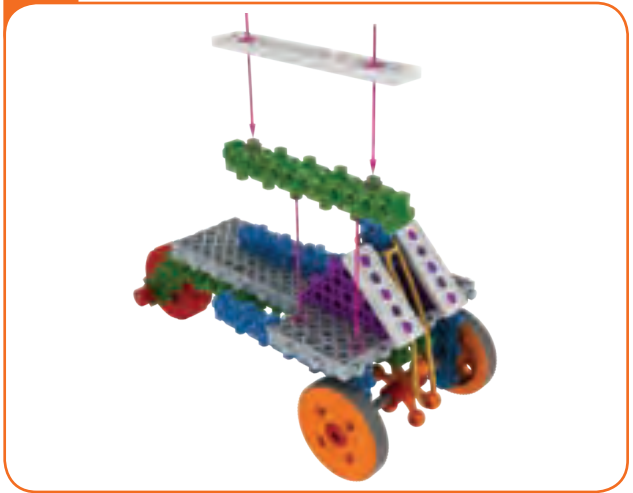
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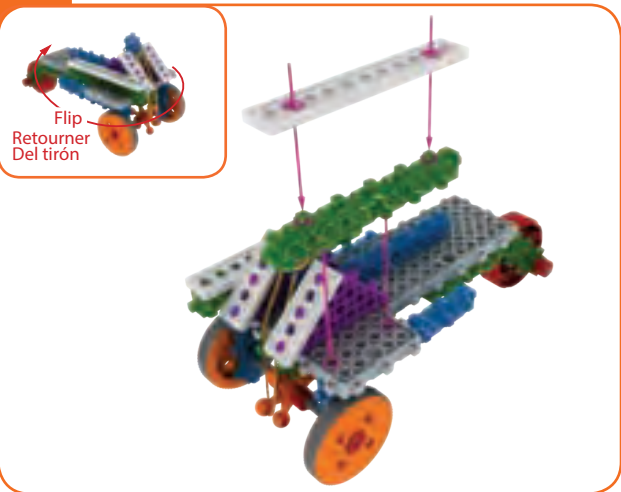
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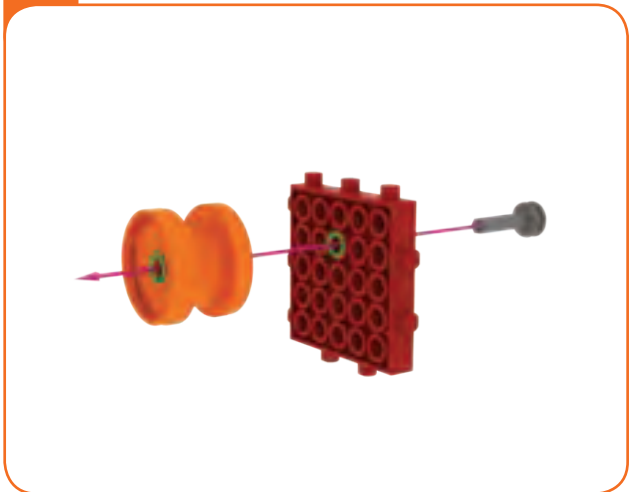
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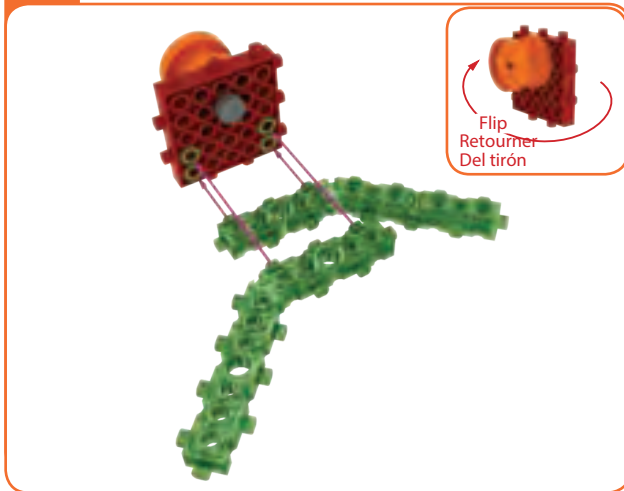
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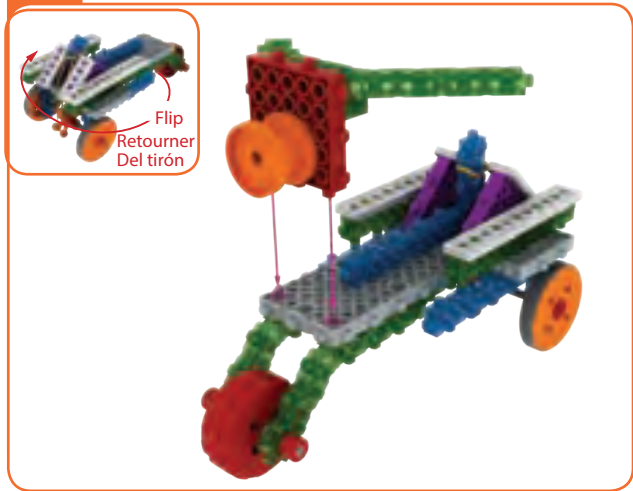
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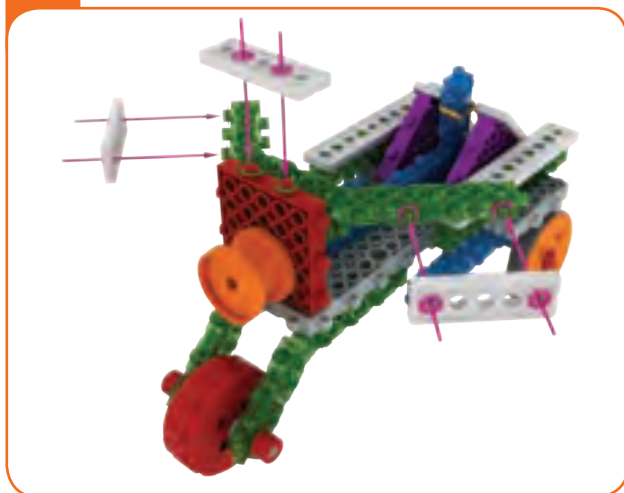
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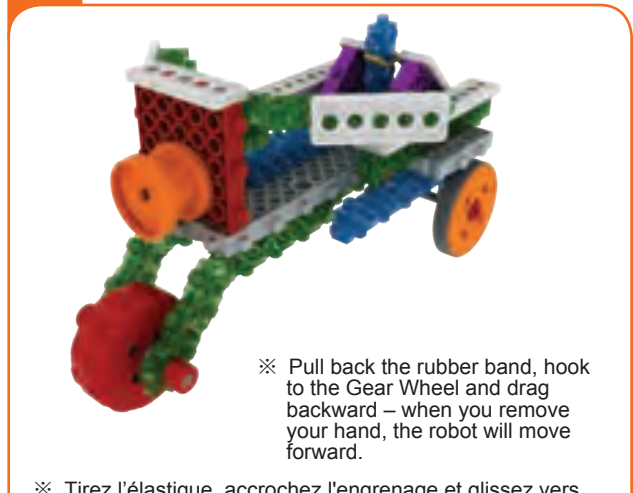
16



17



18



※ Pull back the rubber band, hook to the Gear Wheel and drag backward – when you remove your hand, the robot will move forward.

※ Tirez l'élastique, accrochez l'engrenage et glissez vers l'arrière – lorsque vous retirez votre main, le robot se déplace vers l'avant.

※ Tire de la goma, gancho a la rueda de engranaje y arrastre hacia atrás – cuando retire la mano, el robot se mueva hacia adelante.

Making My Robot • Fabrication de mon robot • Haciendo mis robots

- ♣ Try to make the robots in the pictures and talk about their shapes.
- ♣ Essayez de faire les robots des illustrations ci-dessous et parlez de leurs formes.
- ♣ Tratar de hacer que los robots en las fotos y hablar de sus formas.



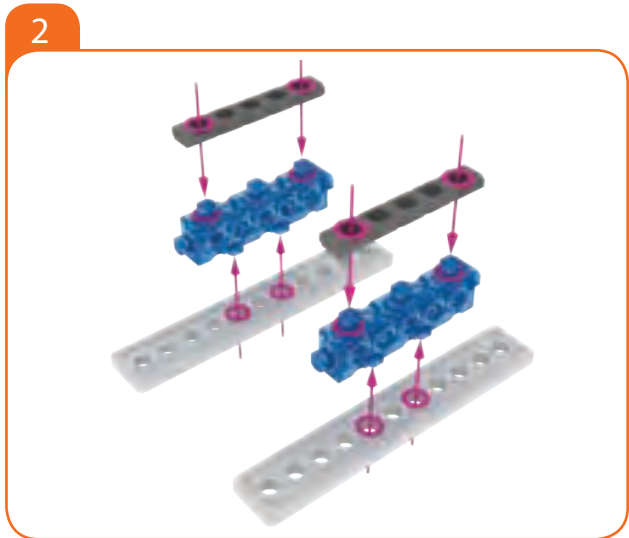
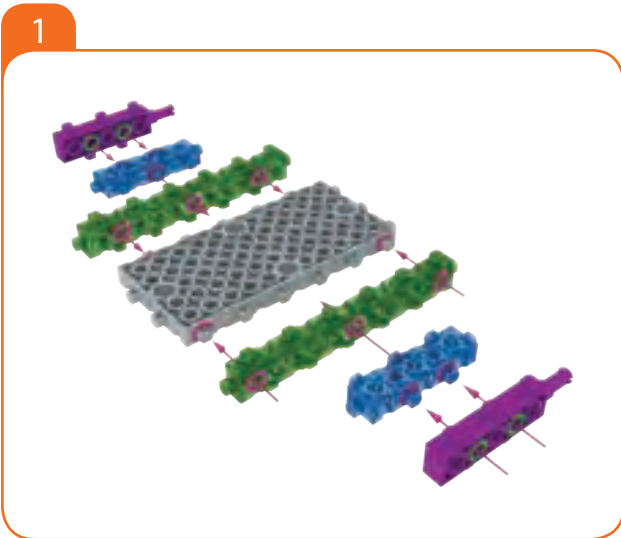
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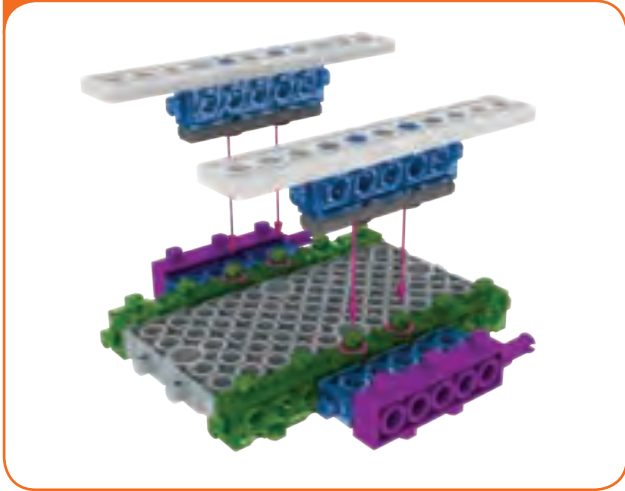
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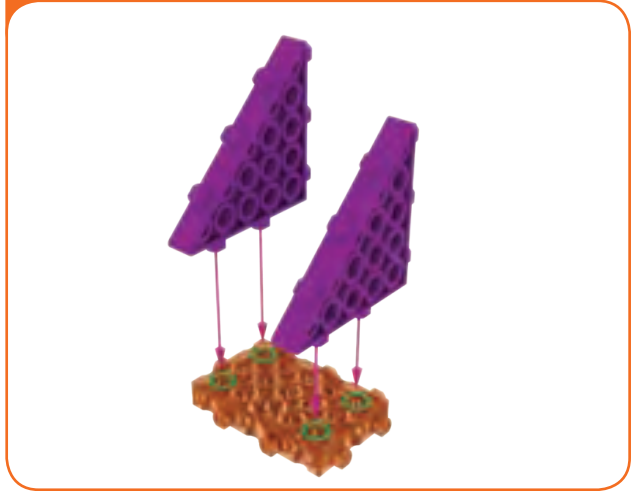
Robot 5: Apache Helicopter
Robot 5 : Hélicoptère Apache
Robot 5: Helicóptero Apache



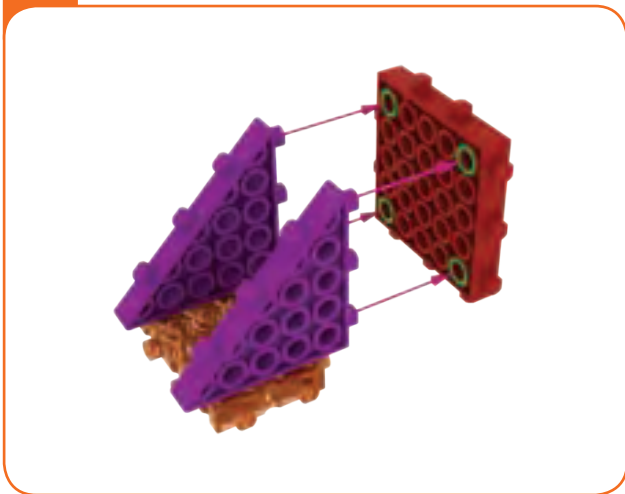
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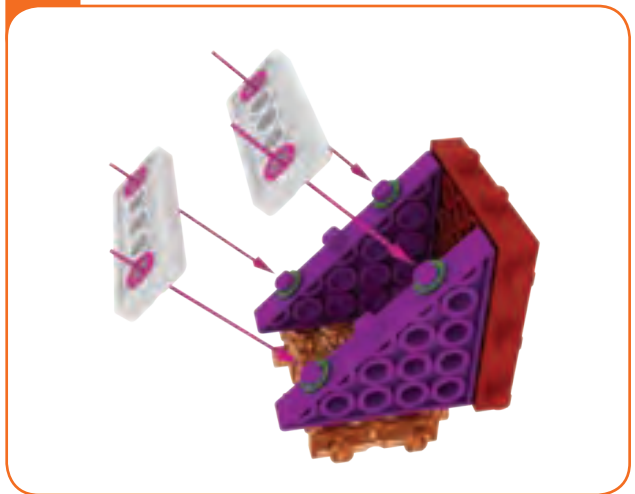
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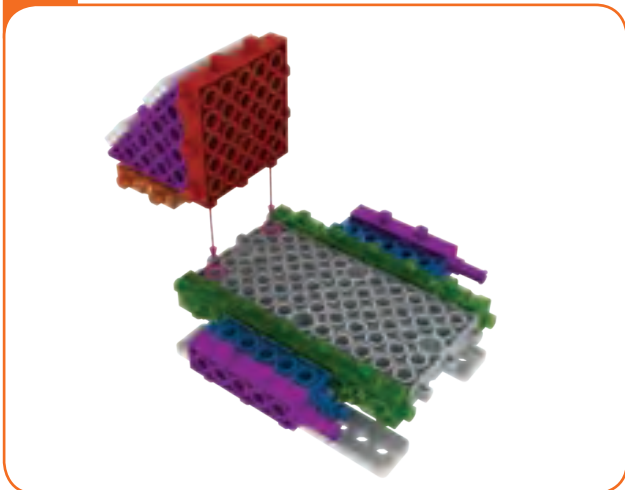
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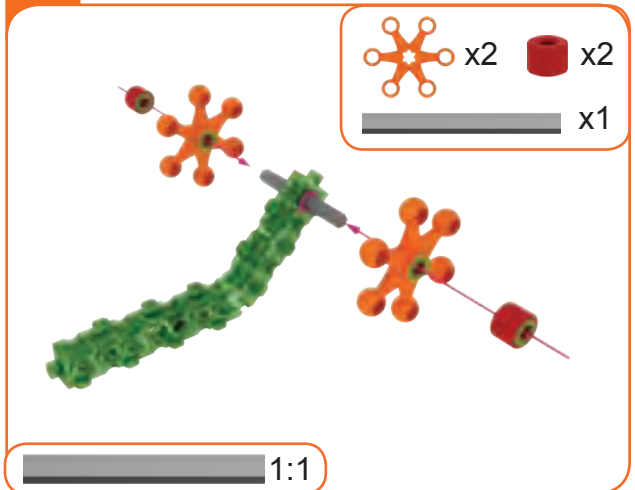
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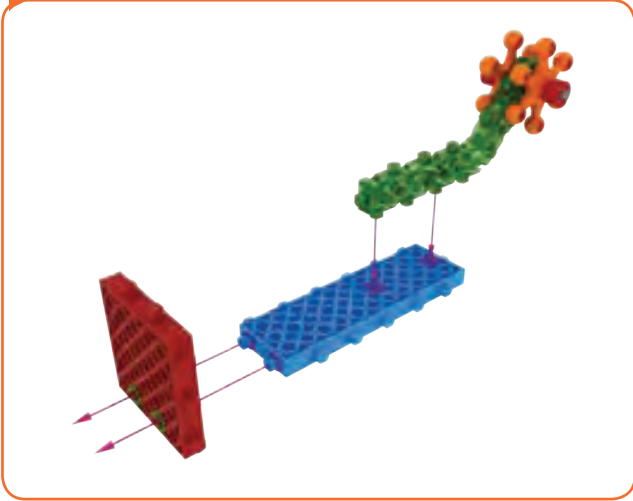
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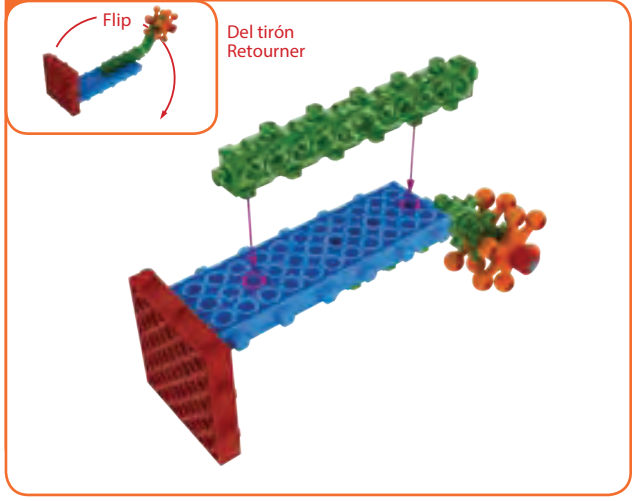
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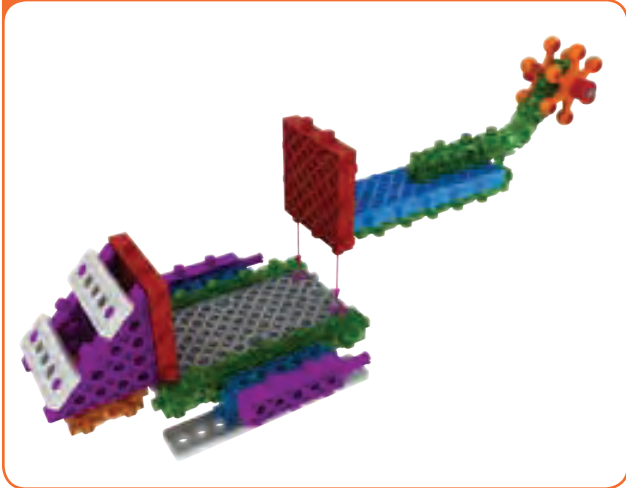
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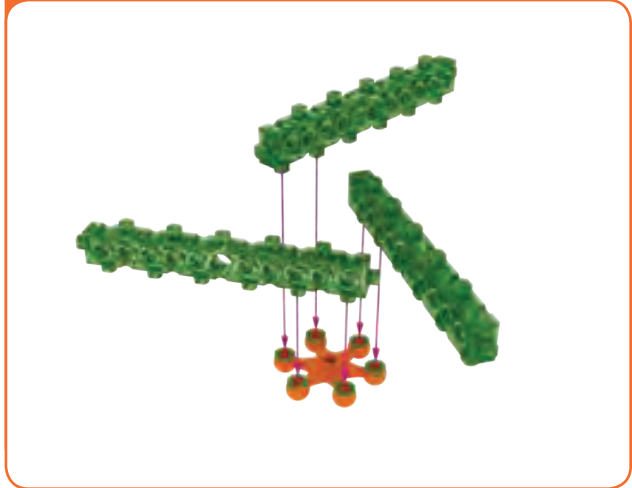
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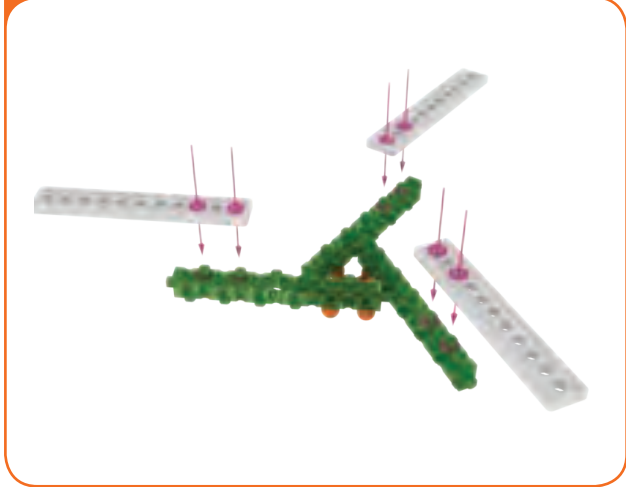
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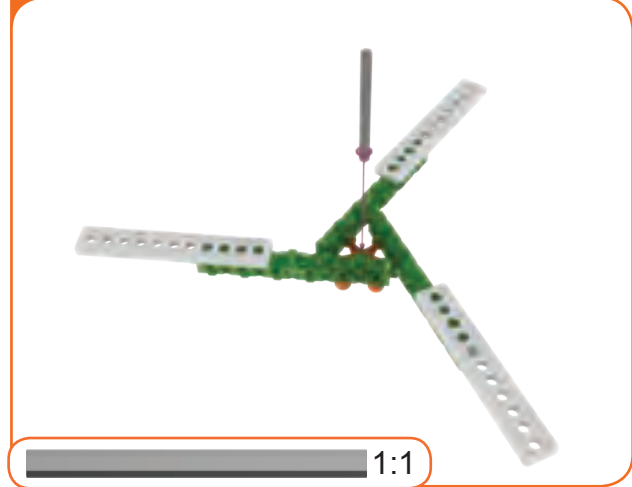
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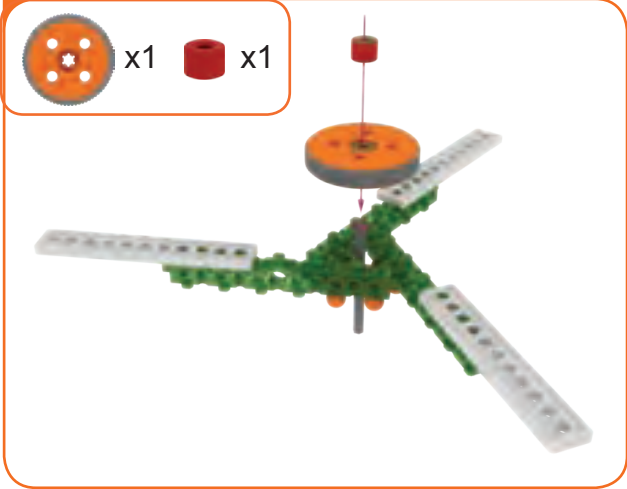
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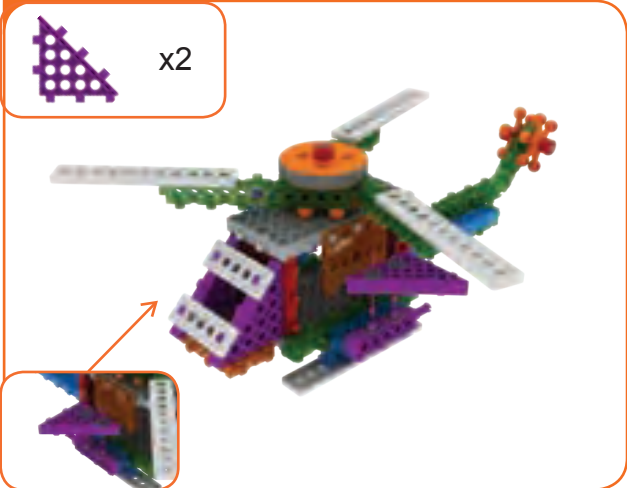
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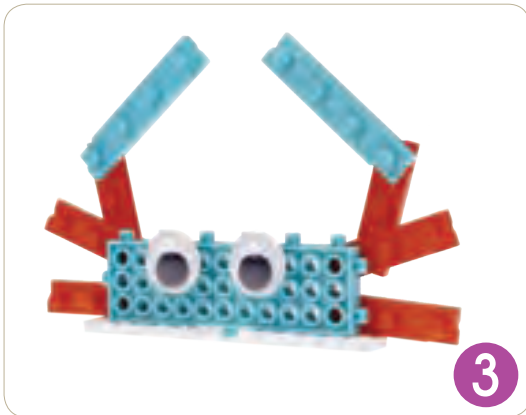
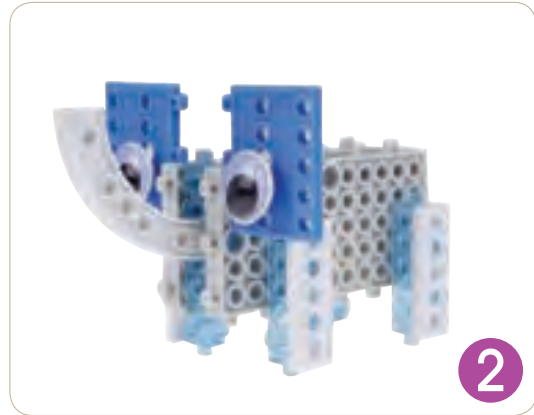
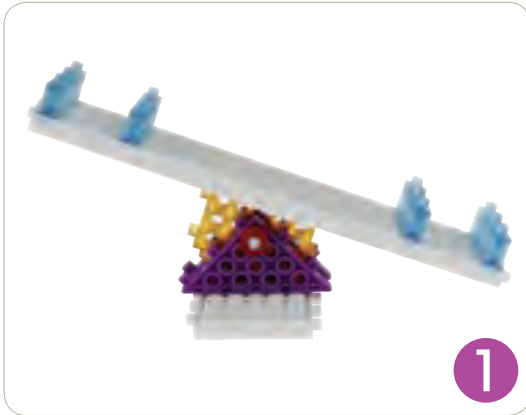


20



Making My Robot • Fabrication de mon robot • Hacer mi Robot

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1

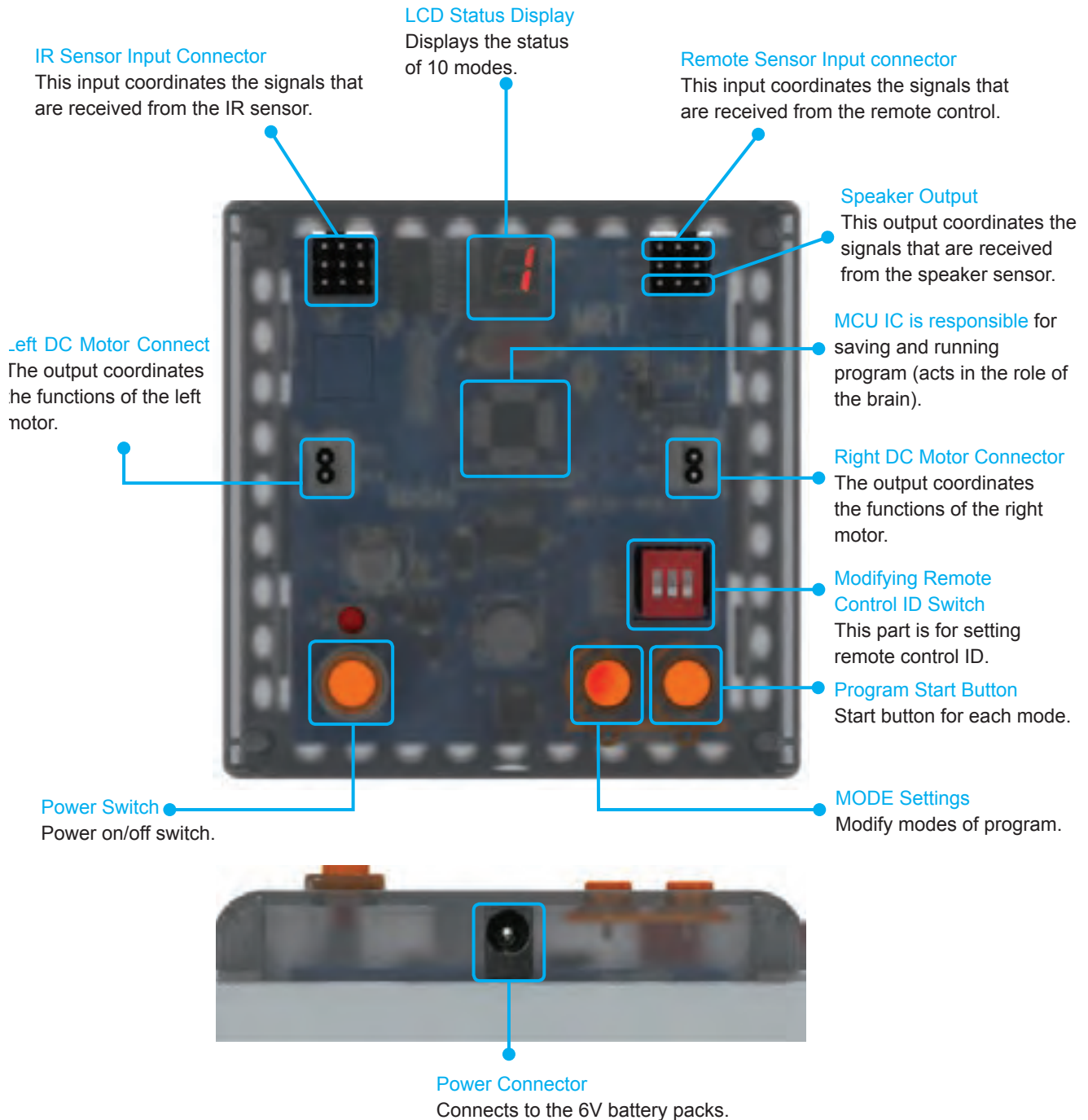
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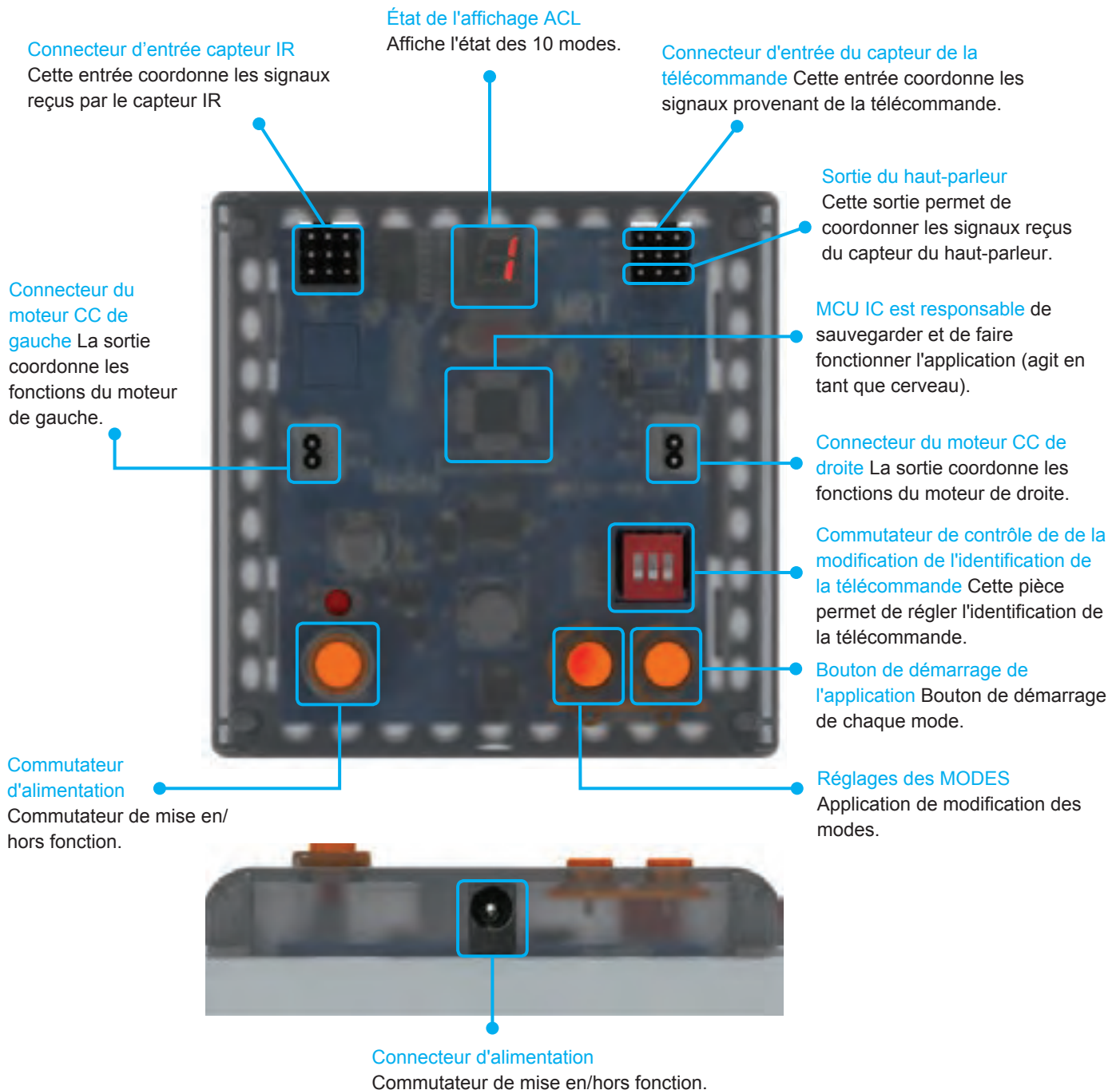
How To Use The Electronic Parts

Mainboard Assembly / Feature Functions



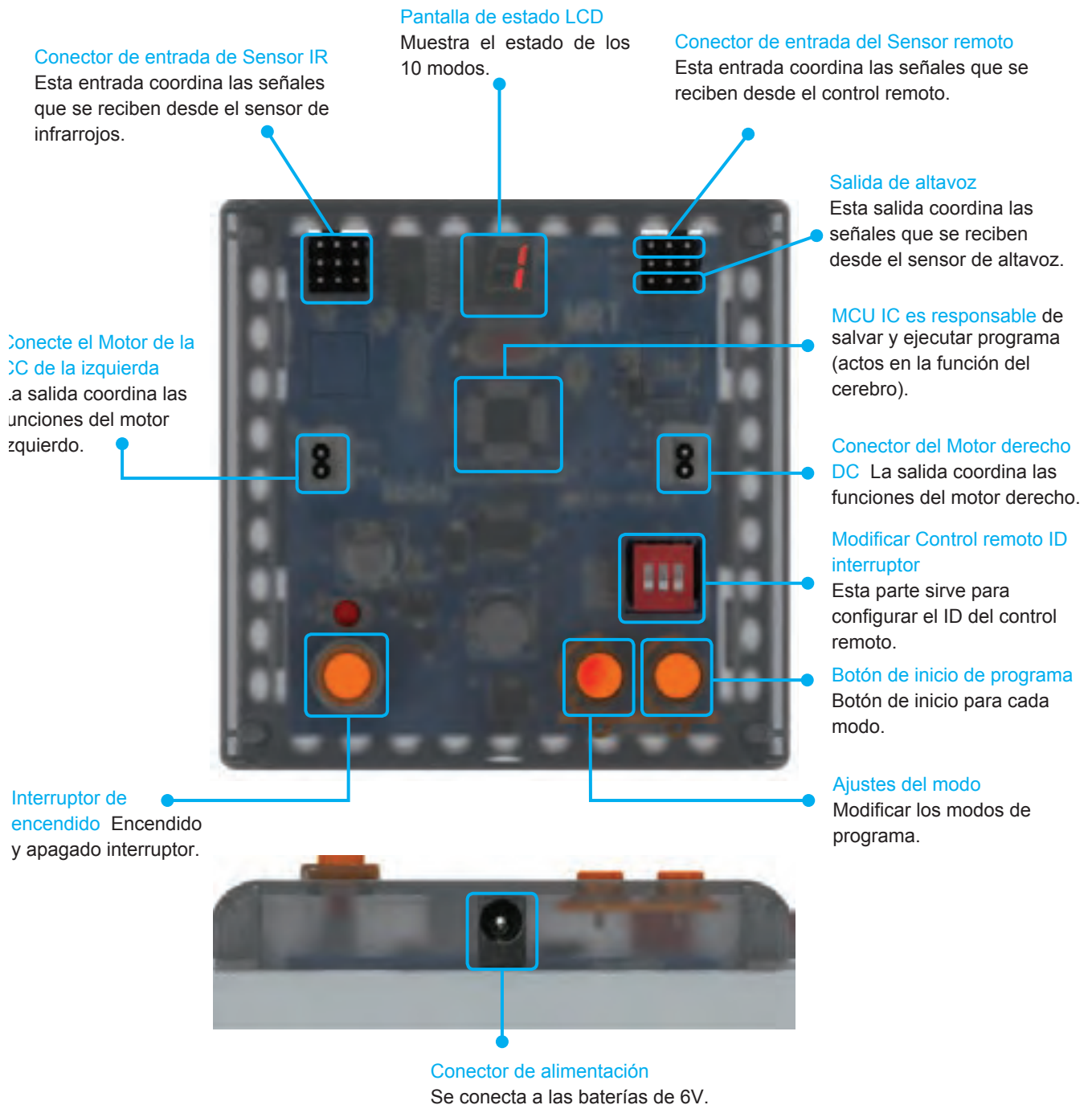
Comment utiliser les pièces électroniques

Montage du panneau principal/fonctions et caractéristiques



Cómo utilizar los componentes electrónicos

Montaje de la placa base/ funciones



Mode Setting • Réglages des modes • Modo de ajuste

1. Press the mode button and the LCD will change, as below. Select your desired function.
2. After selecting a mode, press the start button and the robot will move.

1. Appuyez sur le bouton Mode et l'affichage ACL changera, tel que démontré ci-dessous. Sélectionnez la fonction désirée.
2. Après avoir sélectionné un mode, appuyez sur le bouton Start et le robot bougera.

1. Pulse que el botón mode y la pantalla LCD cambiará, como abajo. Seleccionar la función deseada.
2. Después de seleccionar un modo, presione el botón start y el robot se moverá.

MODE 1



Free Move
Mouvement gratuit
Movimiento libre

MODE 2



Remote Control Controller
Télécommande
Controlador del mando a distancia

MODE 3



Line Tracer
Traceur de ligne
Trazador de línea

MODE 4



Avoider
À éviter
Evitar

MODE 5



Stalker
Harceleur
Acosador

MODE 6



Drop Checker
Vérificateur de chute
Comprador de gota

MODE 7



Touch
Toucher
Toque

MODE 8



Remote Control + IR
Télécommande + IR
Control à distancia + IR

MODE 9



Remote Control + Touch
Télécommande + toucher
Mando a distancia + Toque

MODE 0



Remote Control (R)
Télécommande (D)
Mando a distancia

RC Receiver • Récepteur RC • Receptor RC

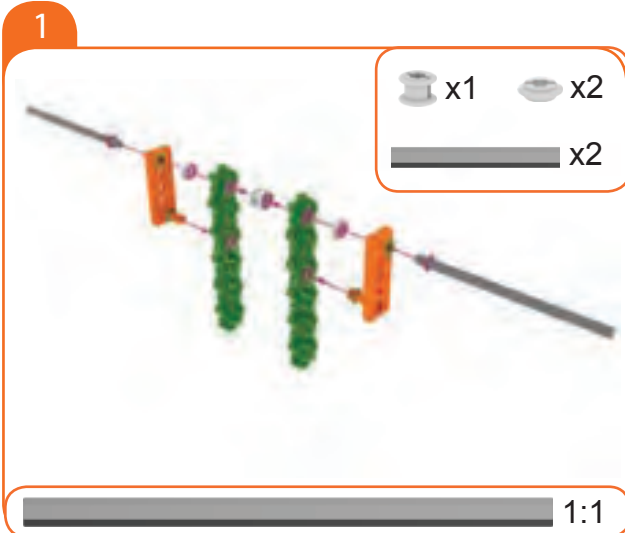


This Sensor receives an IR signal from the remote controller and converts it into input signal.

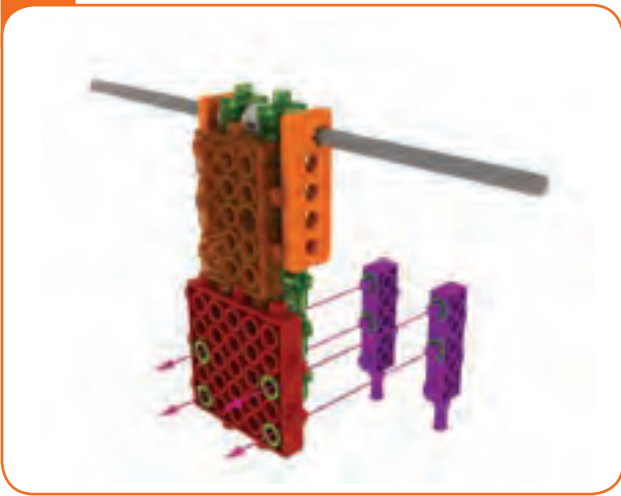
Ce capteur reçoit un signal IR de la télécommande et le converti en signal d'entrée.

Este Sensor recibe una señal de IR desde el control remoto y la convierte en la señal de entrada.

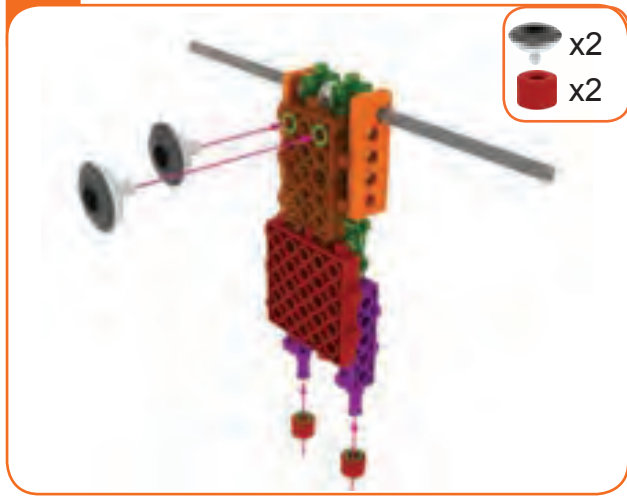
Robot 6: I Am a Gymnast!
Robot 6 : Je suis un(e) gymnaste
Robot haciendo 6: ¡soy un gimnasta!



3



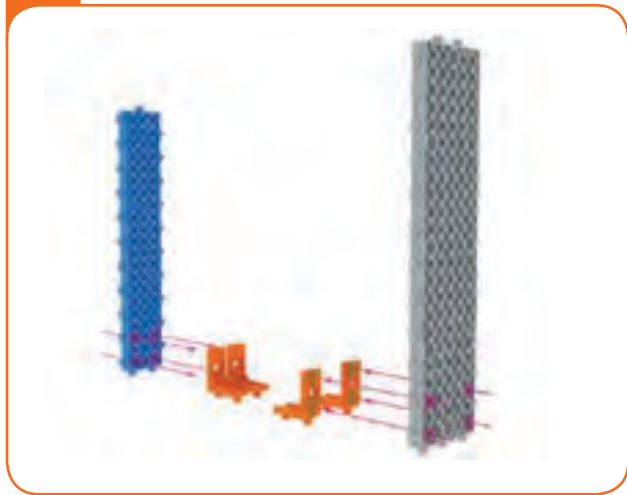
4



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9



10



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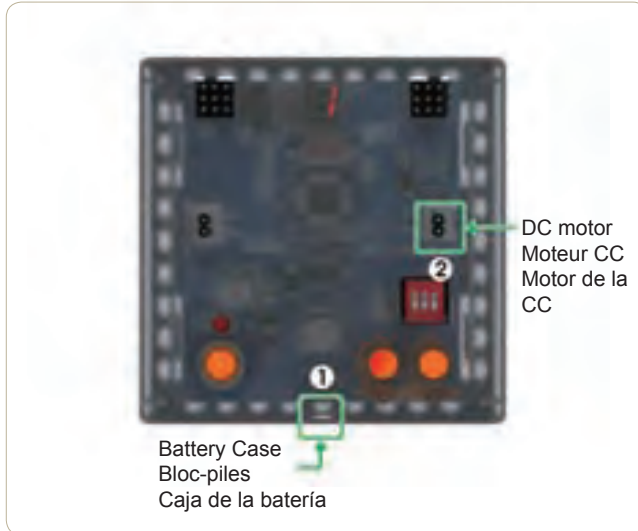


13



How to operate the Gymnast Comment fonctionne le gymnaste Cómo funciona el gimnasta

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect the Battery Case to Power Connector.
2. Connect the DC Motor to the Right-Motor Connector.

Branchez dans l'ordre suivant :

1. Branchez bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC au connecteur du moteur de droite.

Conecte en este orden:

1. Conecte la caja de la batería al conector de alimentación.
2. Conecte el Motor de la CC para el conector del Motor derecho.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:



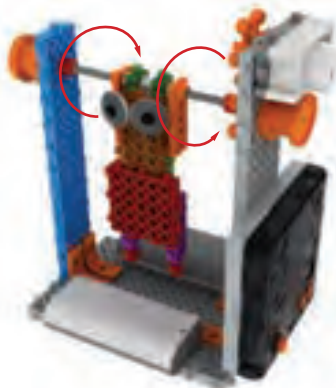
4. Press the START button.

4. Appuyez sur le bouton START.

4. Presione el botón START.

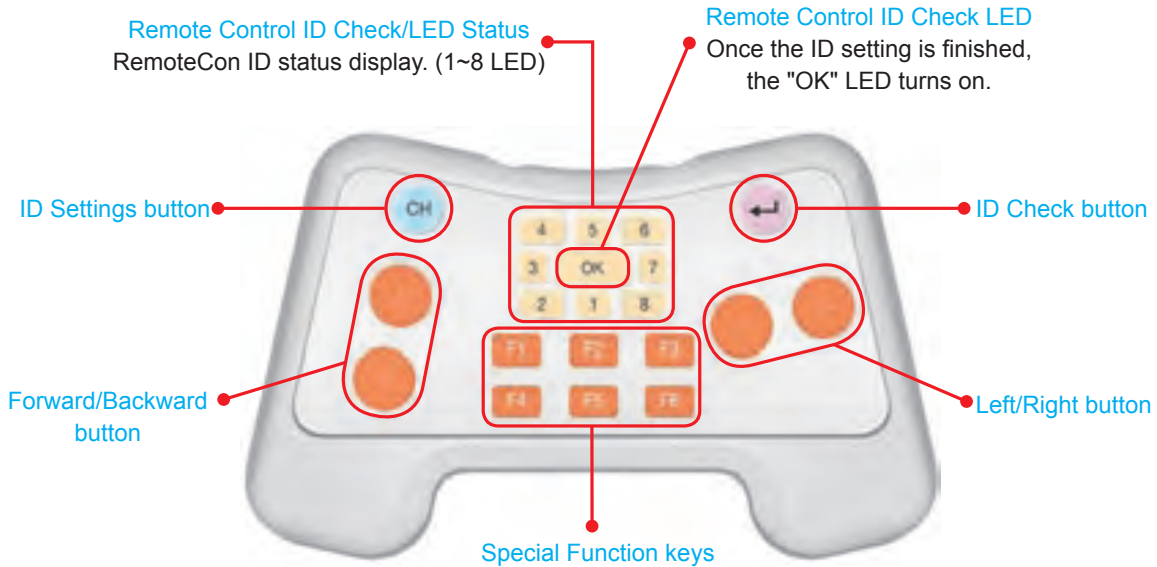
How to make it move? • Comment puis-je le faire bouger? • Cómo hacer que se mueva

- ※ Press START button and the robot will swing like a Gymnast.
- ※ Appuyez sur le bouton START et le robot se balancera tel un gymnaste.
- ※ Presione el botón START y el robot se moverá como una gimnasta.











How to Use the Remote Control

Remote Control Configuration



Setting Remote Control ID

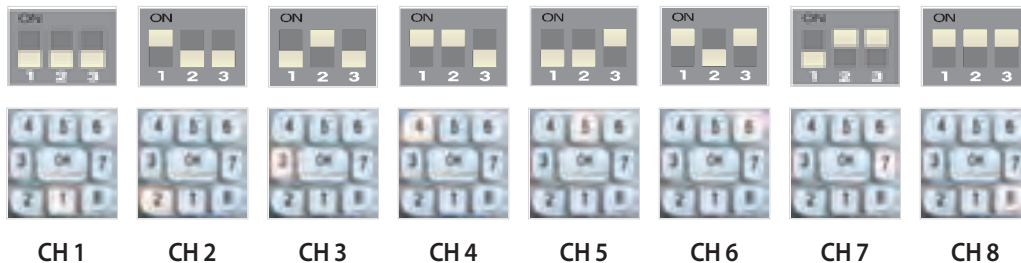
- ① Turn on the robot.
- ② Select mode # 2 mode. 
- ③ Press  button while holding  button. The A panel ID LED turns on and shows you the chosen mode.
- ④ Press  button while holding  button and choose your ID. (Number 1~8)
- ⑤ After selecting ID, if you release  button and press  button, ID will be selected.
- ⑥ The LED on the mainboard will blink 3 times and it will turn off automatically.
That means the ID Selection is finished.
- ⑦ If you press  button, you can see your selected ID.

※ If there is a problem, repeat steps 1-7 carefully.



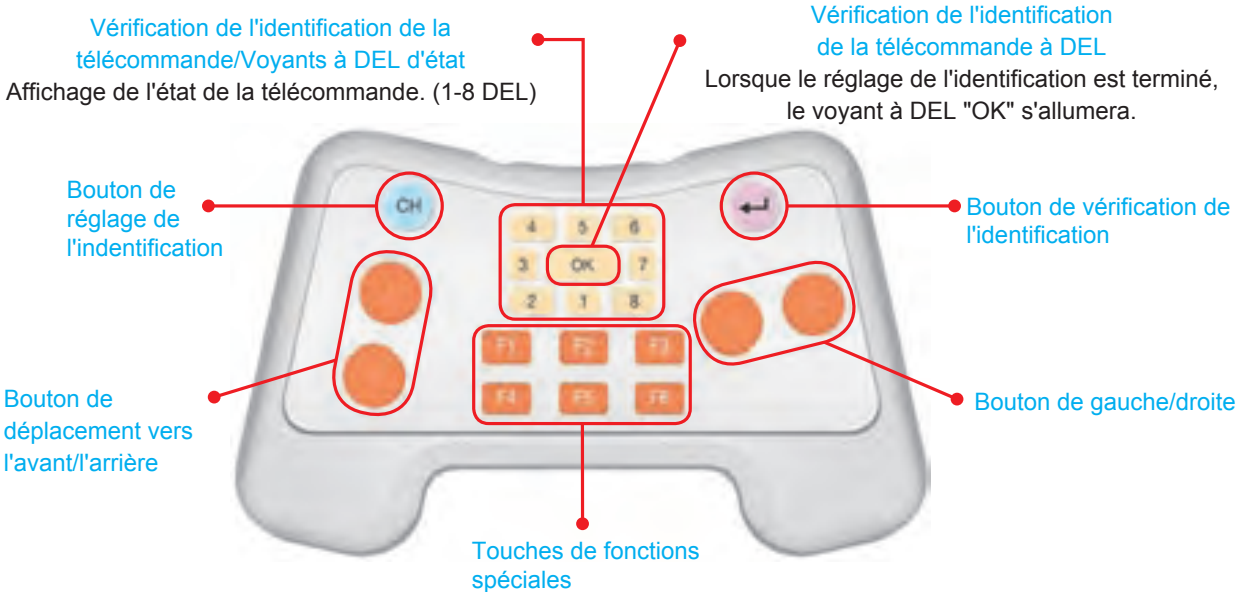
How to Set Up Communication ID

- ※ The maximum number of channels can be set as shown below without interference.
Use the picture to assign the channels to the communication ID.











Comment utiliser la télécommande

Configuration de la télécommande



Réglage de l'identification de la télécommande

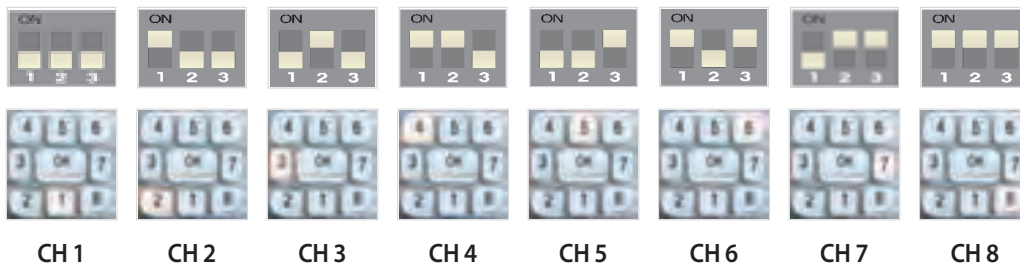
- ① Mise en fonction du robot.
- ② Sélectionnez le mode no. 2. 
- ③ Appuyez sur le bouton  en maintenant enfoncé le bouton 
L'identification à DEL du panneau A s'allumera et affichera le mode choisi.
- ④ Appuyez sur le bouton  en maintenant enfoncé le bouton  et choisissez votre identification. (Numéro 1-8).
- ⑤ Après avoir sélectionné l'identification, si vous relâchez le bouton  et appuyez sur le bouton  l'identification sera sélectionné.
- ⑥ Le voyant à DEL du panneau principal clignotera trois fois et s'étendra automatiquement. Ceci signifie que la sélection de l'identification est terminée.
- ⑦ Si vous appuyez sur le bouton , vous pourrez voir l'identification sélectionnée.



※ S'il y a un problème, répétez attentivement les étapes 1-7.

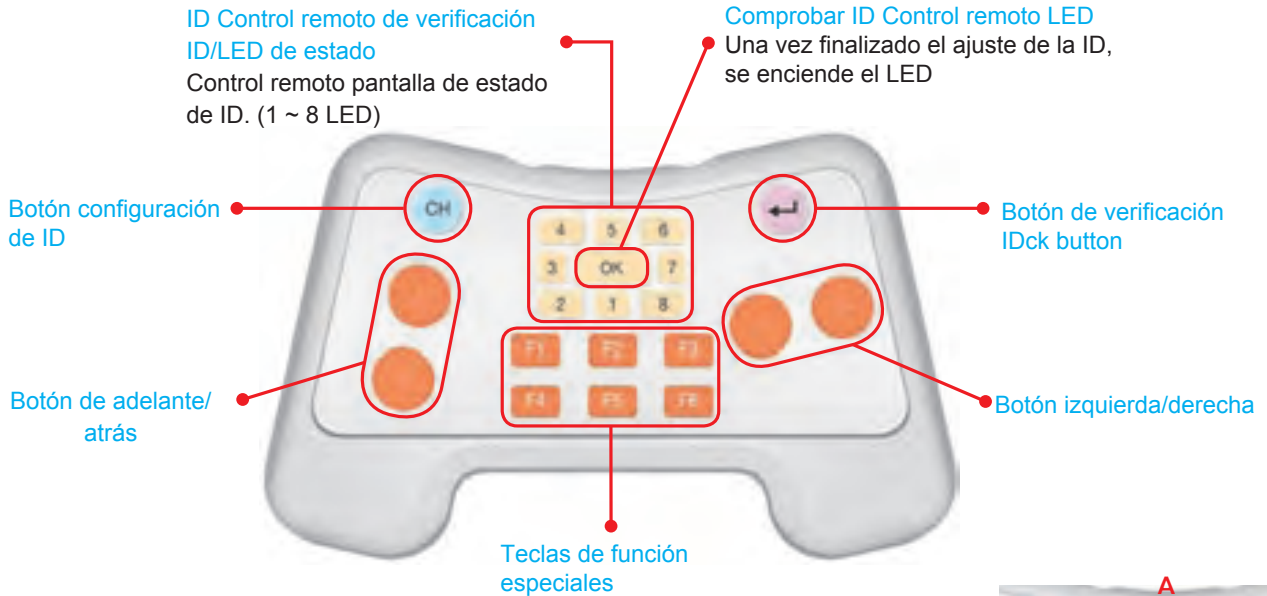
Comment régler l'identification de la communication

- ※ Le nombre maximum de canaux peuvent être réglés comme suis sans interférence.
Utilisez l'illustration pour assigner les canaux à l'identification de la communication.




Cómo utilizar del mando de distancia

Configuración del mando de distancia



Configuración de ID control remoto

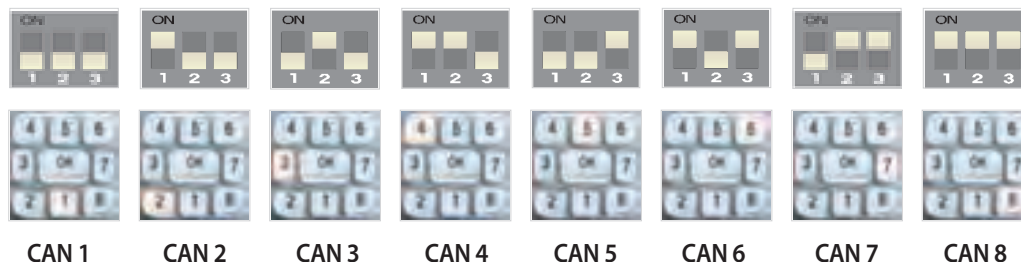
- ① Encender el robot.
- ② Seleccione el modo # 2. 
- ③ Toque el **CH** botón mientras mantiene el botón **↵**. Un grupo ID LED se enciende y muestra el modo seleccionado.
- ④ Toque el botón **CH** mientras mantiene el botón **↵** y elija su identificación. (Número 1 ~ 8).
- ⑤ Después de seleccionar el ID, si suelta el botón **↵** y presione el botón **CH**, ID será seleccionado.
- ⑥ El LED de la placa base parpadeará 3 veces y se apagará automáticamente. Eso significa que haya terminado la selección de ID.

⑦ Si pulsas el botón **↵**, puede ver su ID seleccionado.

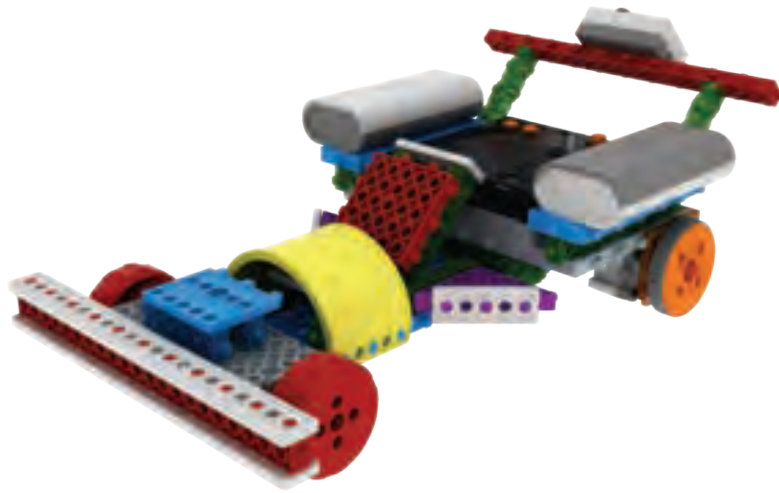
※ Si hay un problema, repita los pasos 1-7 con cuidado

Cómo configurar ID de comunicación

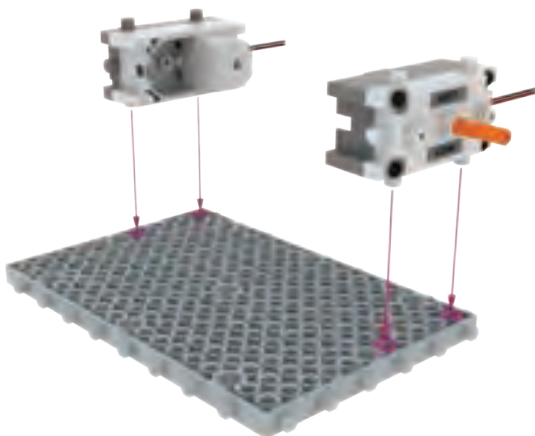
※ El número máximo de canales se puede configurar como se muestra a continuación sin interferencia. Use el cuadro para asignar los canales para la identificación de la comunicación.



Robot 7: Mini Racing Car
Robot 7 : Mini voiture de course
Robot 7: Mini coche de carreras



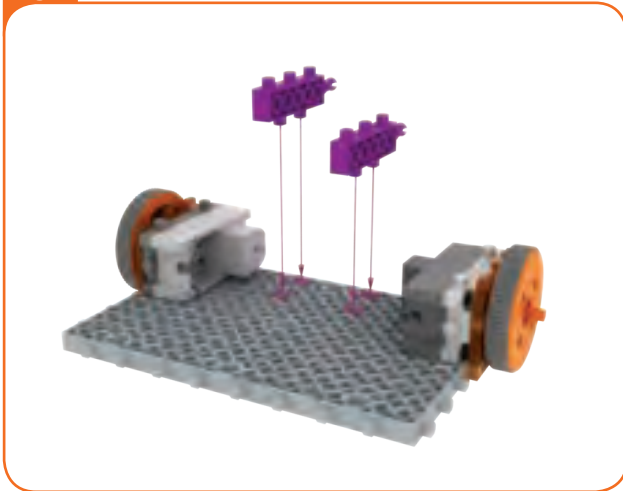
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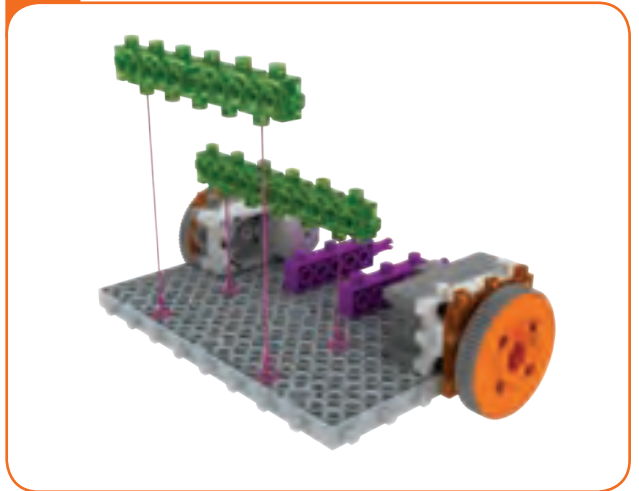
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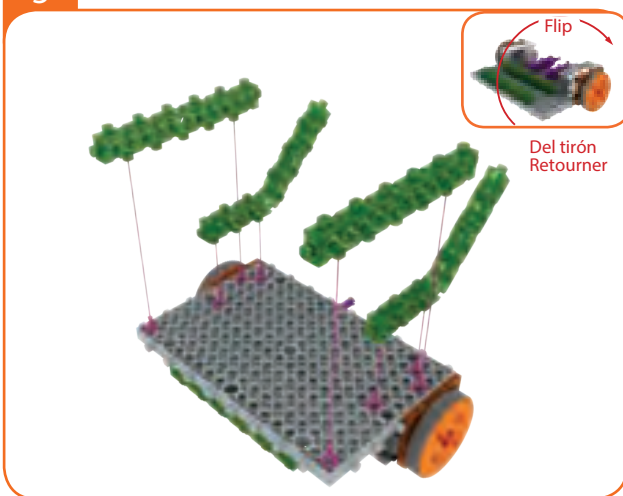
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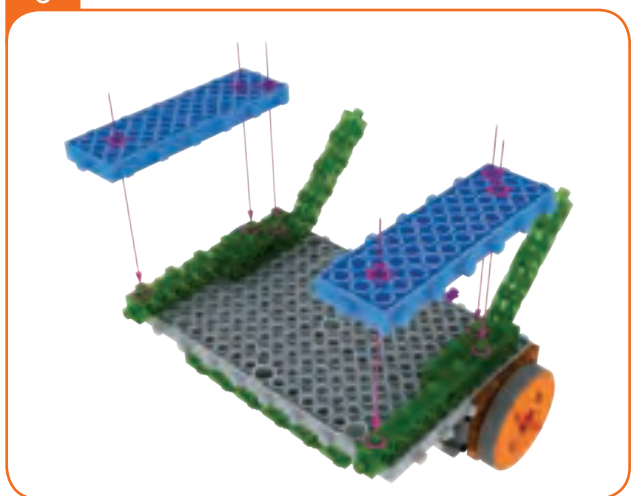
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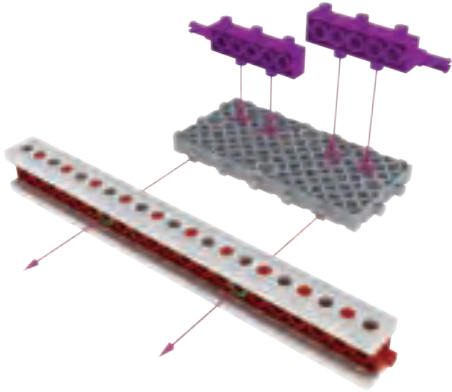
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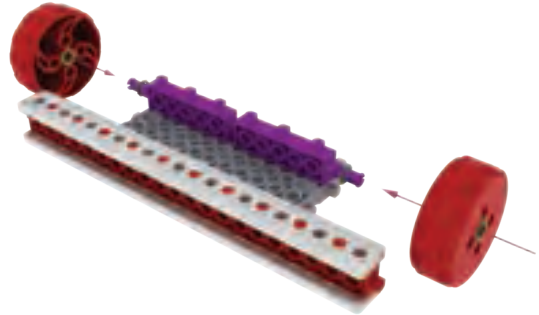
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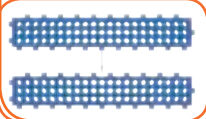
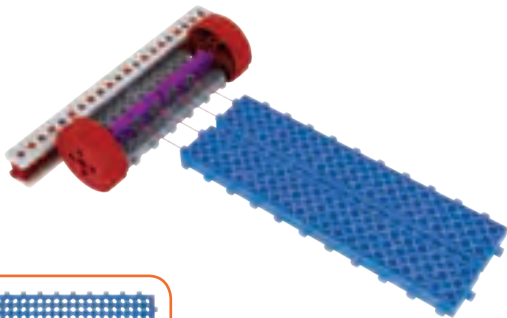
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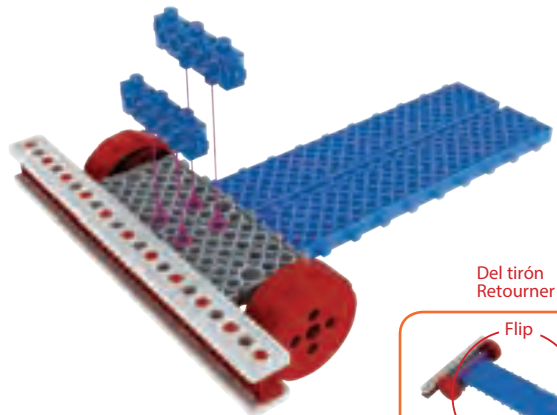
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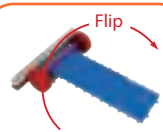


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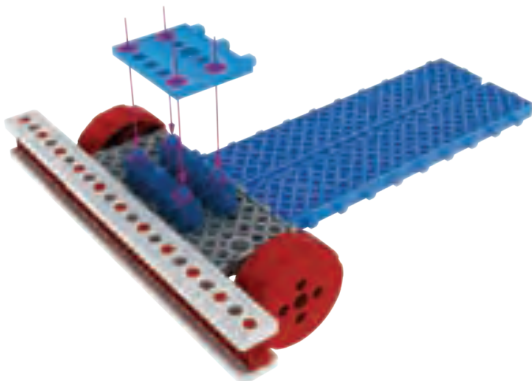


Del tirón
Retourner

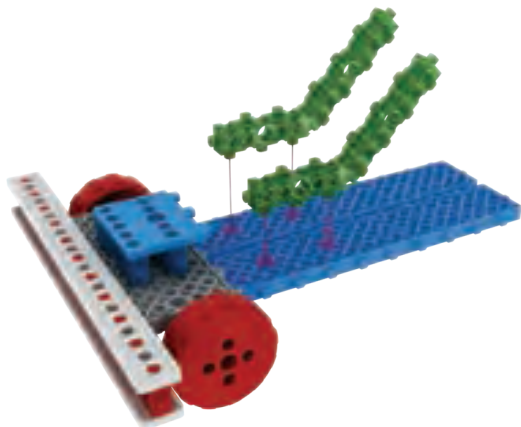
Flip



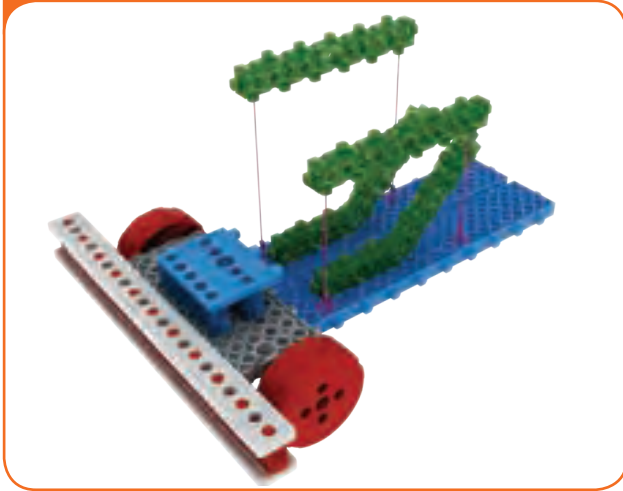
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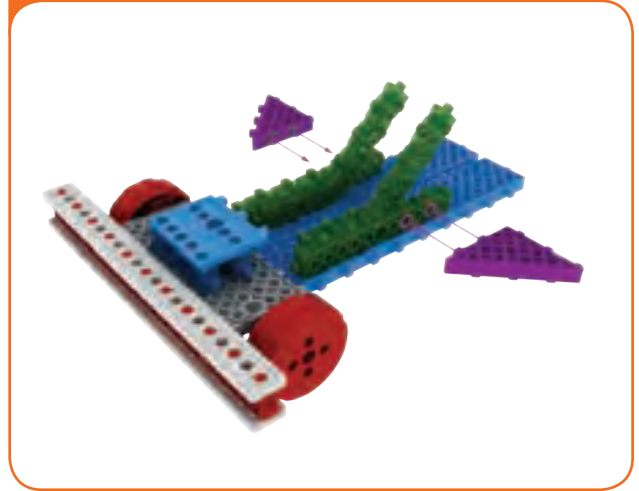
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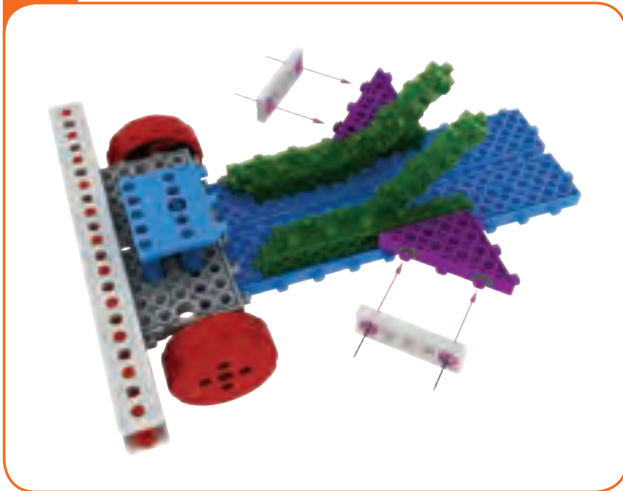
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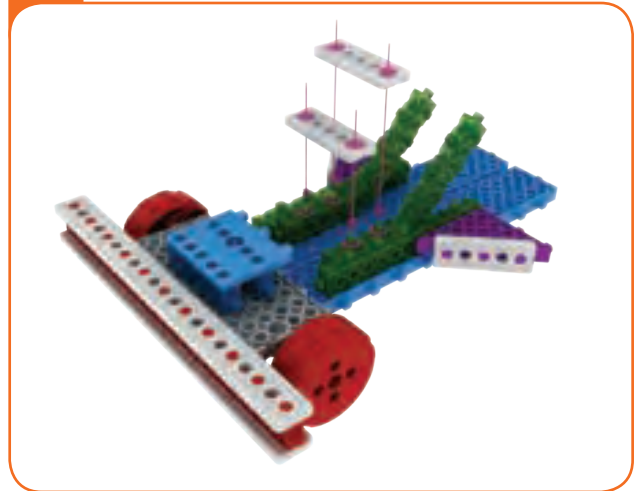
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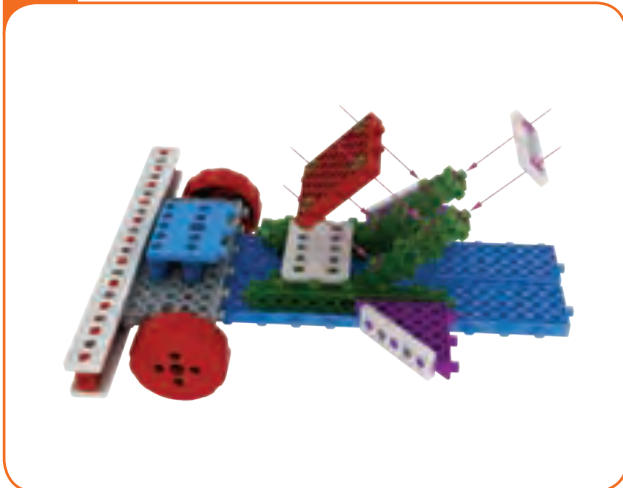
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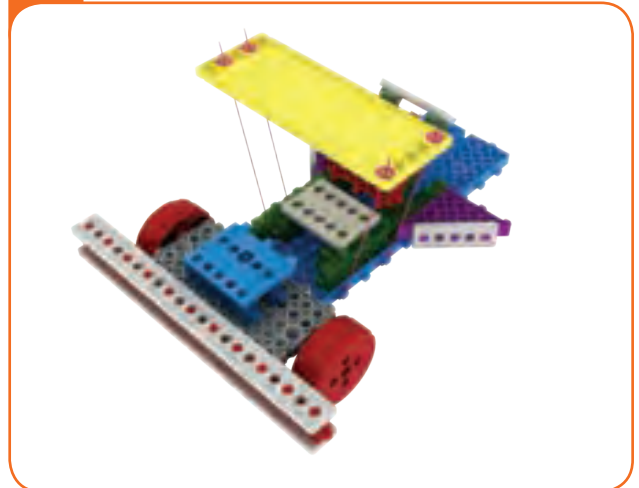
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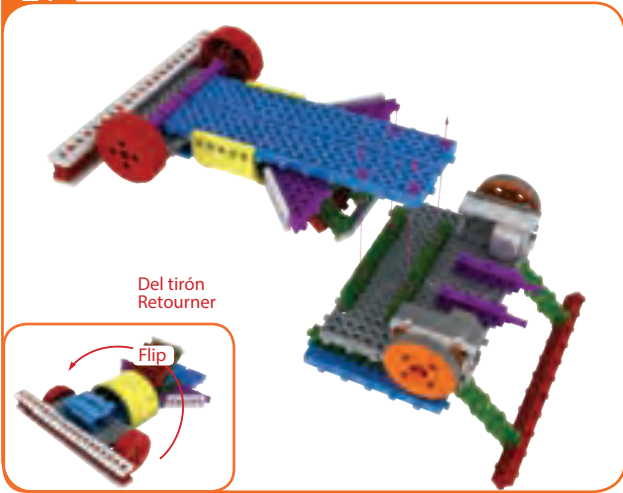
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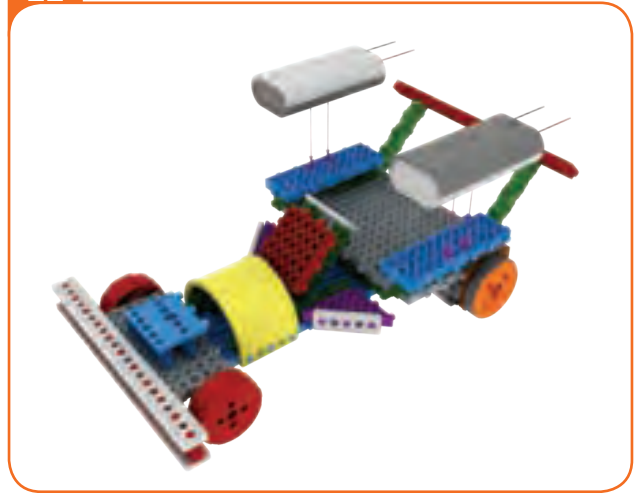
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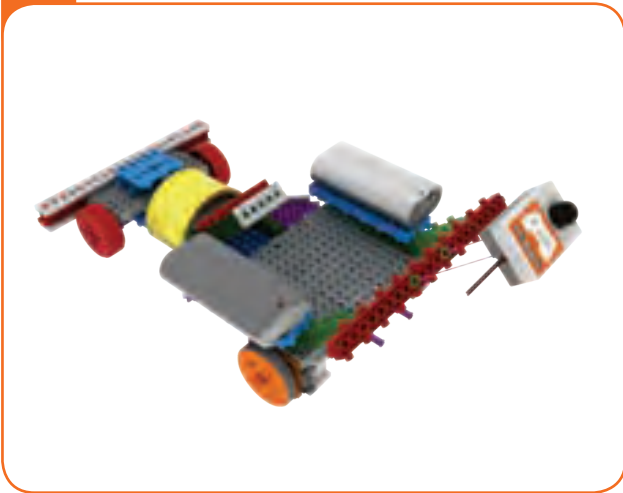
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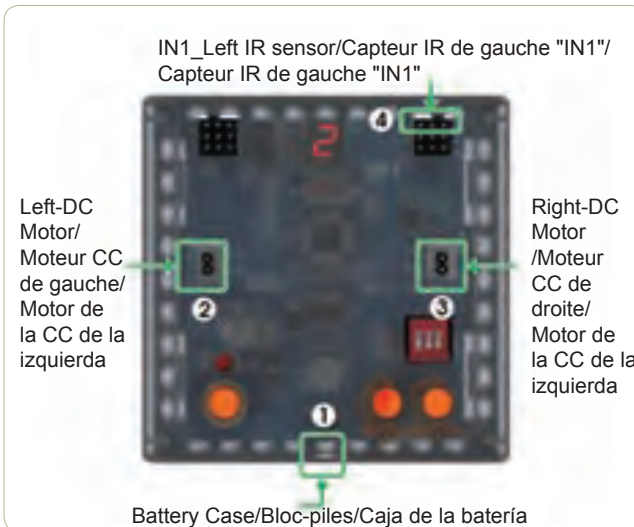


25



How to operate Mini Racing Car Comment faire fonctionner la mini voiture de course Funcionamiento del Mini coche de carreras

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:

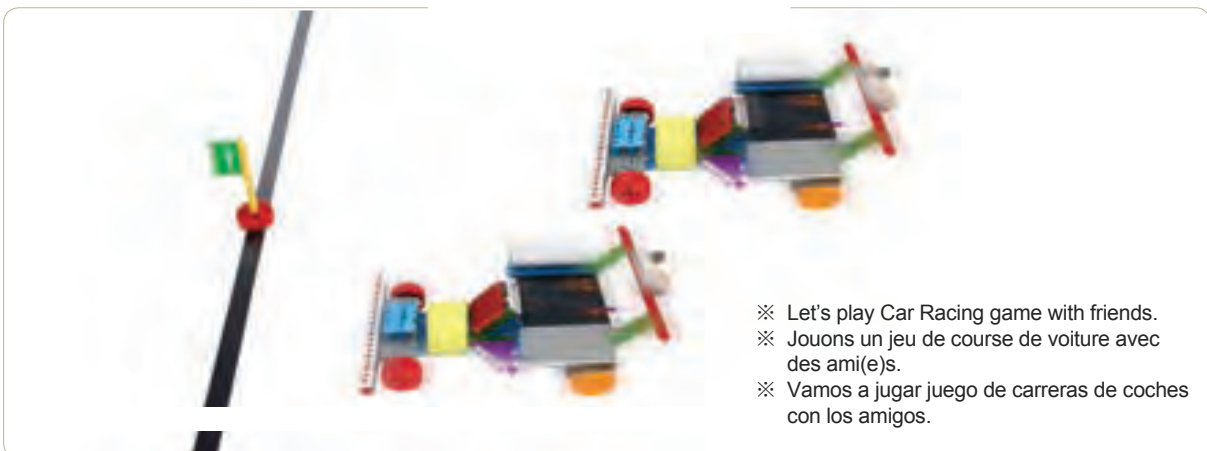


4. Press the START button.
5. Select Remote ID.

4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

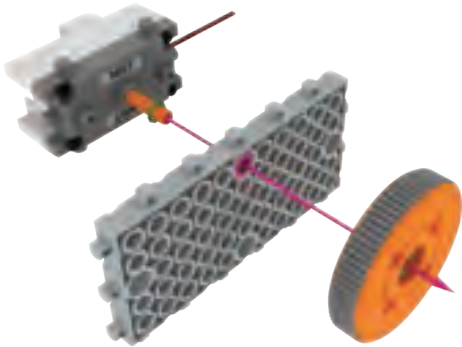
How to make it move? • Comment puis-je le faire bouger? • Cómo hacer que se mueva



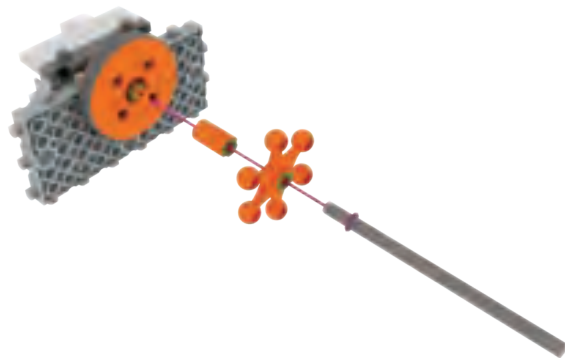
Robot 8: Helicopter
Robot 8 : Hélicoptère
Robot 8: Helicóptero



1

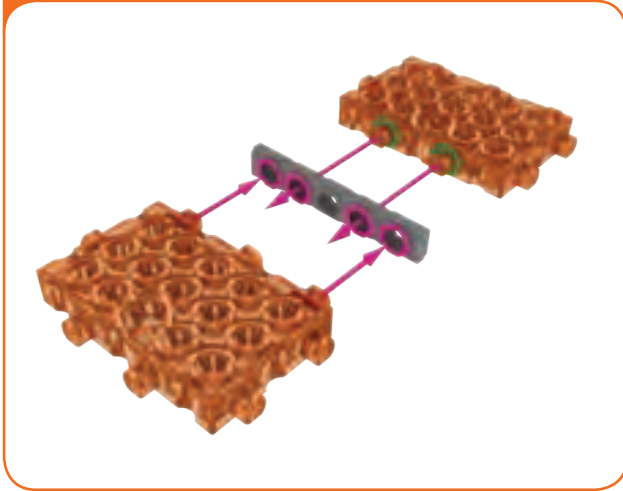


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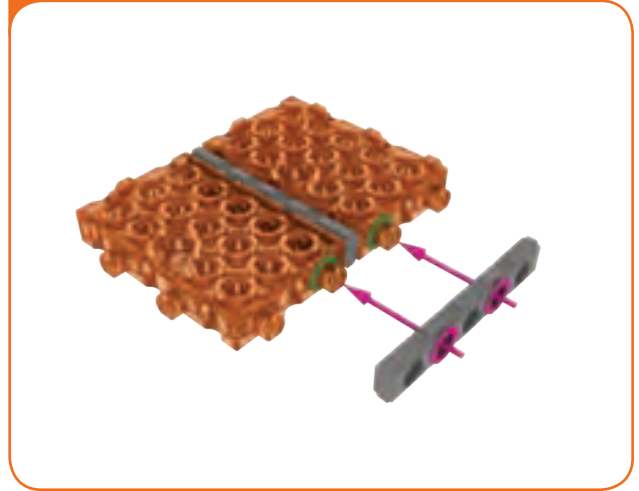


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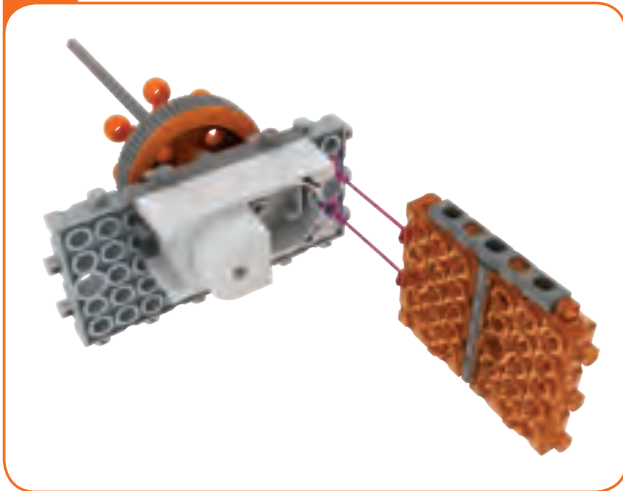
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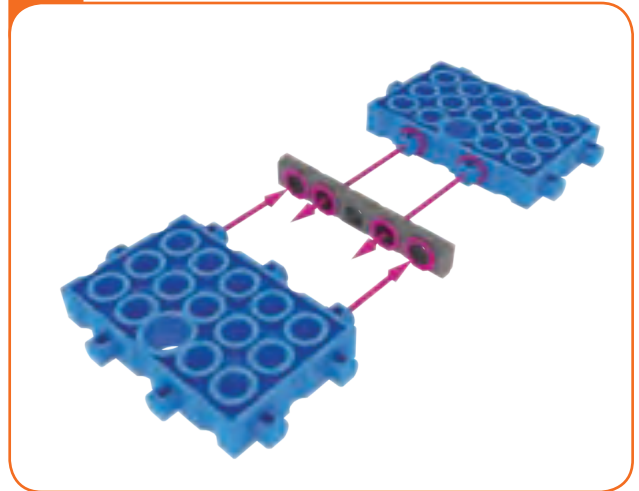
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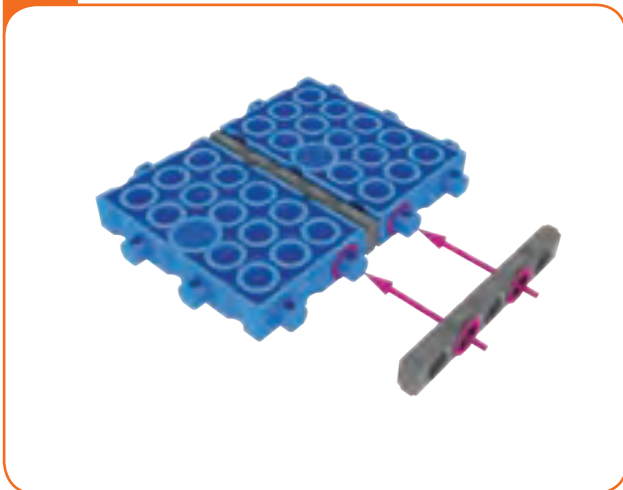
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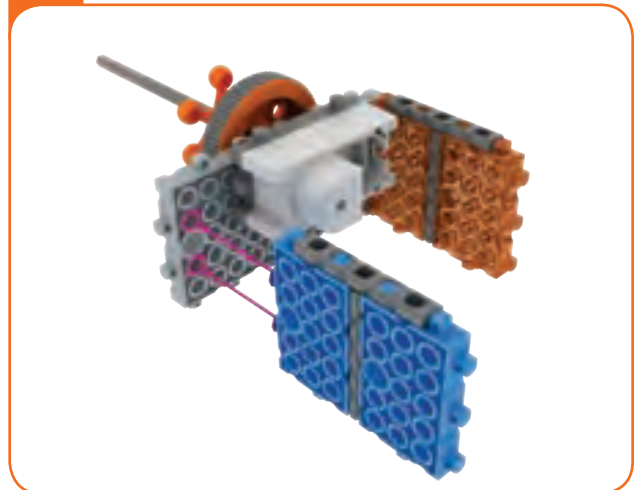
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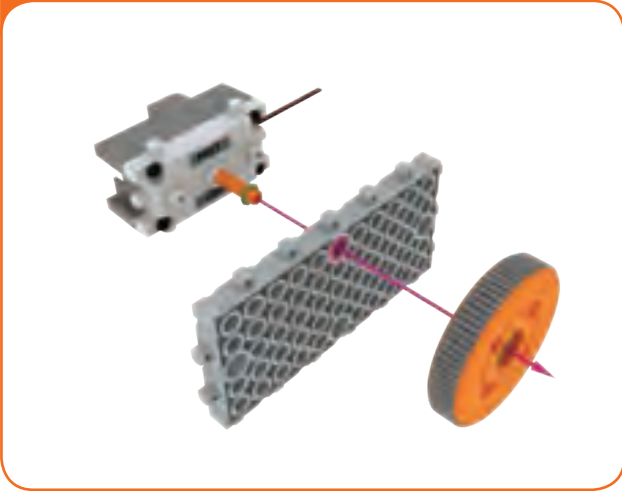
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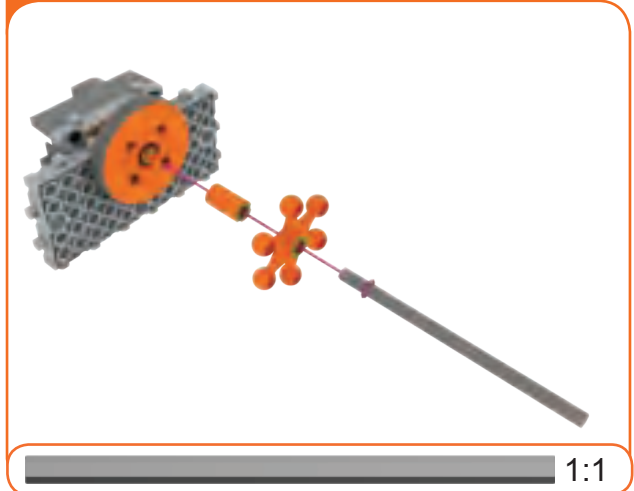
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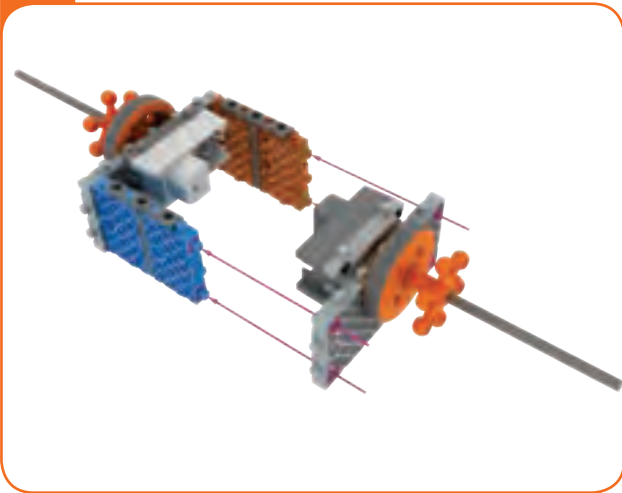
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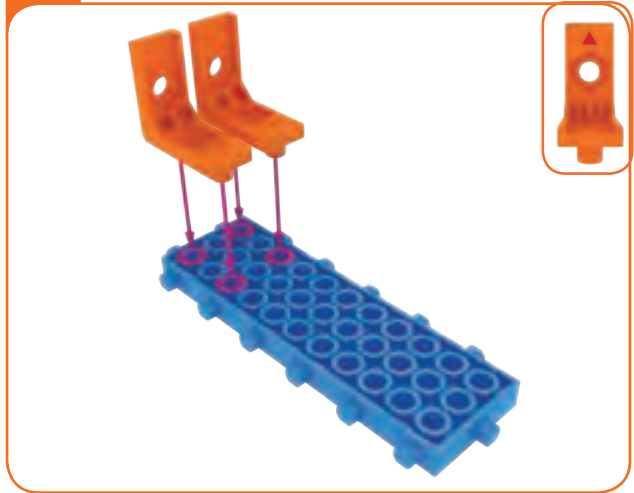
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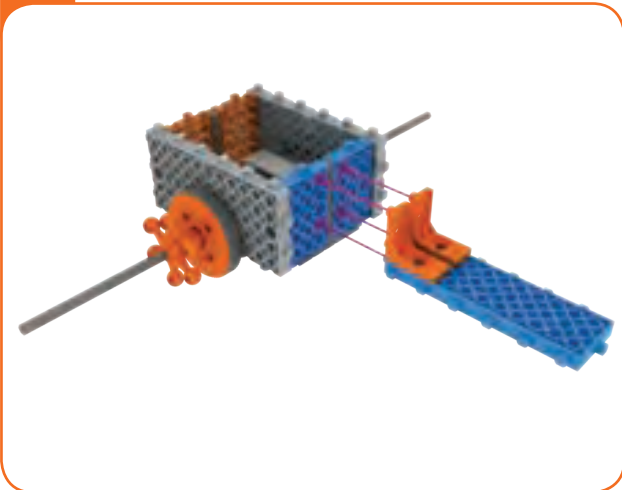
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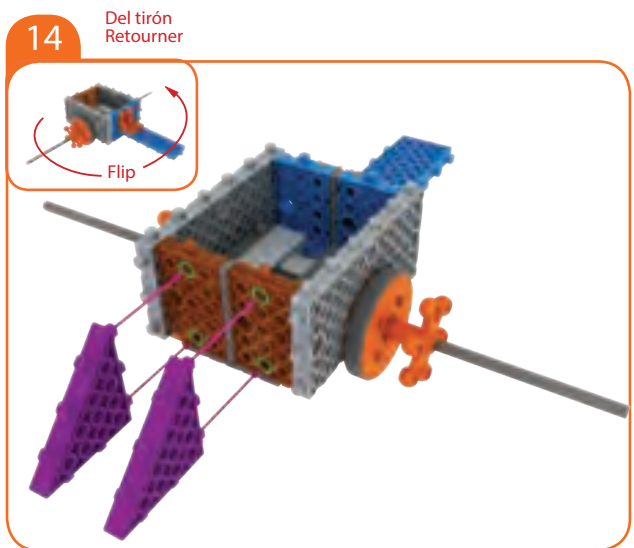
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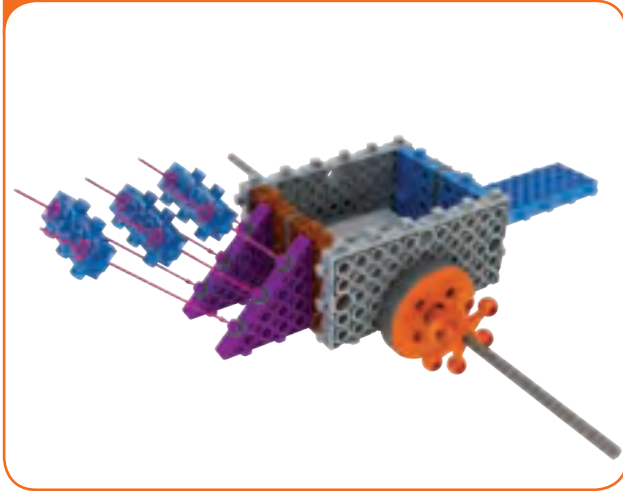
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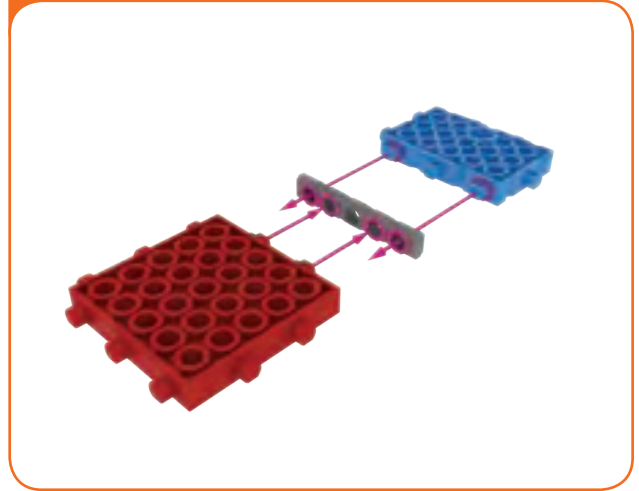
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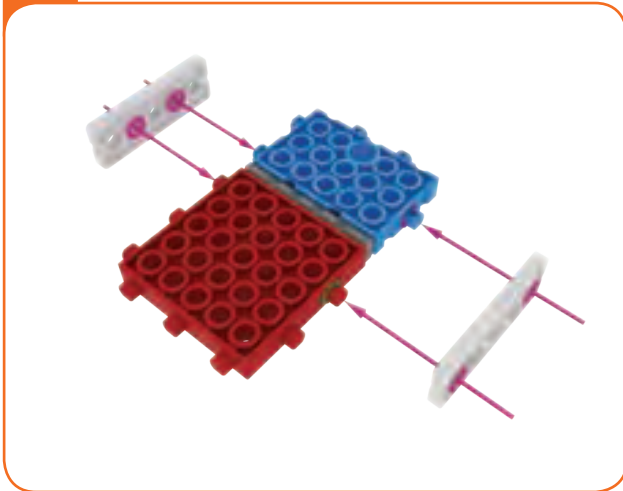
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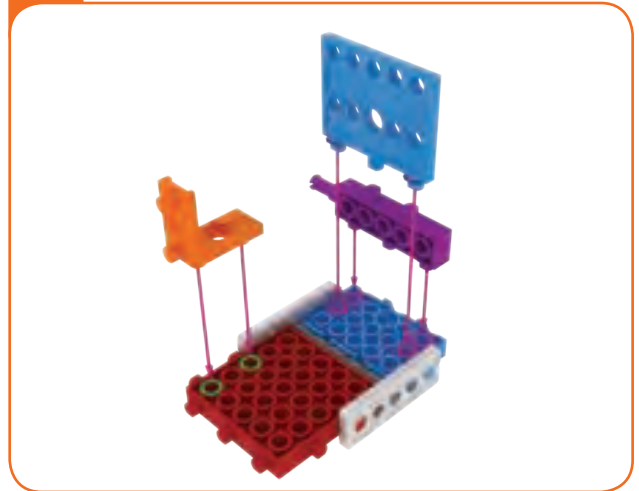
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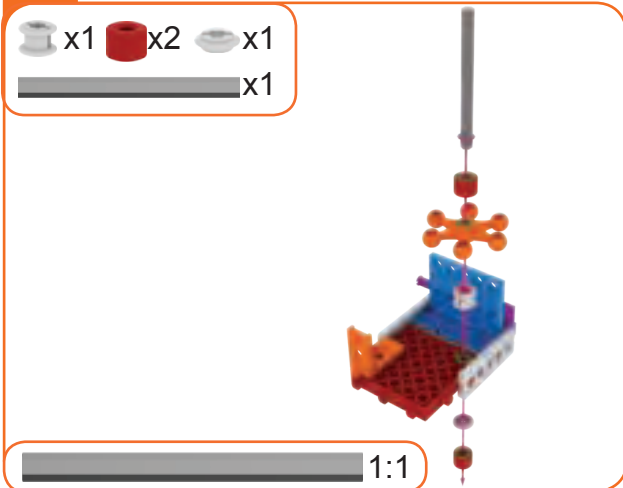
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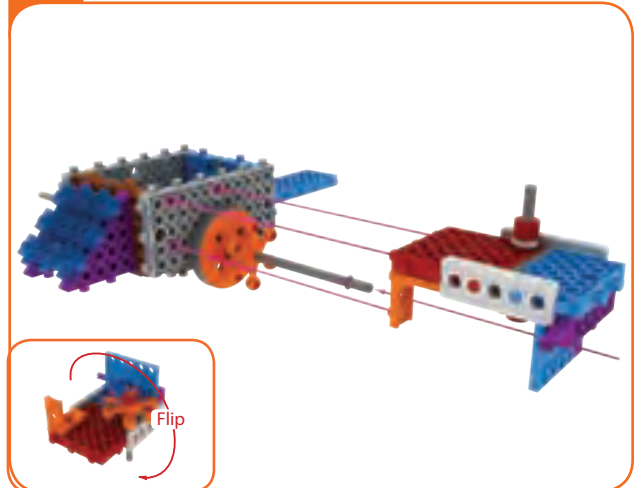
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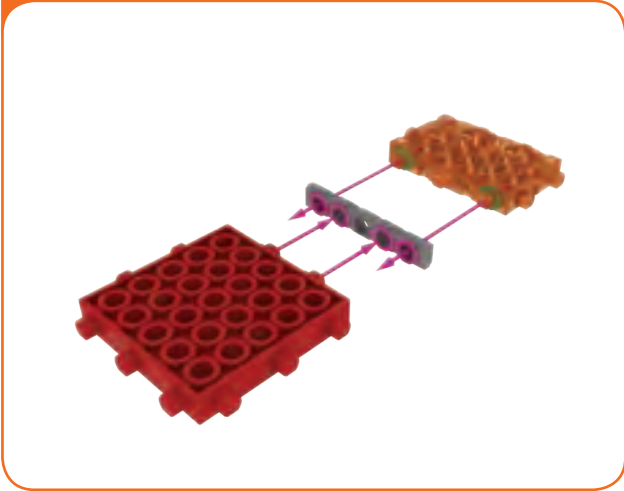
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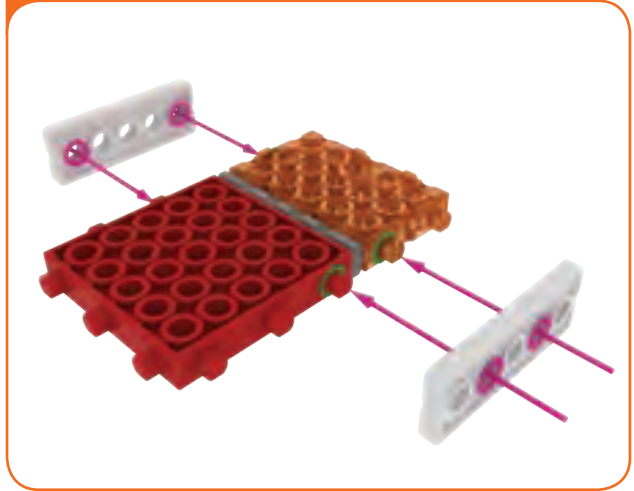
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21



22



23

-  x1
-  x2
-  x1
-  x1

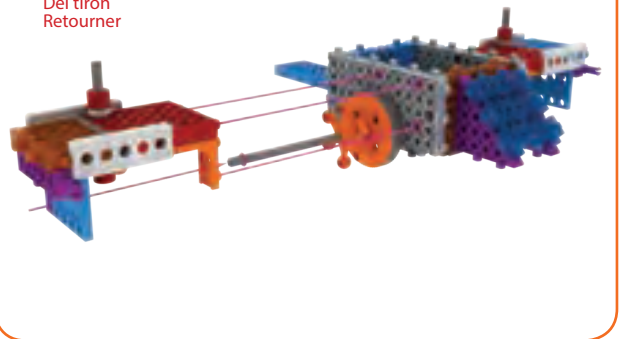


 1:1

24



Del tirón
Returner



25

-  x2



26

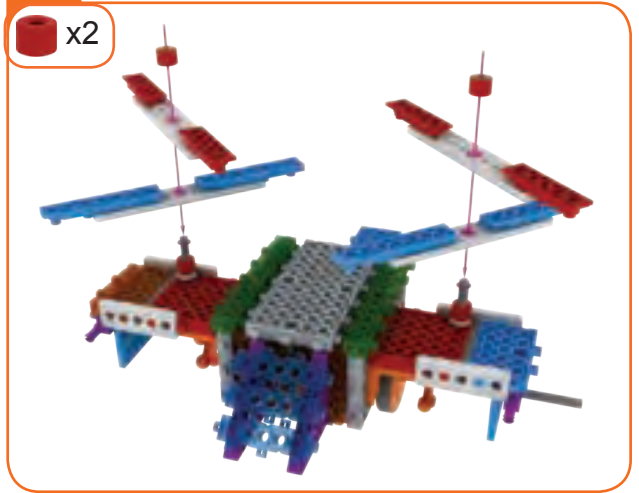


x2

27



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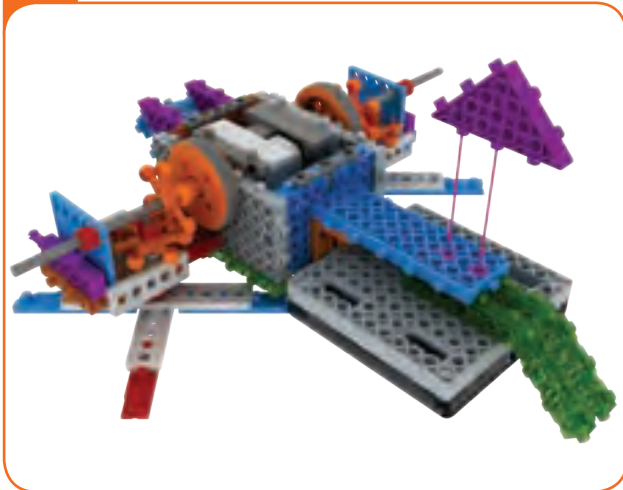
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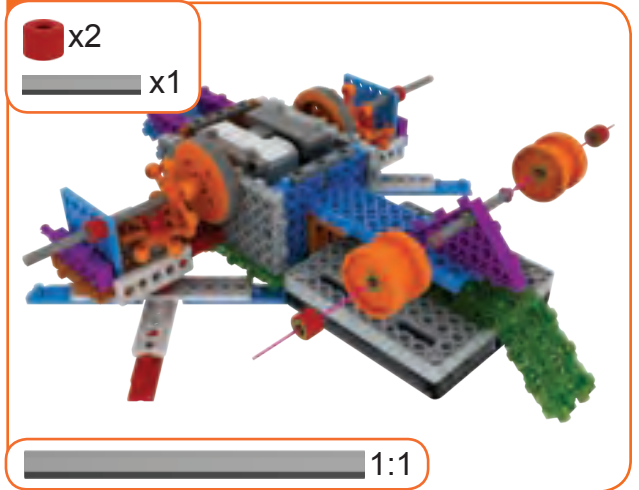
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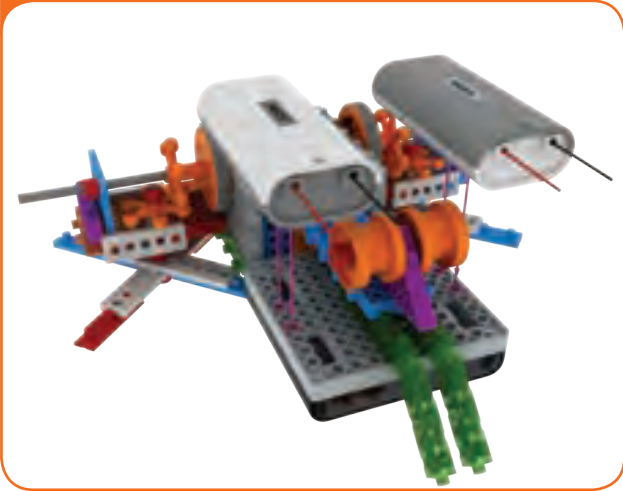
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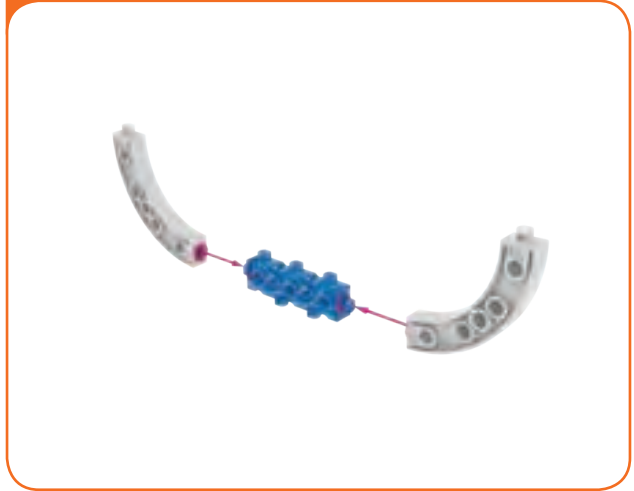
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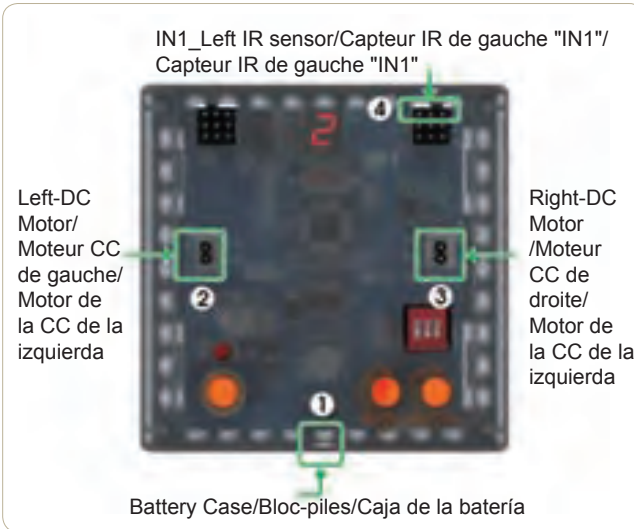


37



How to operate the Helicopter Comment faire fonctionner l'hélicoptère Funcionamiento del helicóptero

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:



4. Press the START button.
5. Select Remote ID.

4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

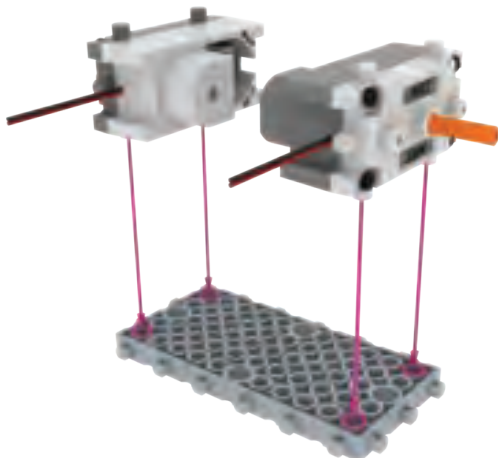
How to make it move? • Comment le faire bouger? • Cómo hacer que se mueva



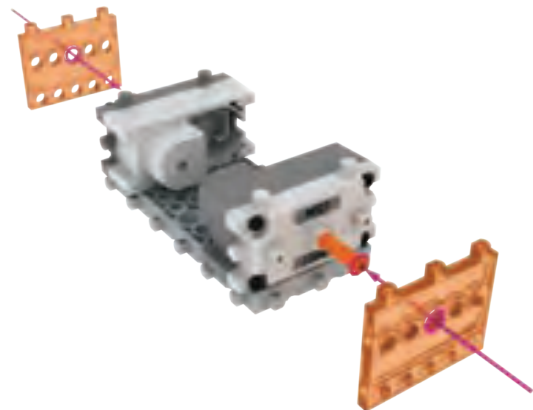
Robot 9: Knight and Donkey (Don Ki Ho Te)
Robot 9: caballero y burro (Don Ki Ho Te)
Robot 9 : Le chevalier et l'âne



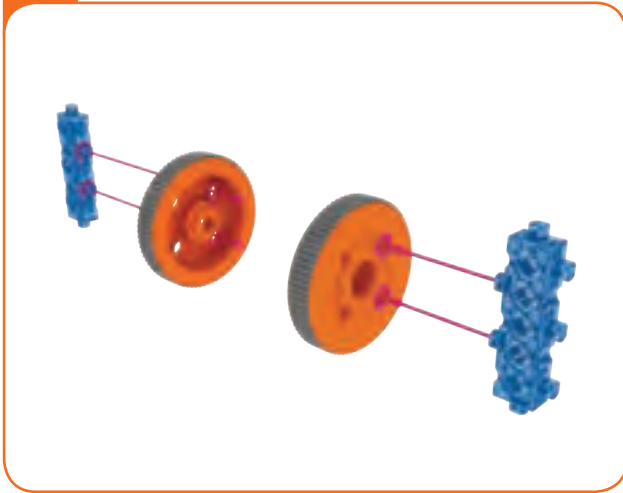
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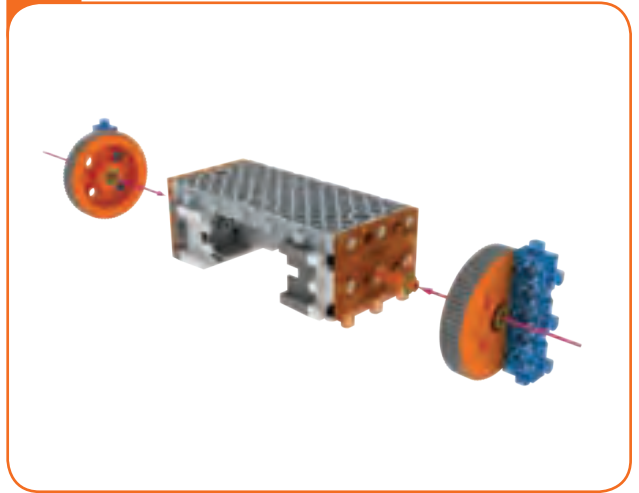
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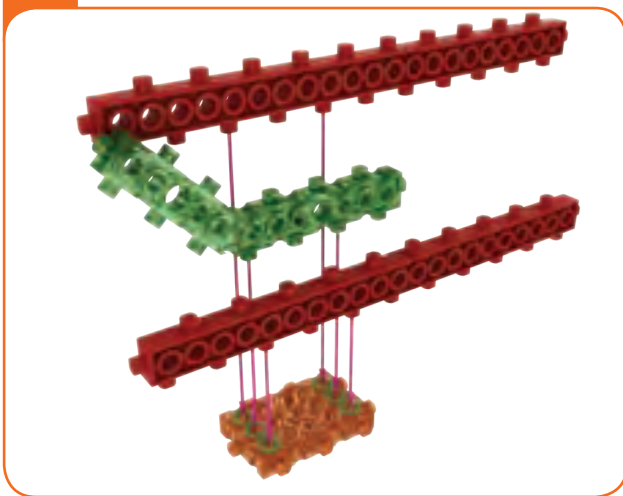
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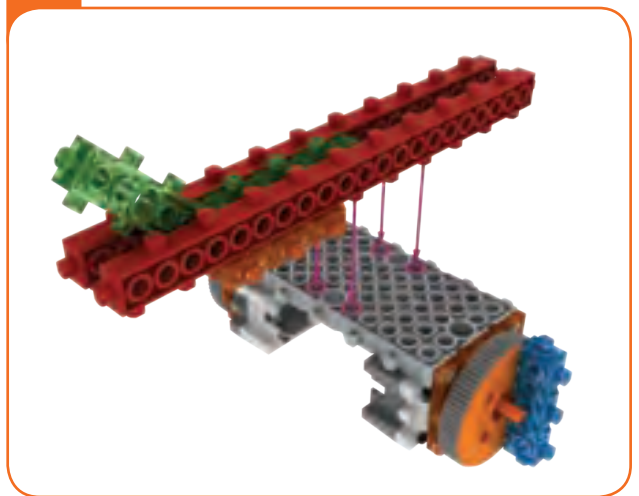
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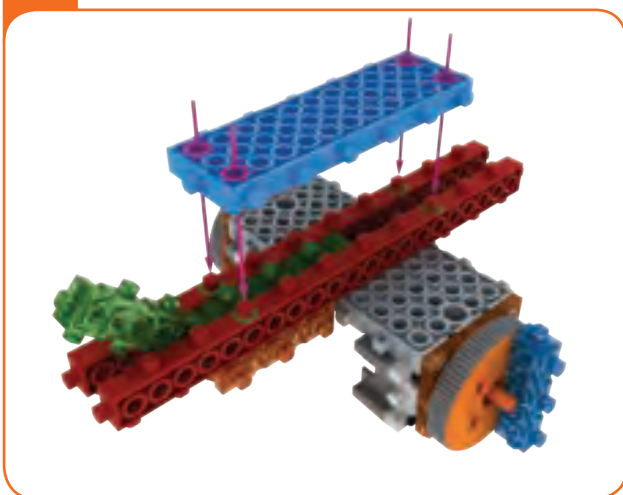
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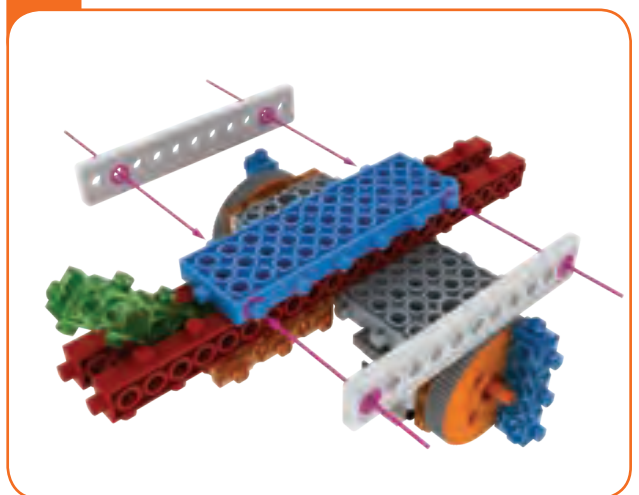
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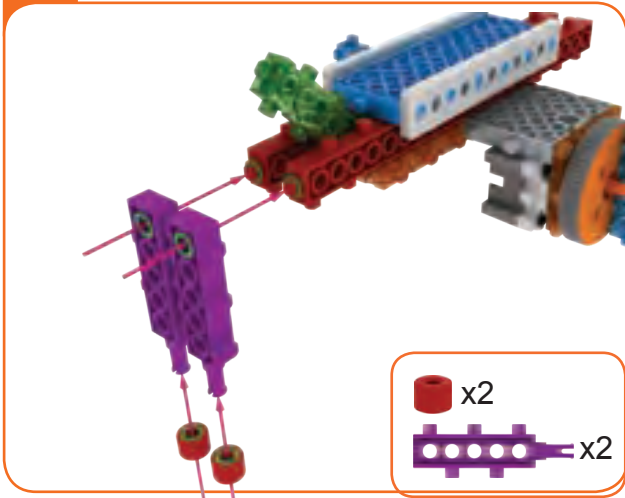
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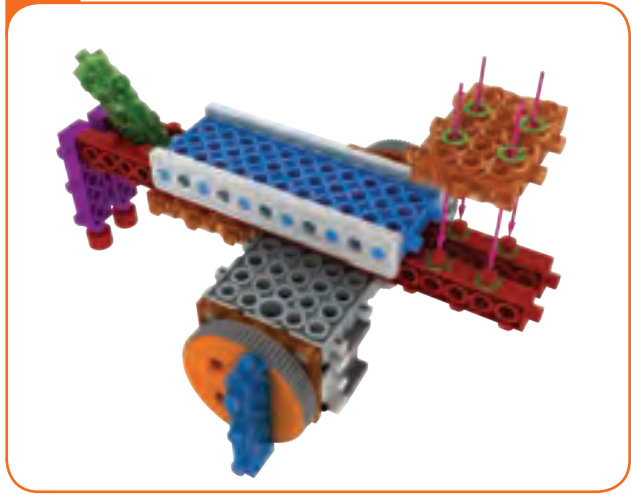
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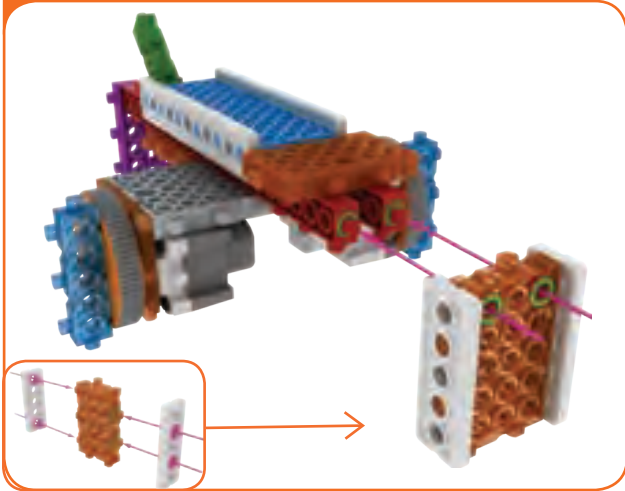
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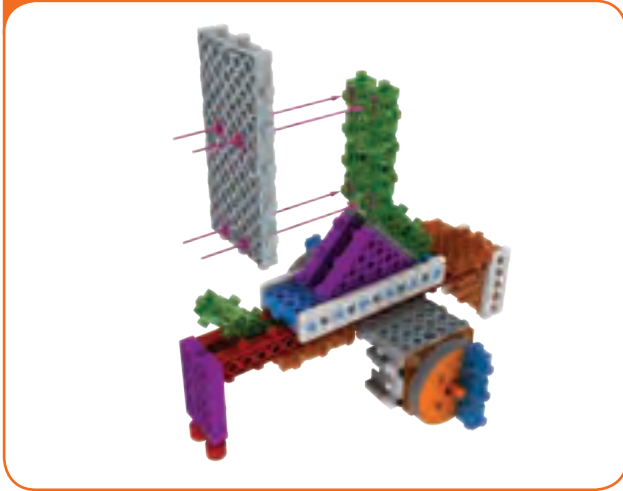
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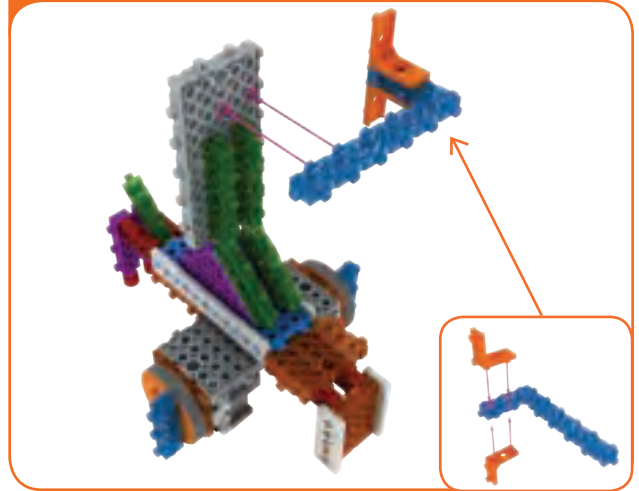
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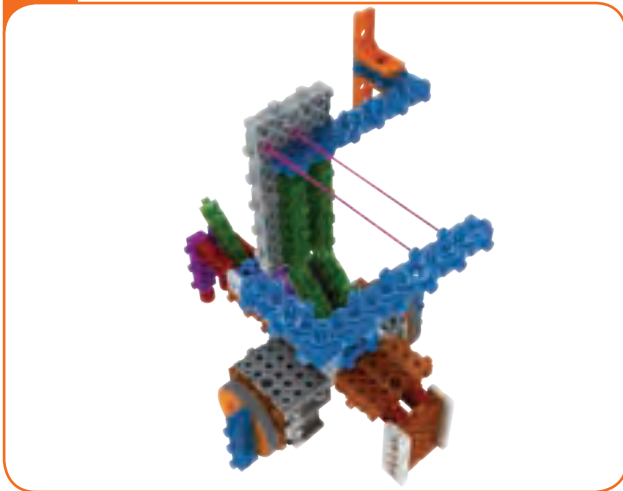
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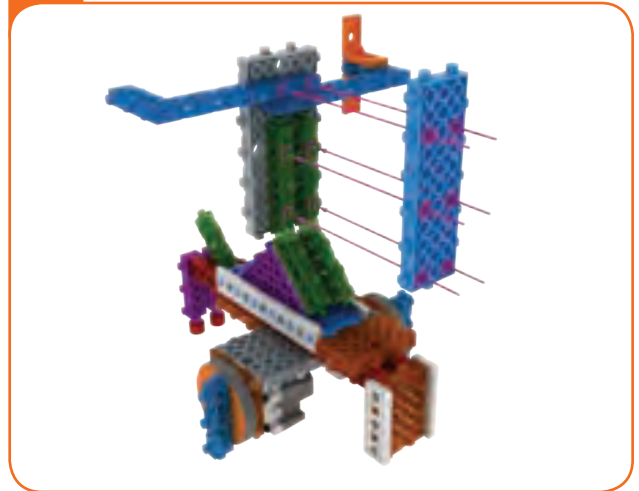
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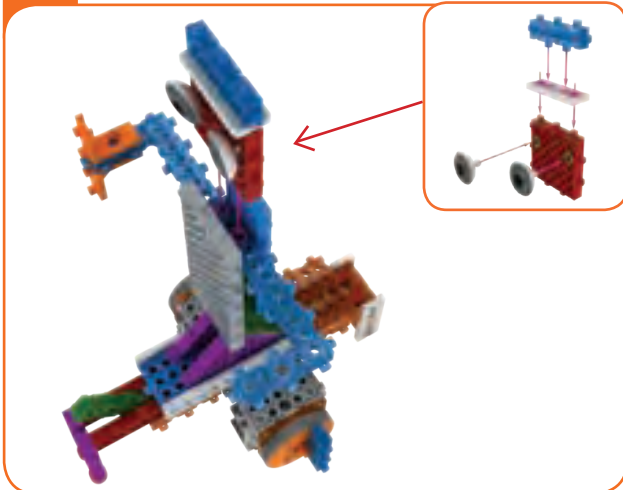
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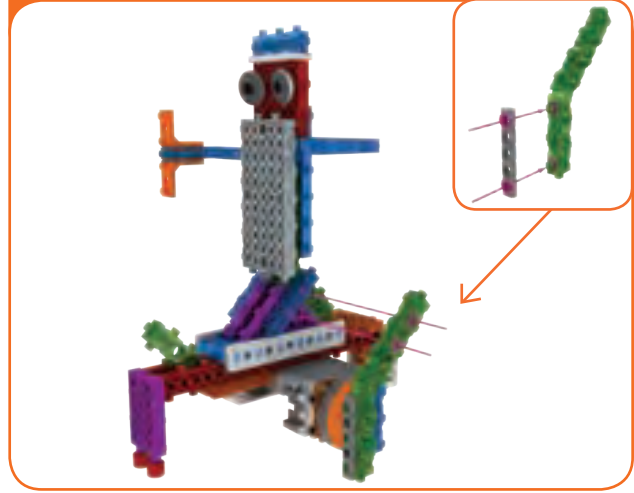
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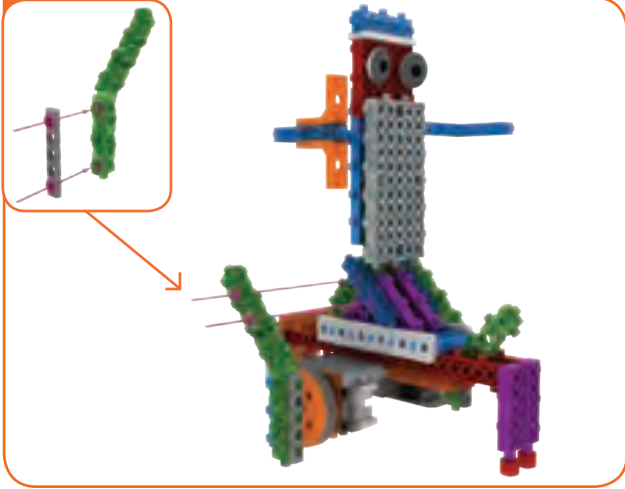
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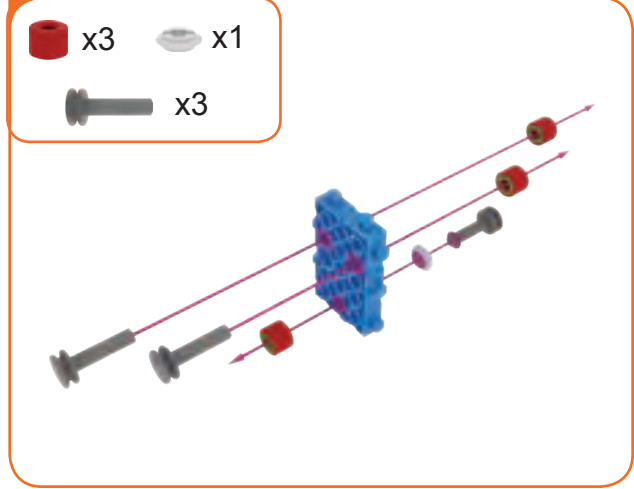
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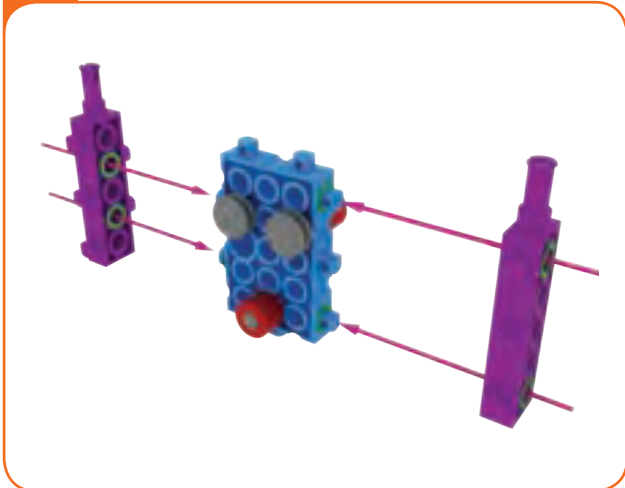
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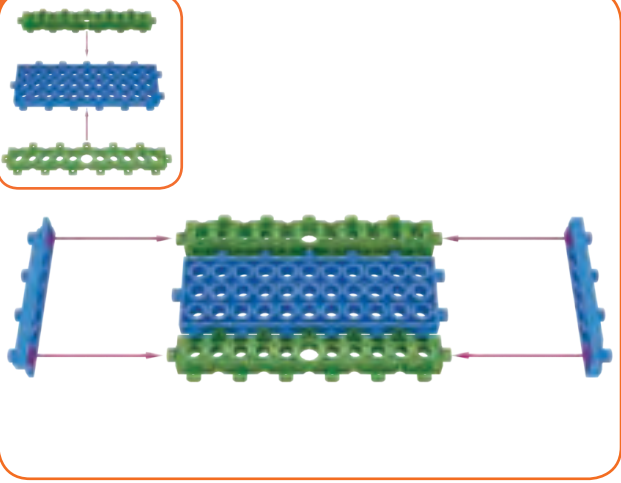
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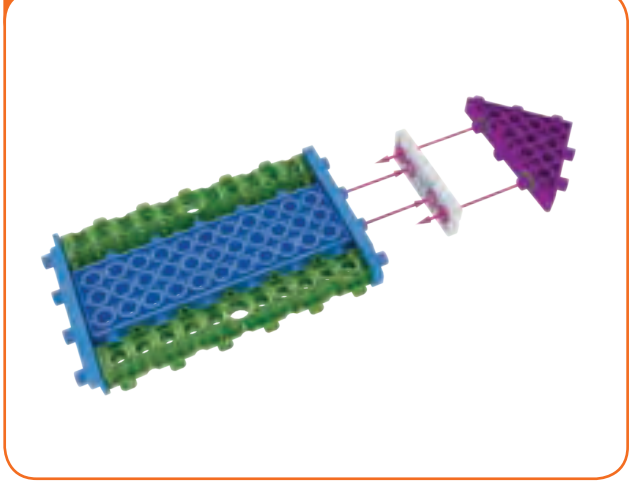
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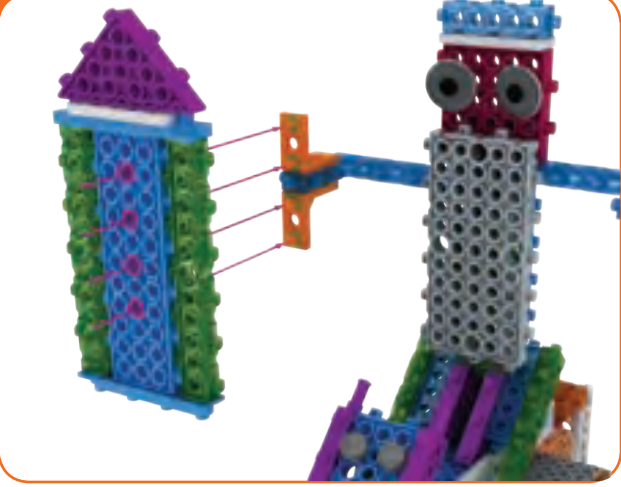
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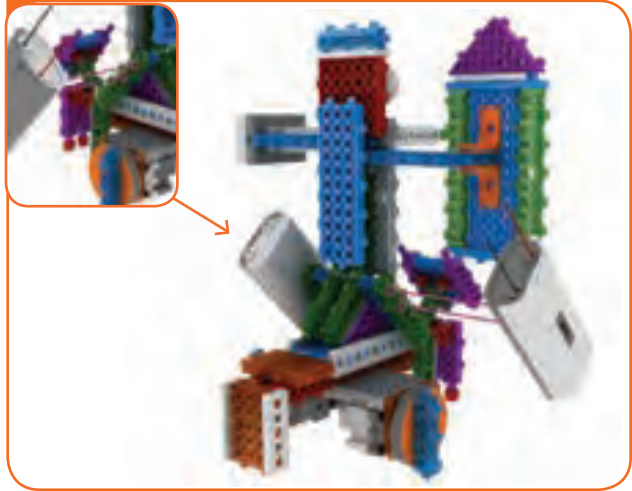
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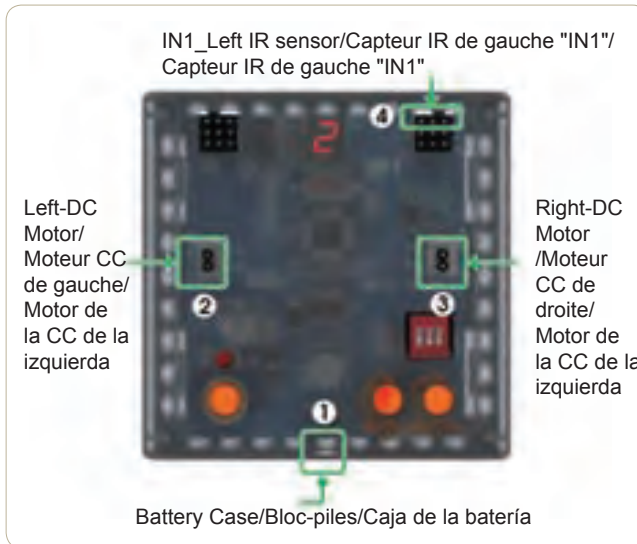


36



How to operate Knight and Donkey Comment faire fonctionner le chevalier et l'âne Funcionamiento del caballero y el burro

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:



4. Press the START button.
5. Select Remote ID.

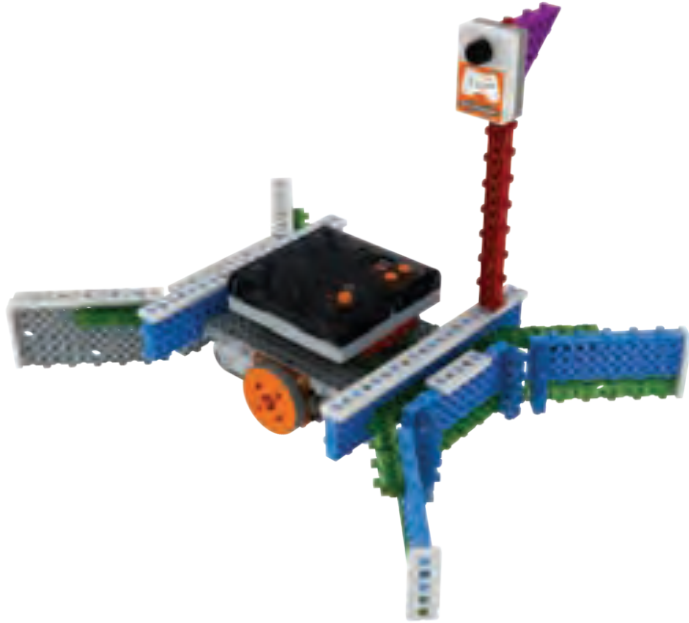
4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

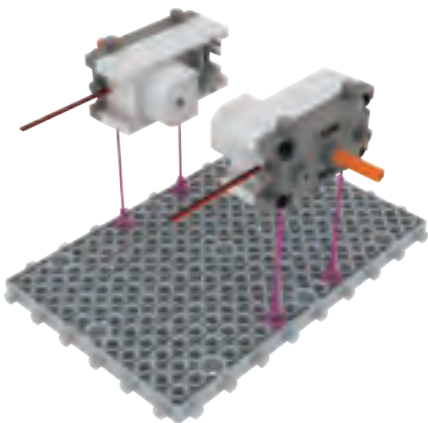
How to make it move? • Comment le faire bouger? • Cómo hacer que se mueva



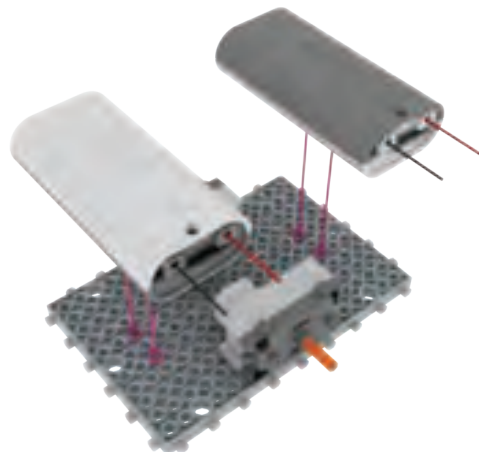
Robot 10: X-Soccer
Robot 10 : Soccer X
Robot 10: X-fútbol



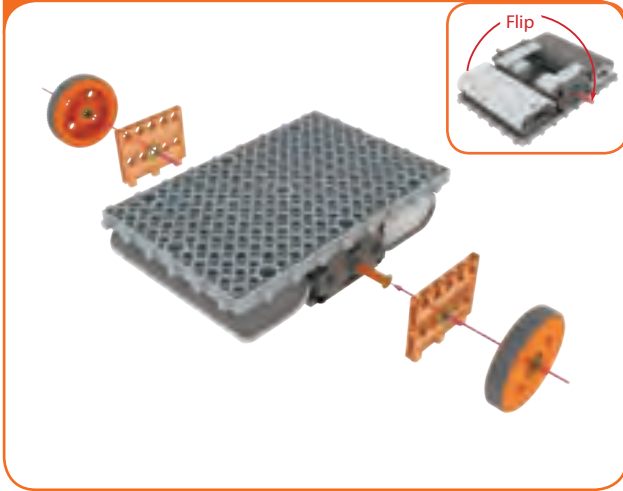
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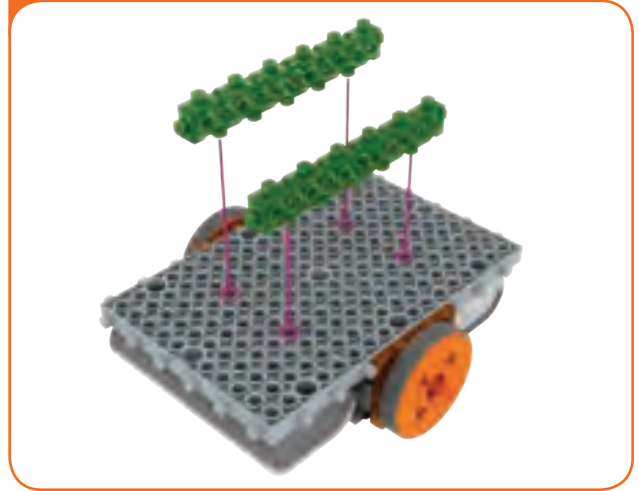
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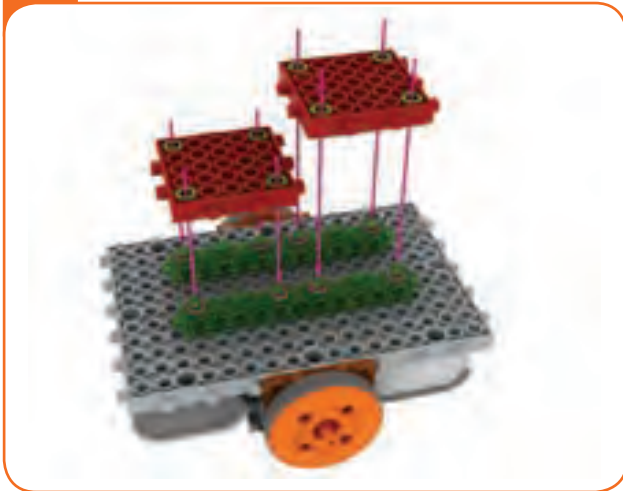
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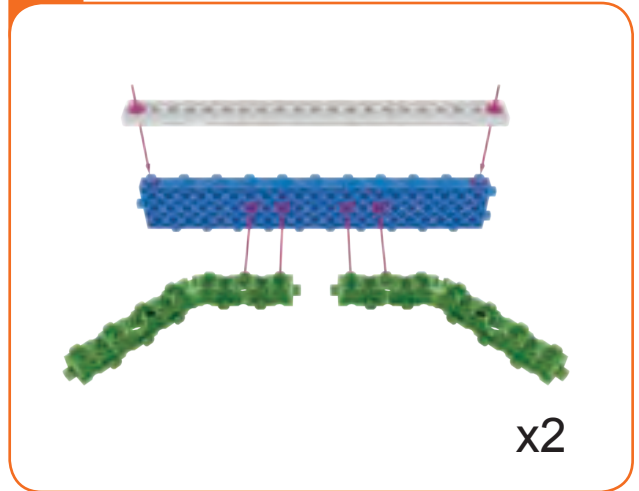
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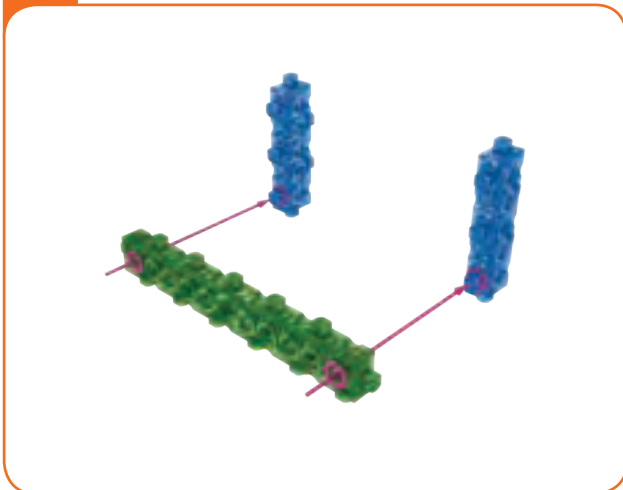
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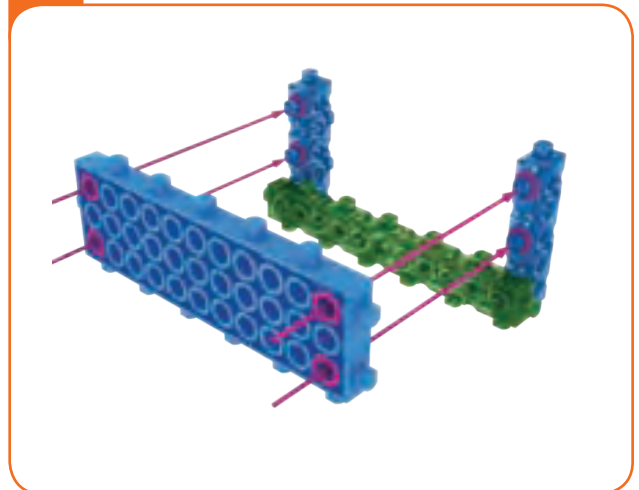
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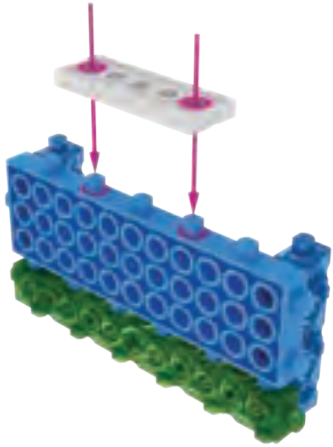
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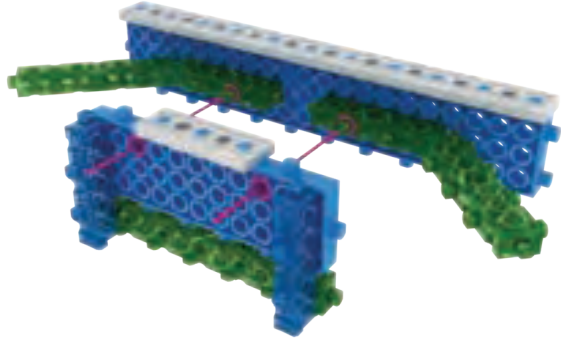
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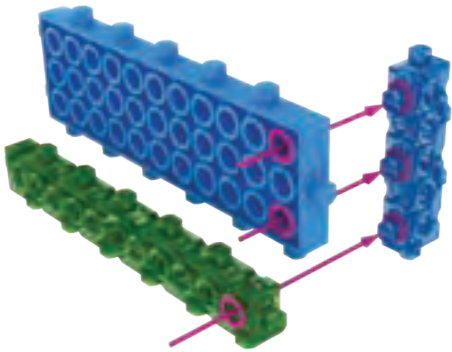
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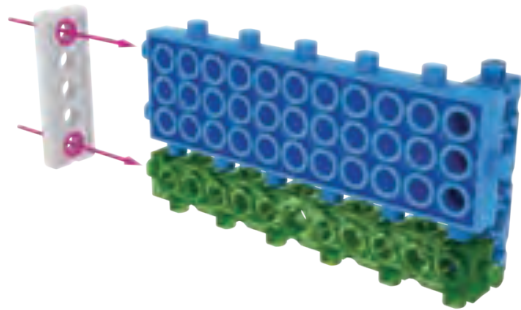
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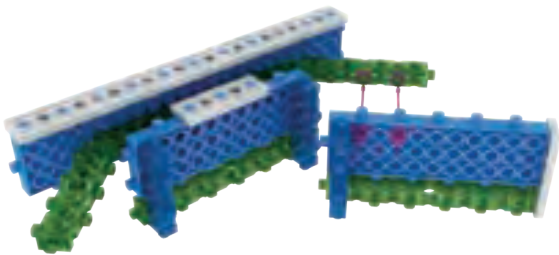
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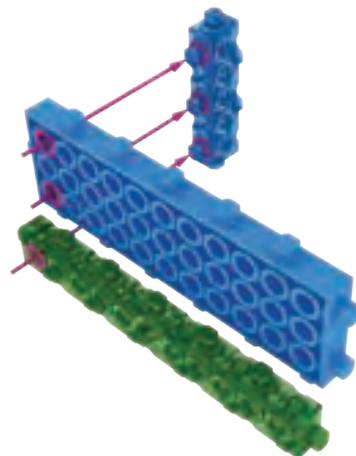
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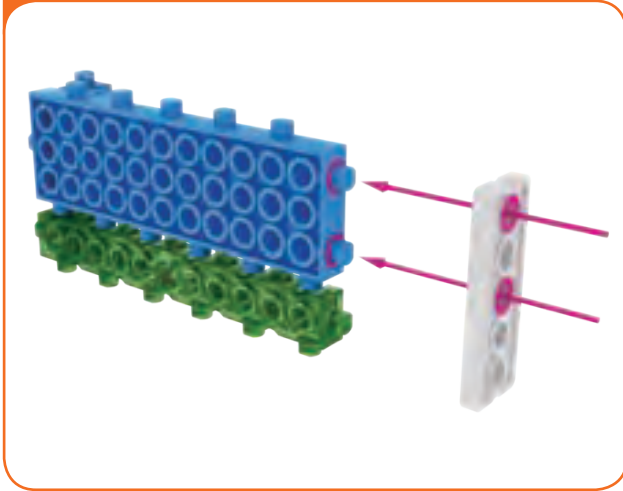
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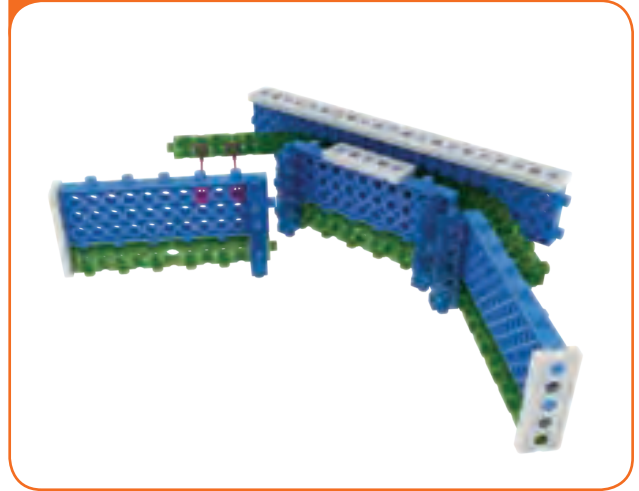
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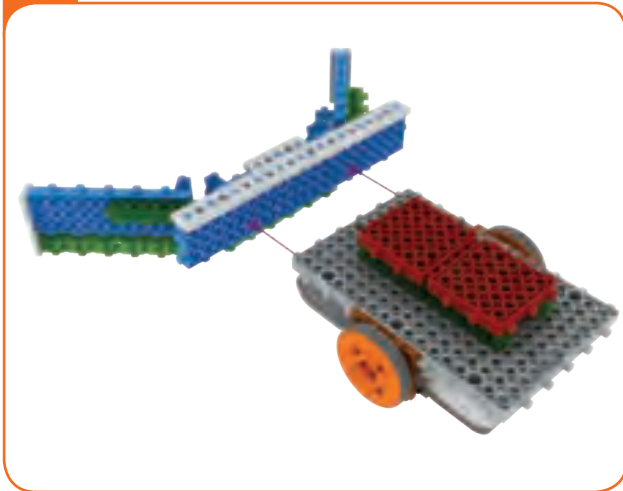
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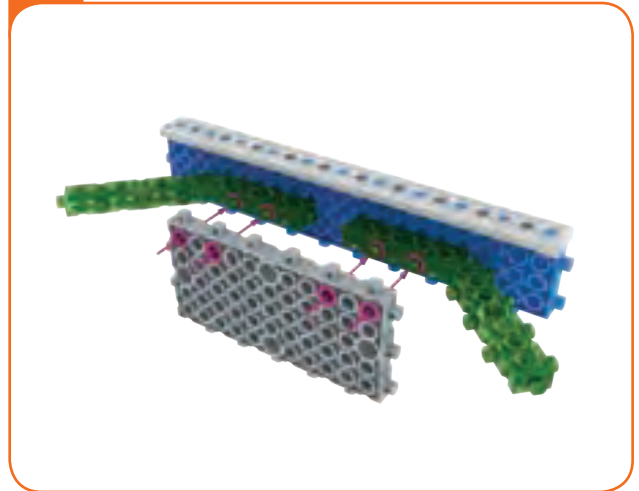
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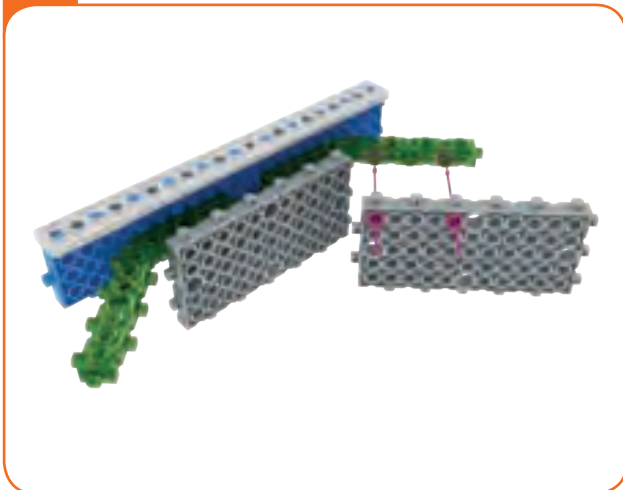
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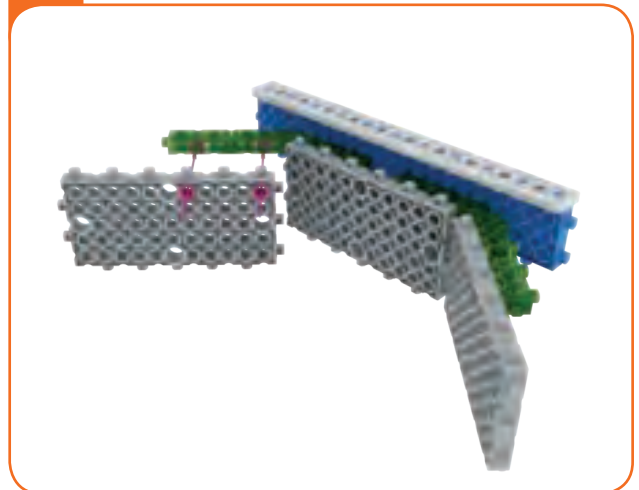
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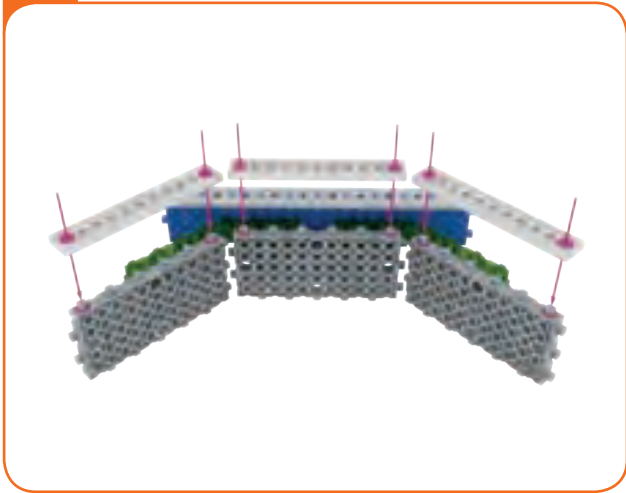
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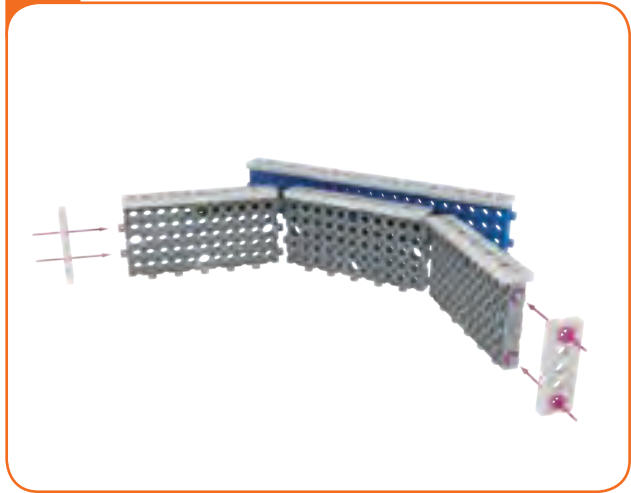
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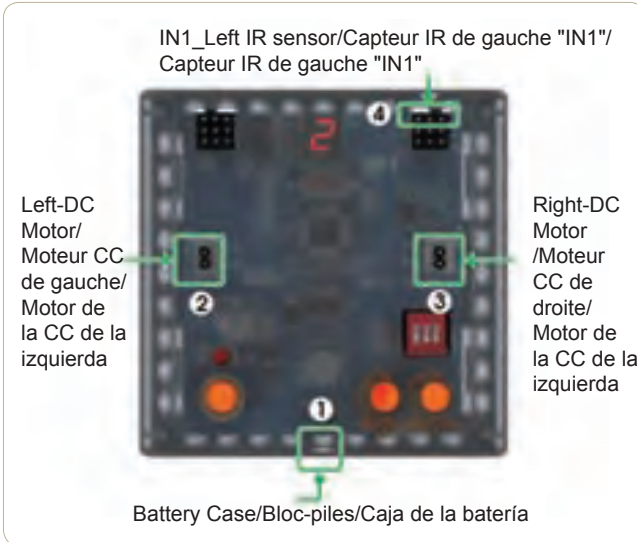


25



How to operate X-Soccer Comment faire fonctionner le Soccer X Funcionamiento del caballero y el burro

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:



4. Press the START button.
5. Select Remote ID.

4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

How to make it move? • Comment le faire bouger? • Cómo hacer que se mueva

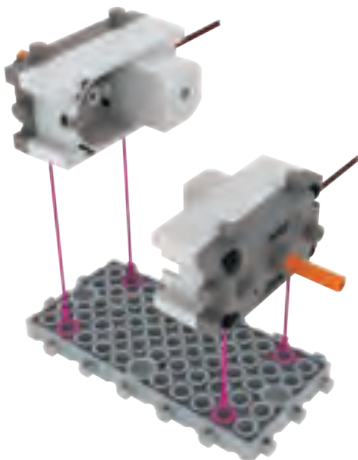


- ※ Let's play X-Soccer game with friends. Make your own soccer field with blocks and frames.
- ※ Jouons un jeu de soccer X avec les ami(e)s. Faites votre propre terrain de soccer avec les blocs et les armatures.
- ※ Vamos a jugar juego de X-fútbol con los amigos. Hacer tu propio campo de fútbol con bloques y marcos.

Robot 11: Drummer Baby Bear
Robot 11 : Ourson batteur
Robot 11: Baterista bebé oso



1

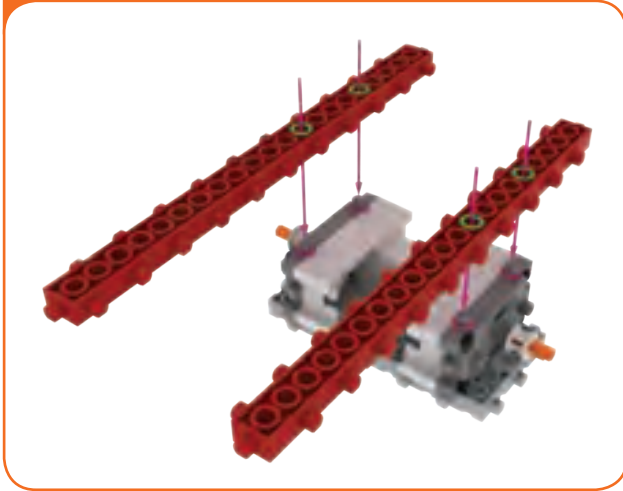


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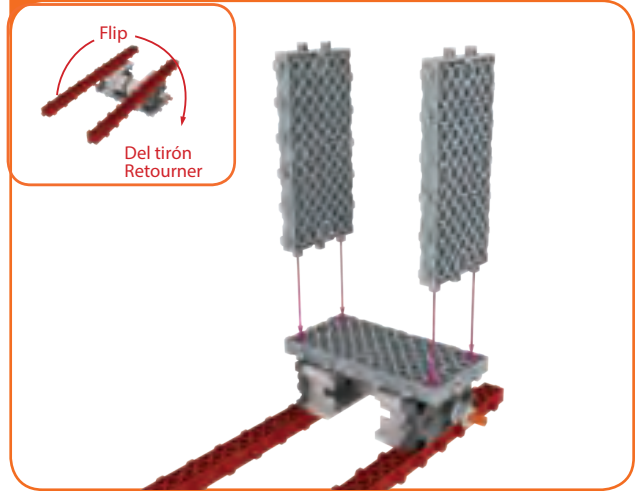
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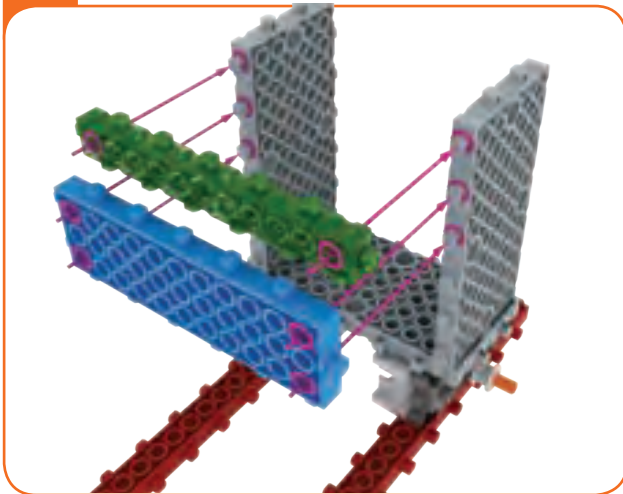
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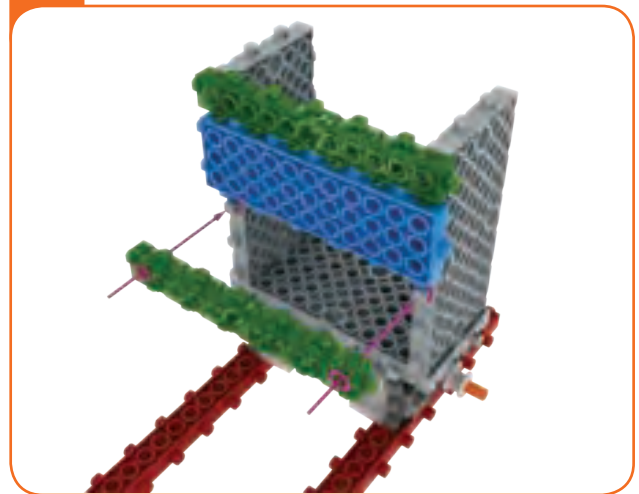
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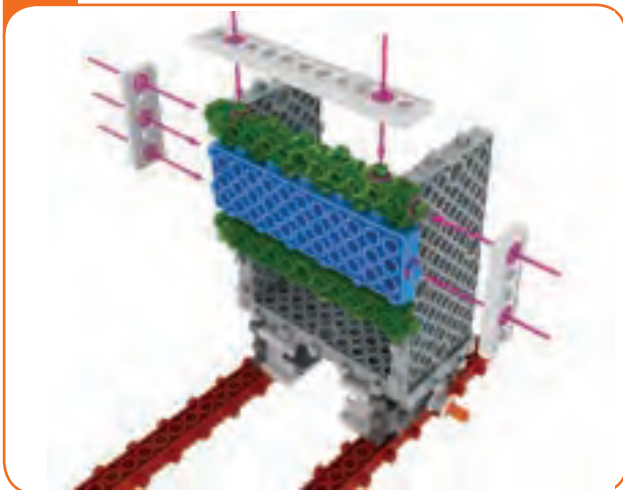
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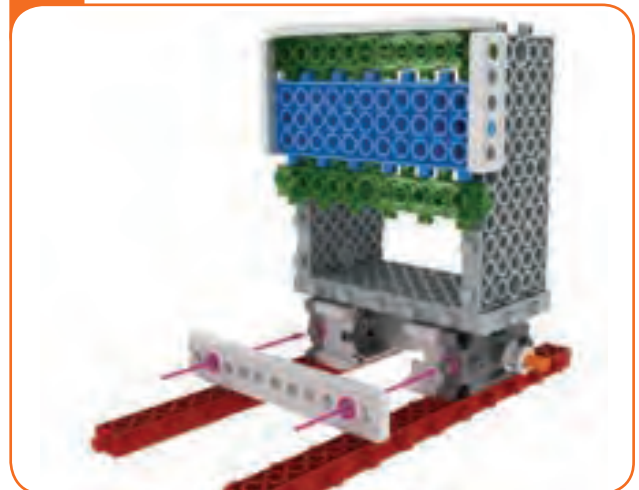
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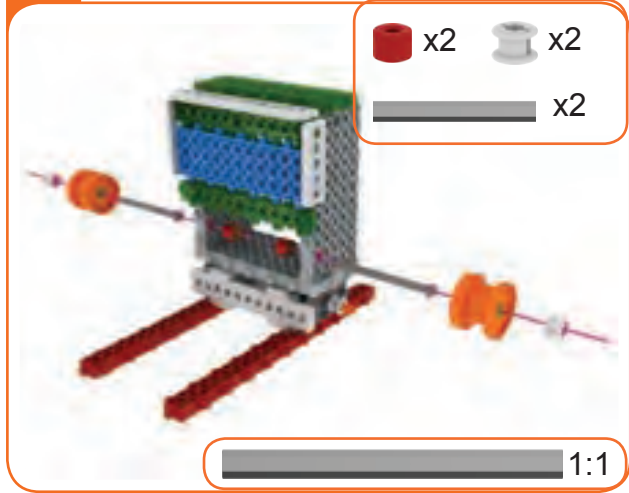
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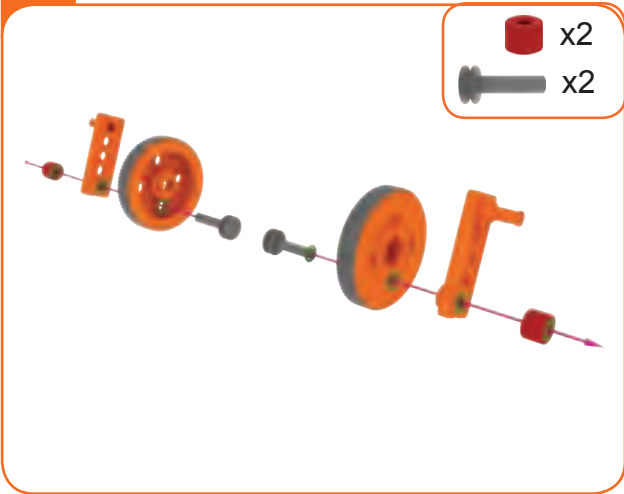
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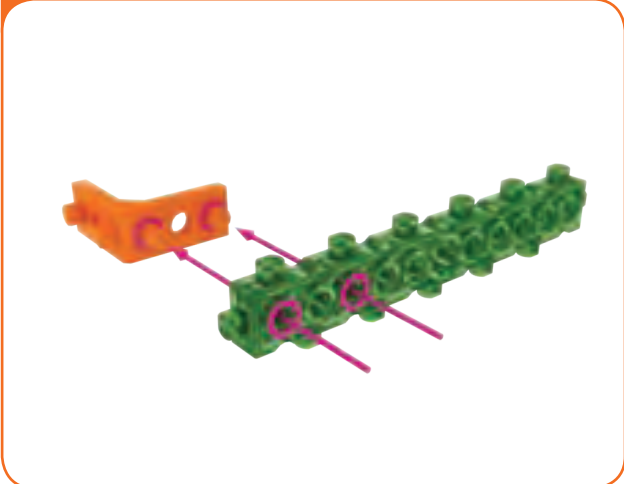
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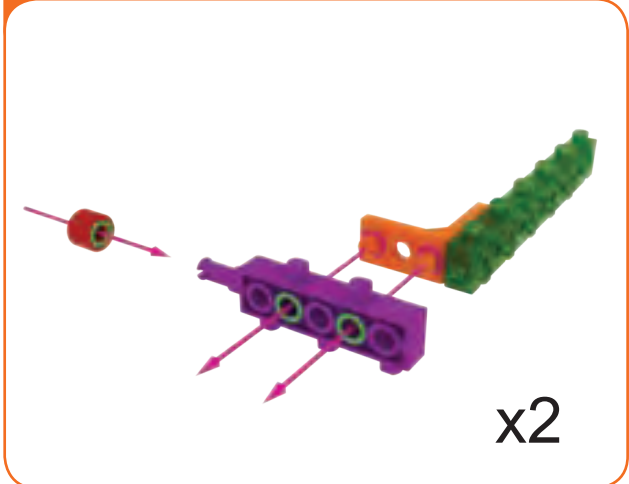
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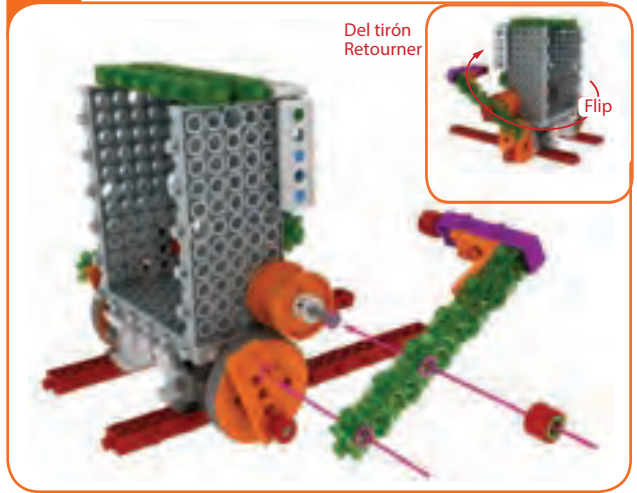
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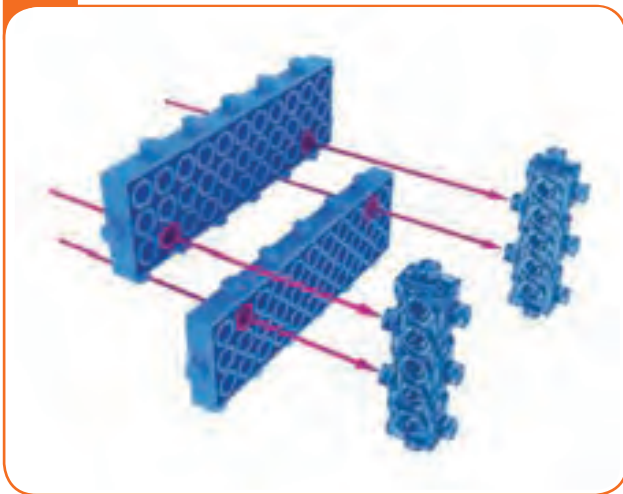
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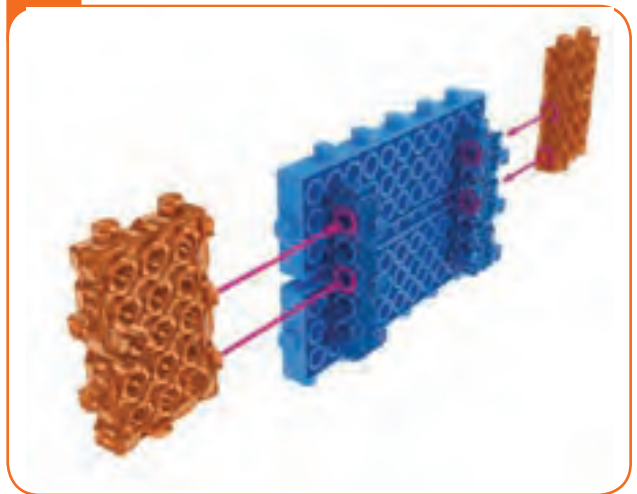
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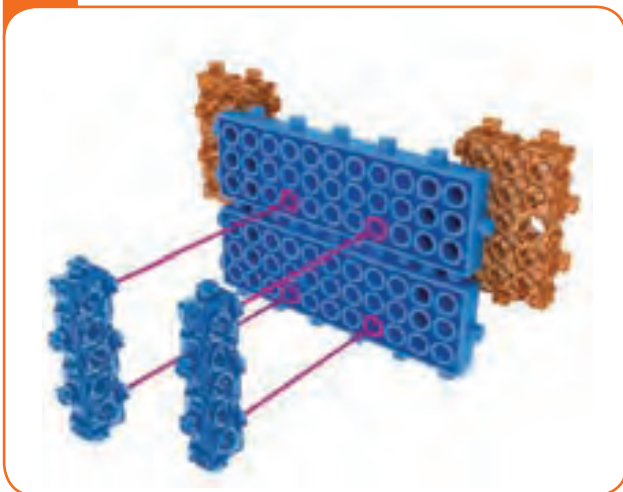
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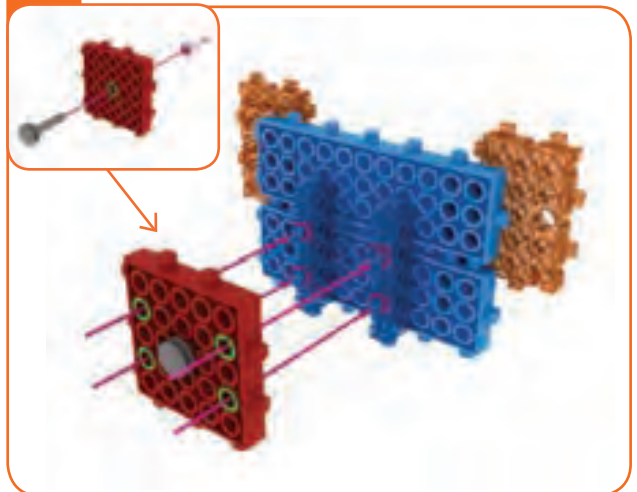
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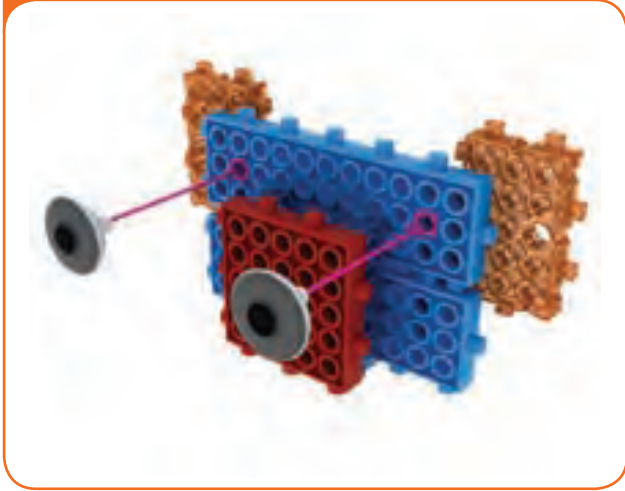
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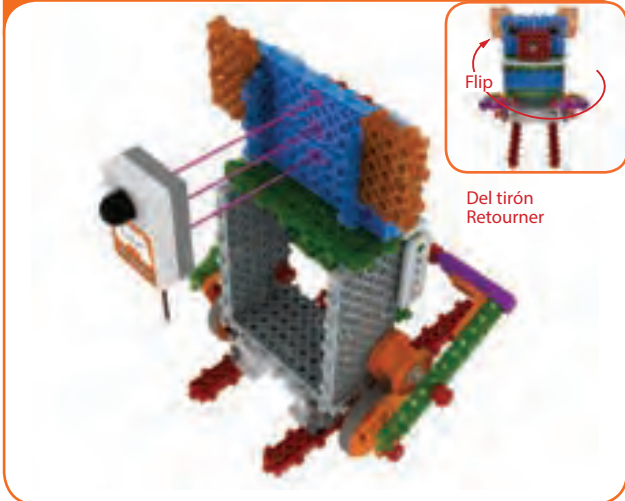
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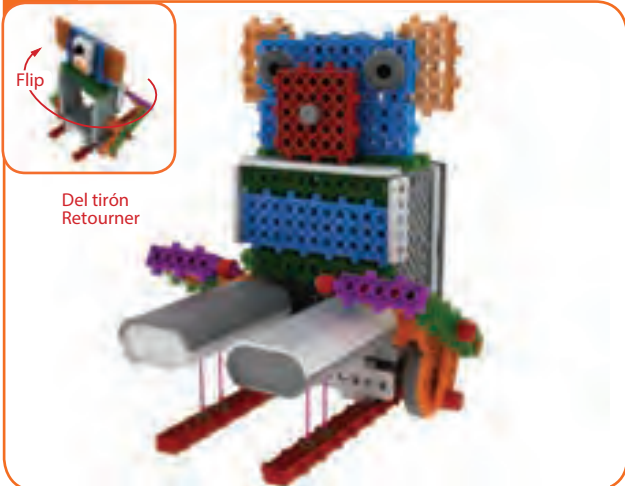
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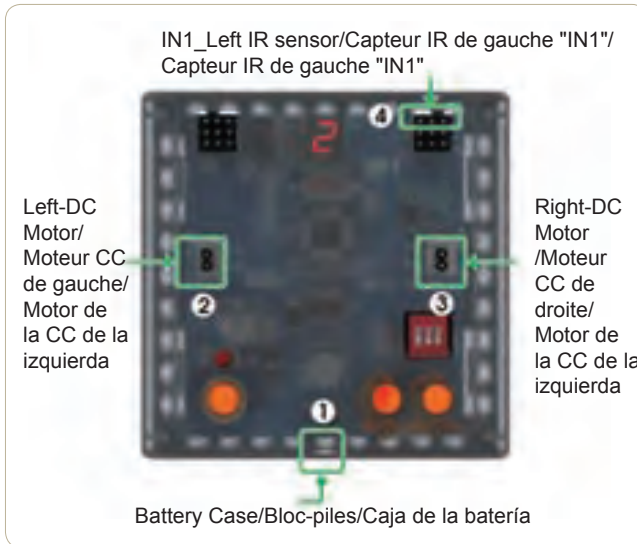


26



How to operate Drummer Baby Bear Comment faire fonctionner l'ourson batteur Funcionamiento del baterista bebé oso

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:



4. Press the START button.
5. Select Remote ID.

4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

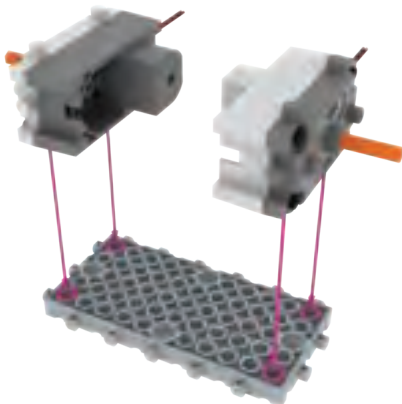
How to make it move? • Comment le faire bouger? • Cómo hacer que se mueva



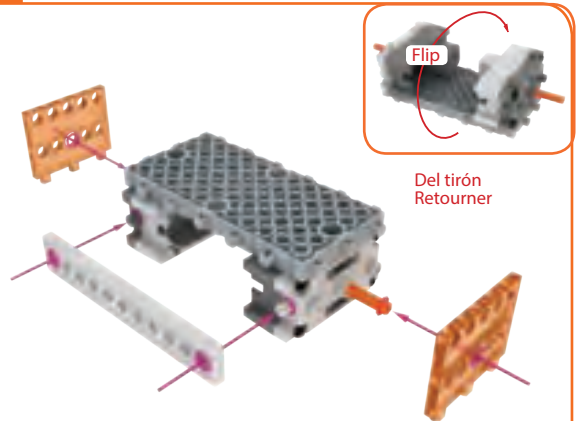
Robot 12: Air Sing Sing Plane
Robot 12 : Ton avion qui chante
Robot 12: Avión de Sing Sing



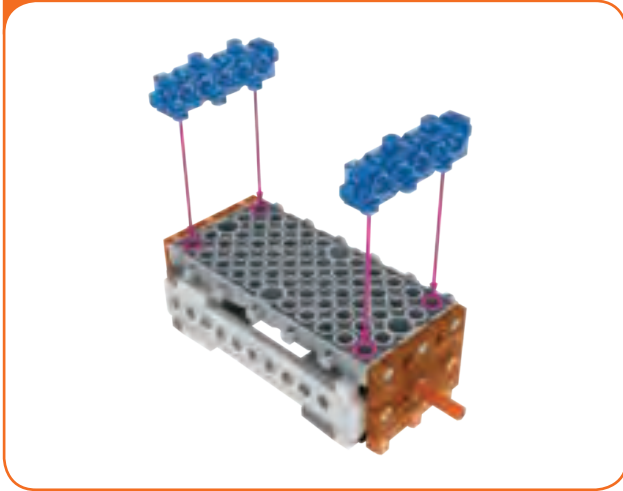
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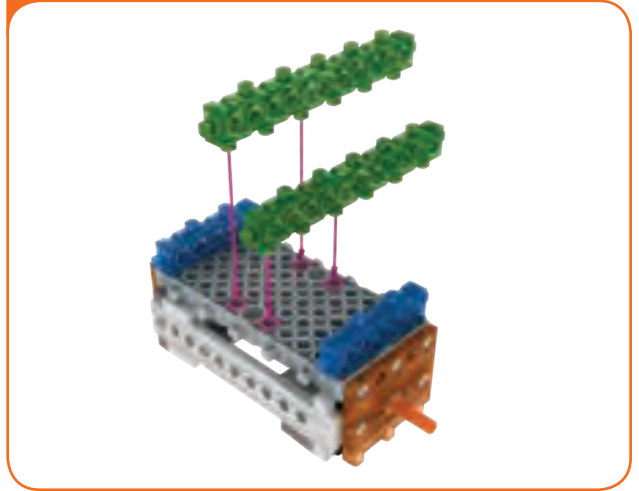
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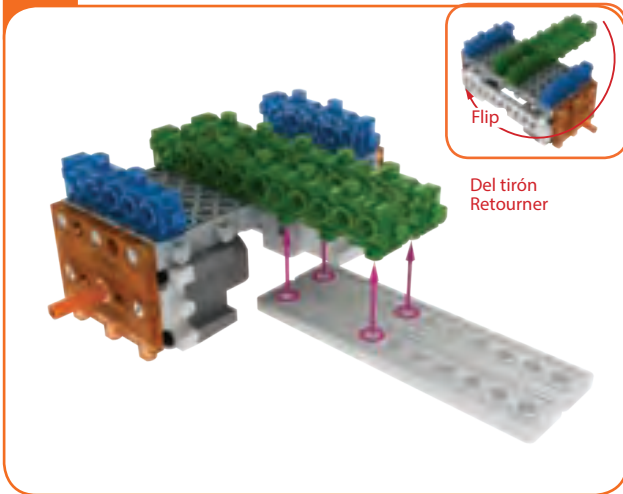
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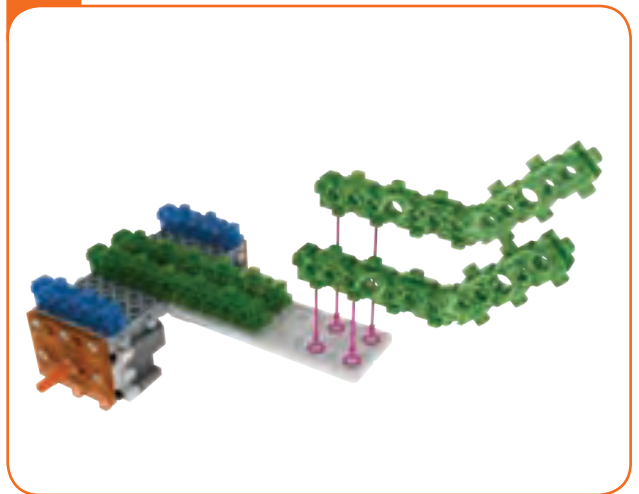
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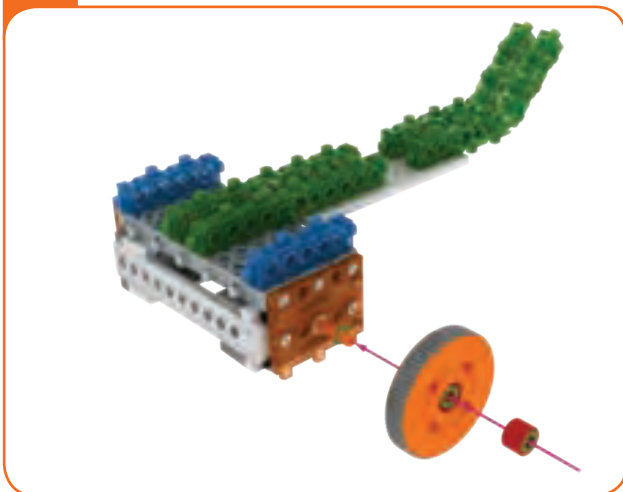
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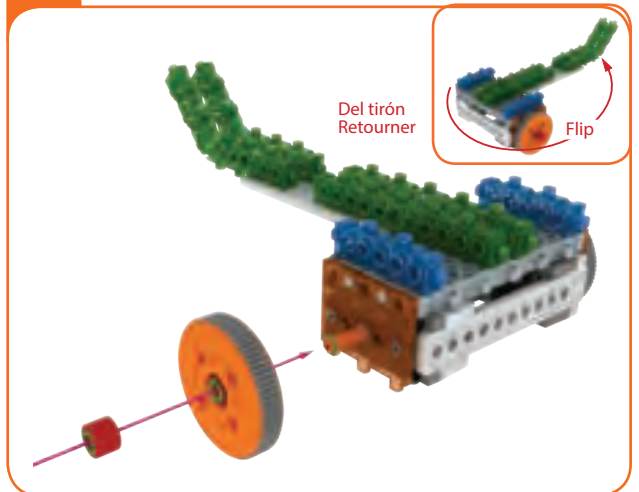
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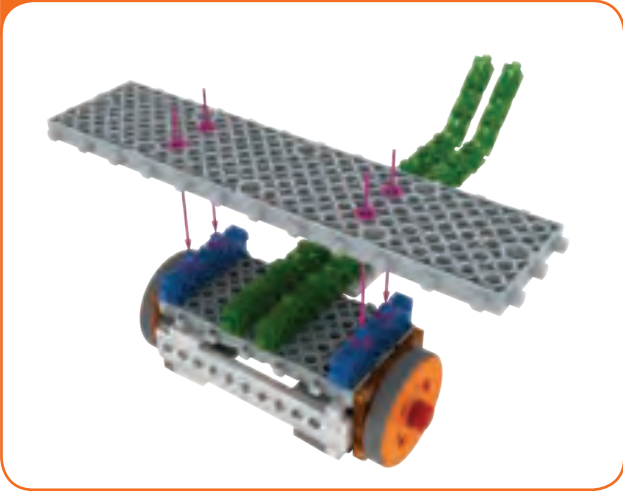
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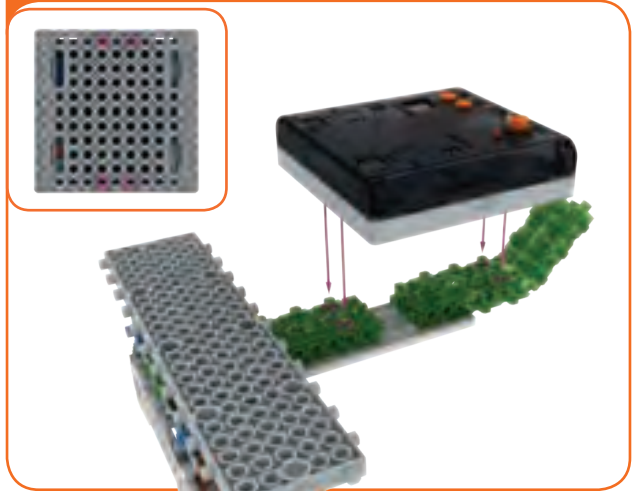
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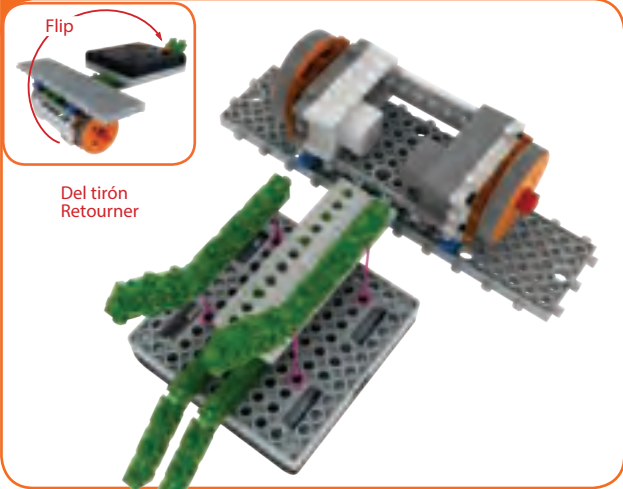
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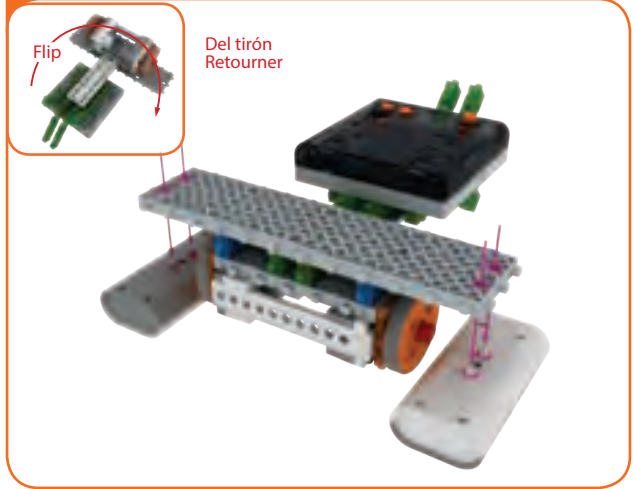
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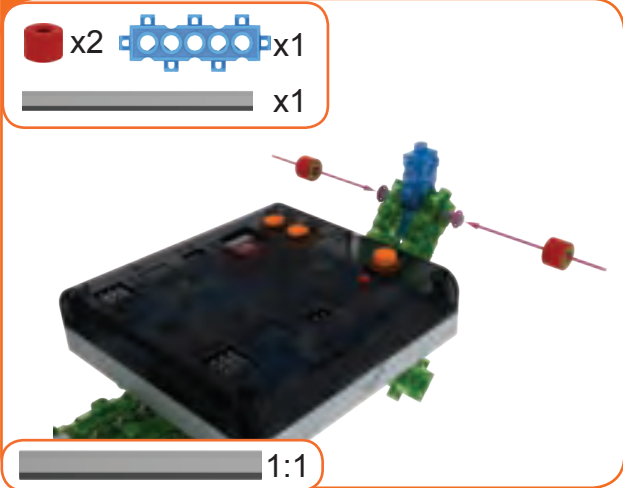
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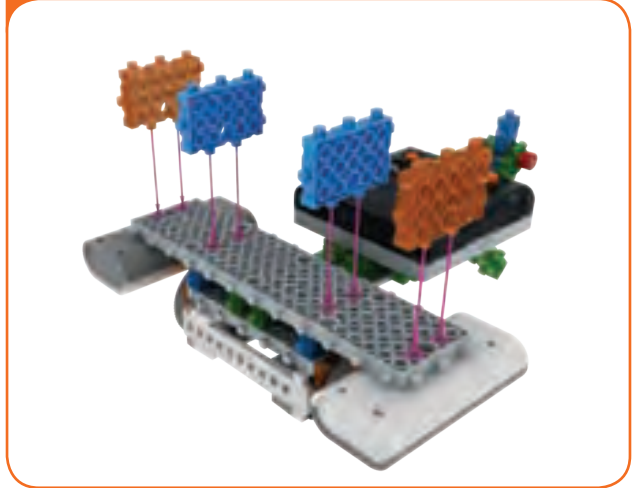
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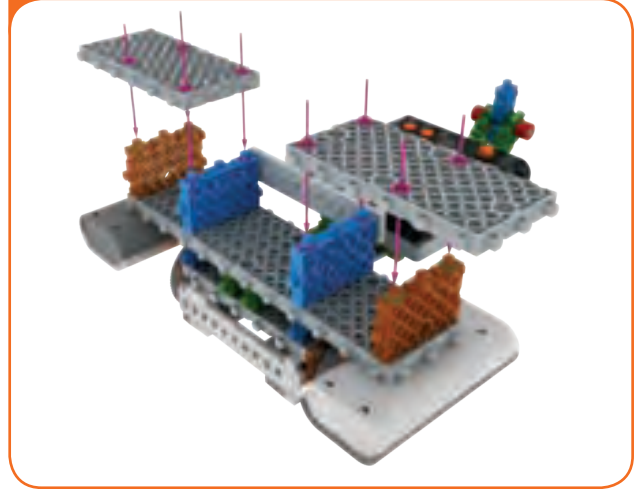
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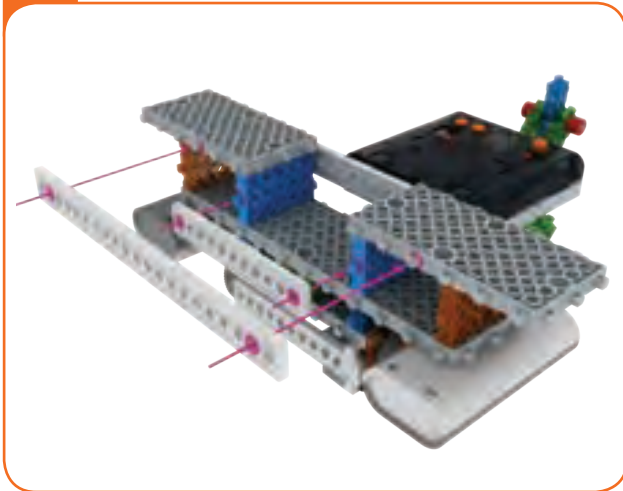
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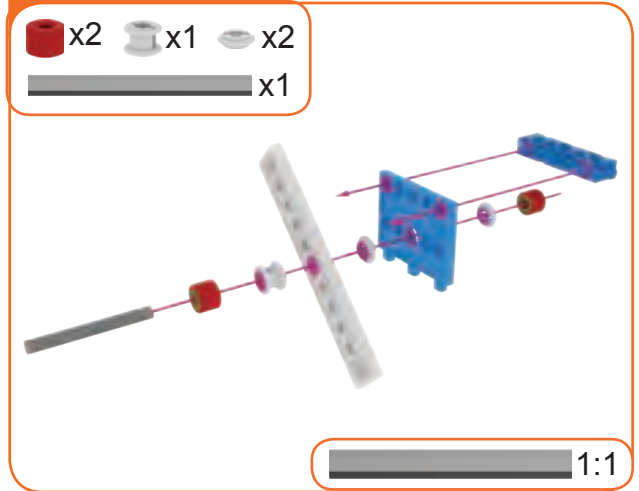
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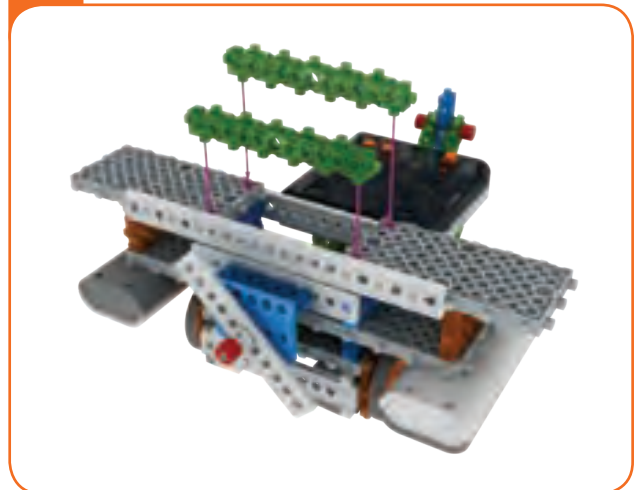
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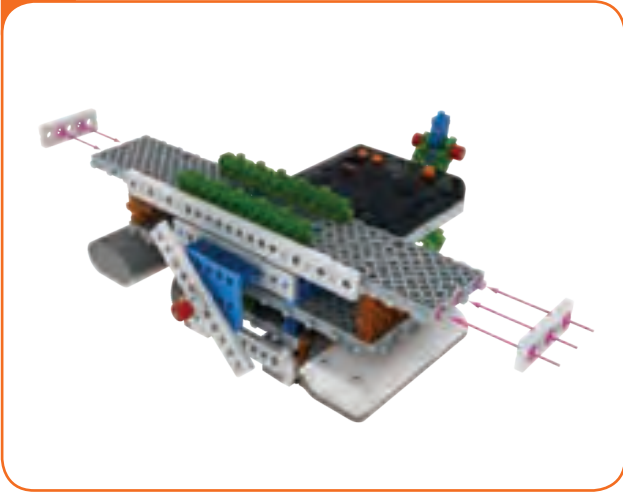
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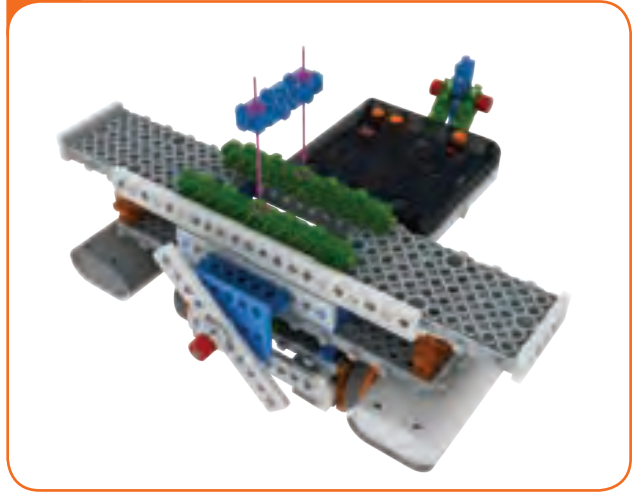
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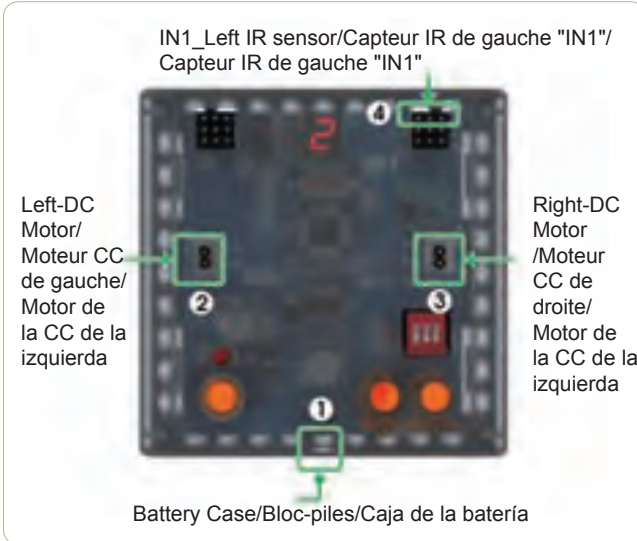
24



How to operate Air Sing Sing Plane

Comment faire fonctionner ton avion chantant Funcionamiento del avión de Sing Sing

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:



4. Press the START button.
5. Select Remote ID.

4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

How to make it move? • Comment le faire bouger? • Cómo hacer que se mueva



*Let's play a bursting balloon game. Ask a teacher or adult to help you use a pushpin or tack to pierce the balloons.

*Jouons un jeu de ballons qui éclatent. Demande au professeur ou à un adulte de t'aider à utiliser une punaise pour percer les ballons.

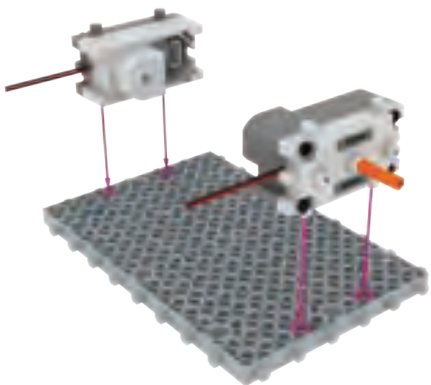
*Vamos a jugar un juego de globo estalla. Pedirle a un profesor o adulto para ayudarlo a utilizar un alfiler o tachuela para pinchar los globos.



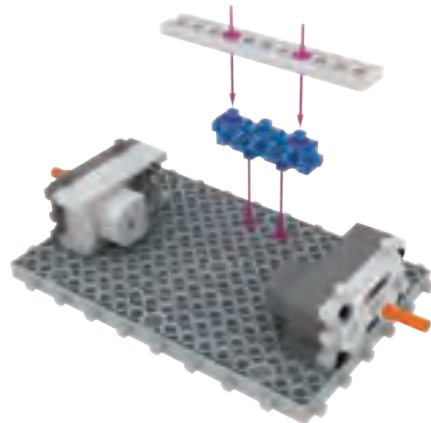
Robot 13: Bumper Car
Robot 13 : Auto tamponneuse
Robot 13: El coche de parachoques



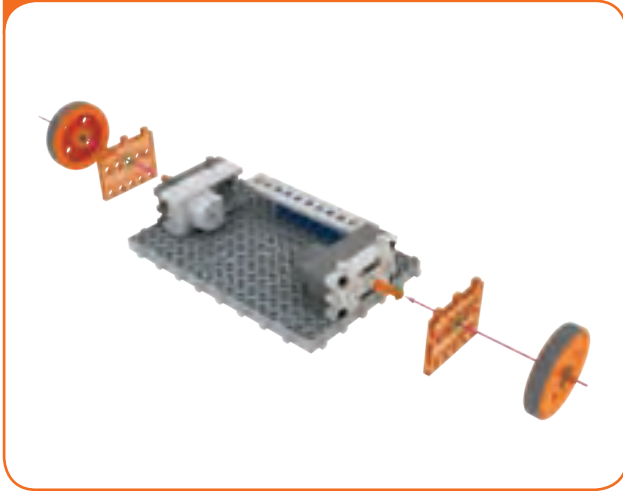
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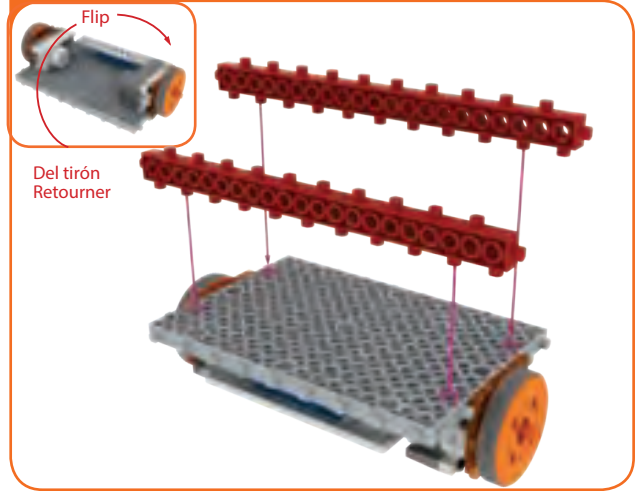
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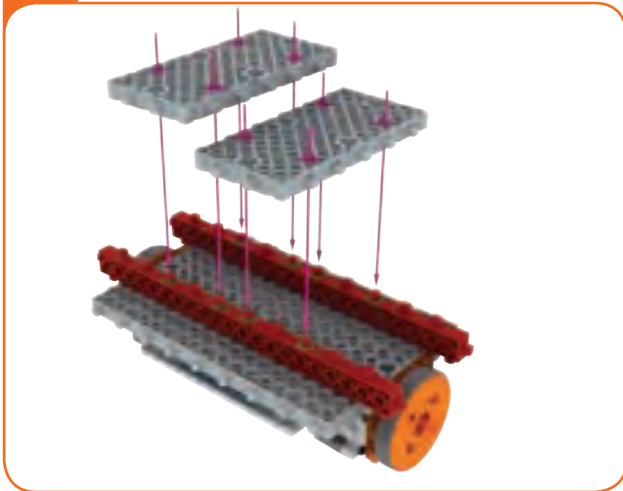
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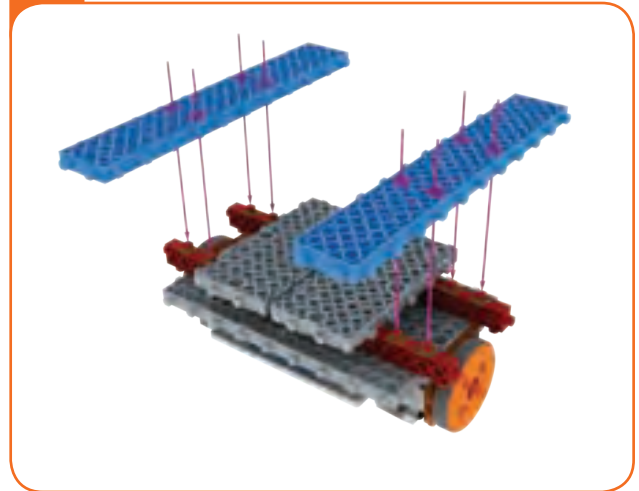
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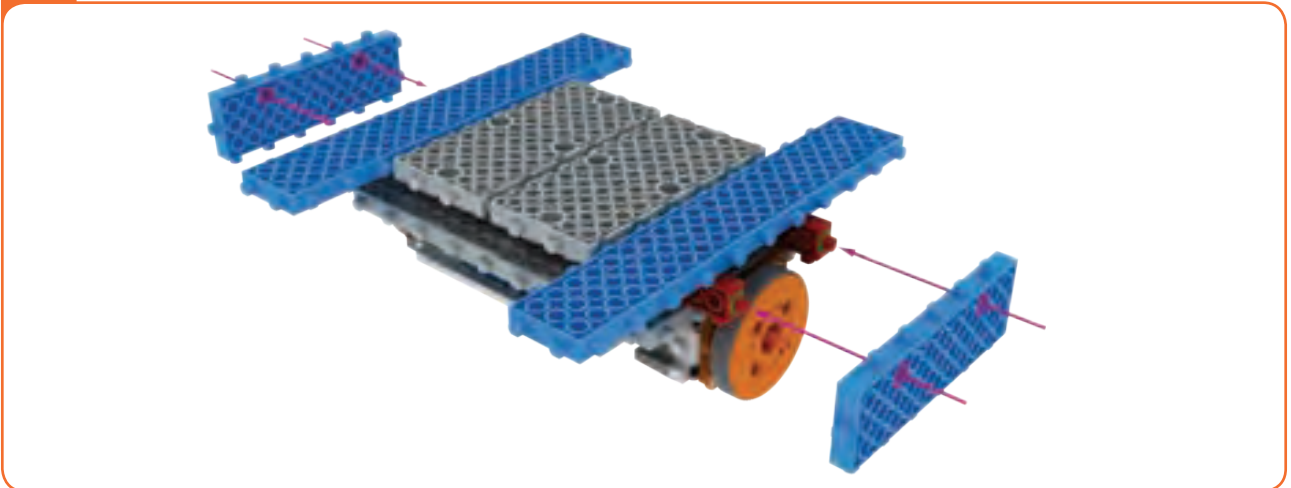
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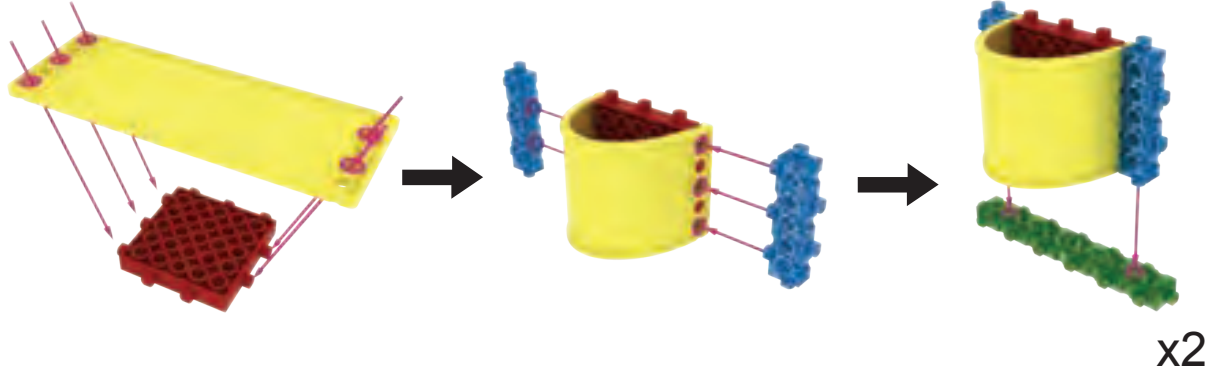
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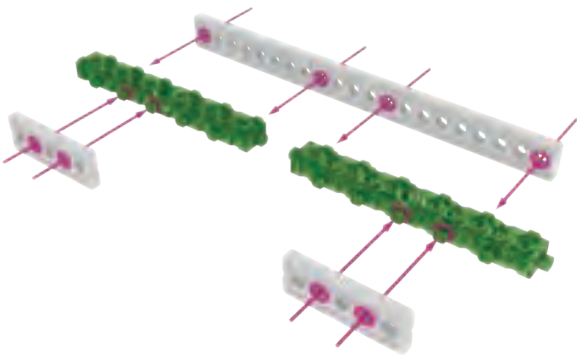
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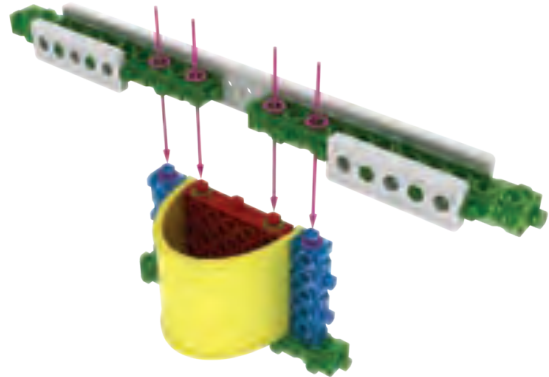
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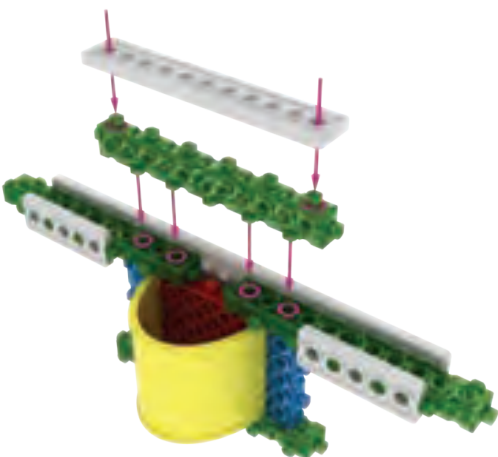
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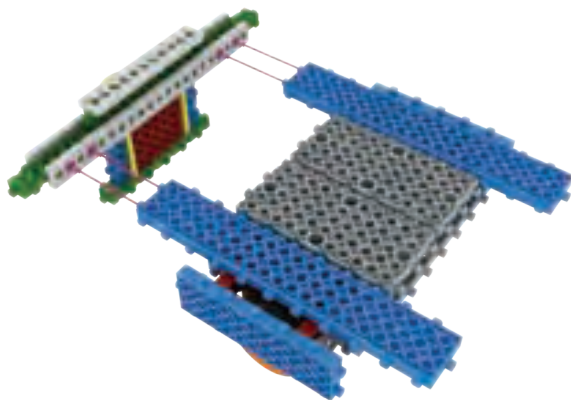
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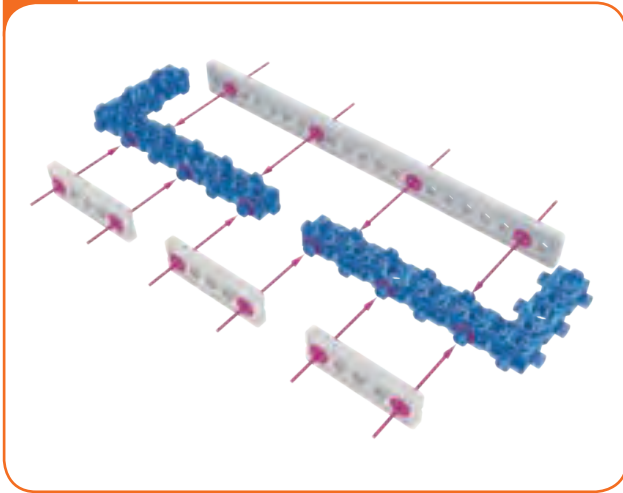
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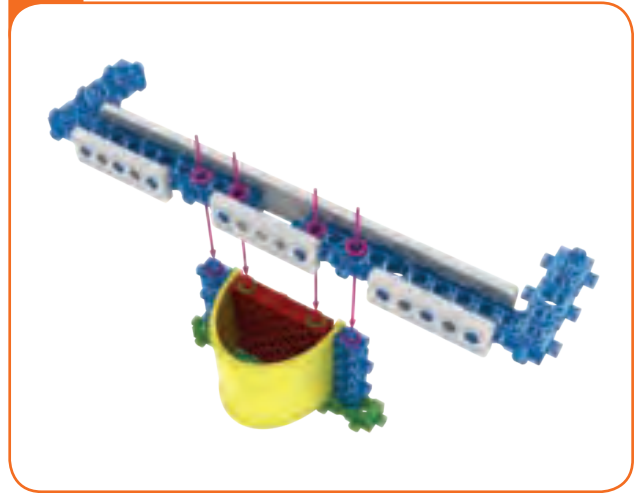
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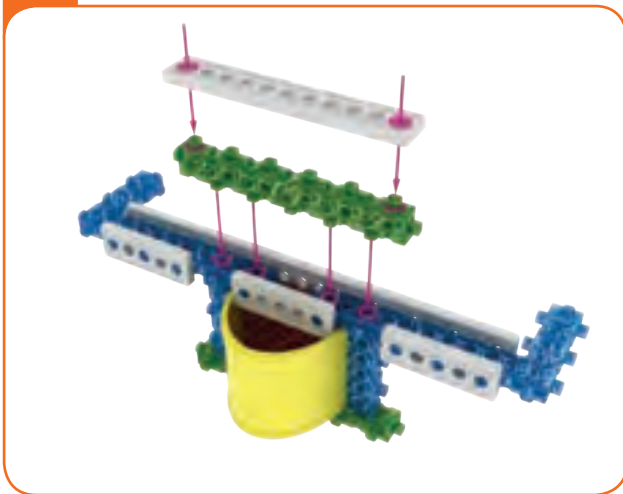
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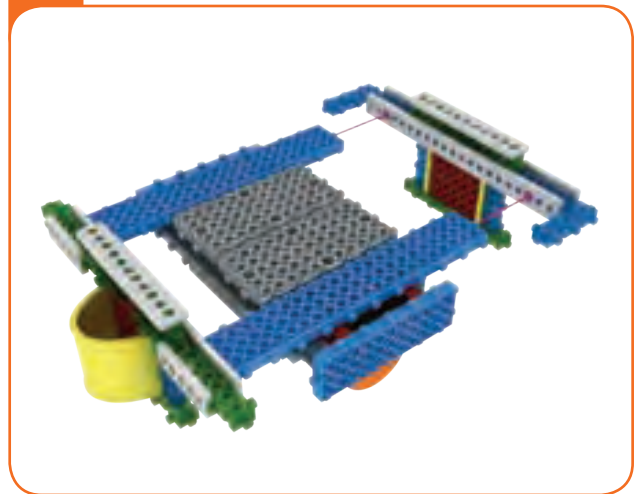
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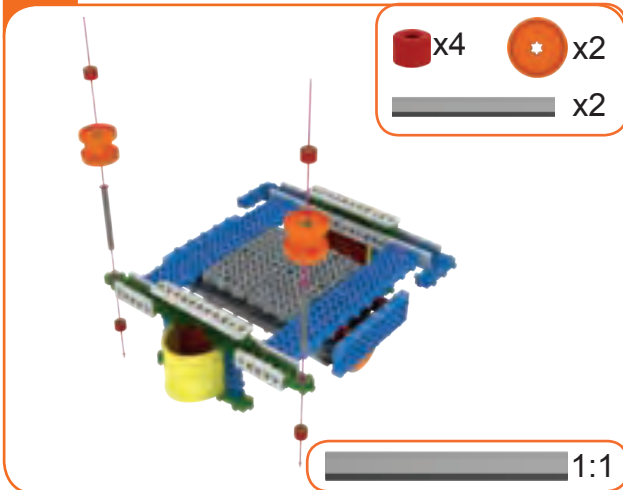
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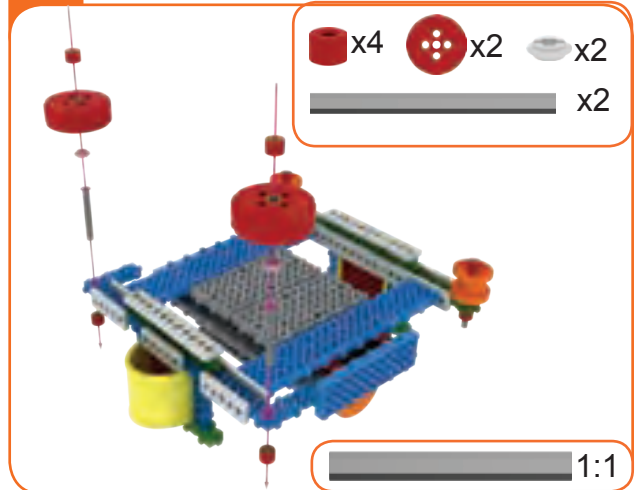
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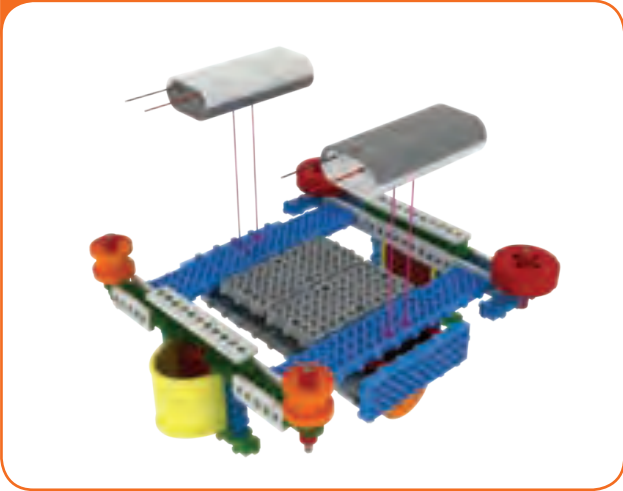
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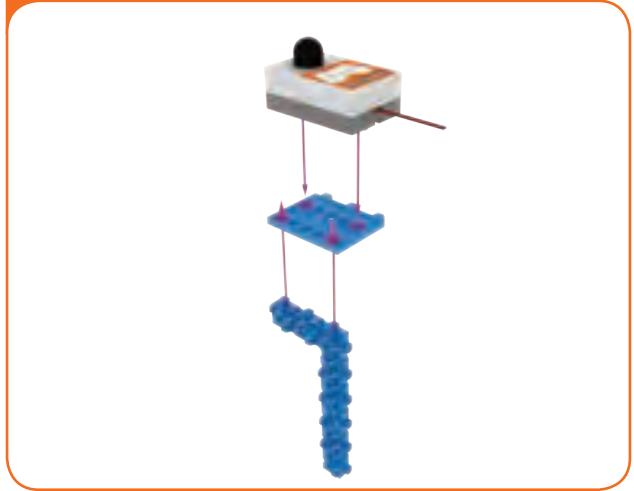
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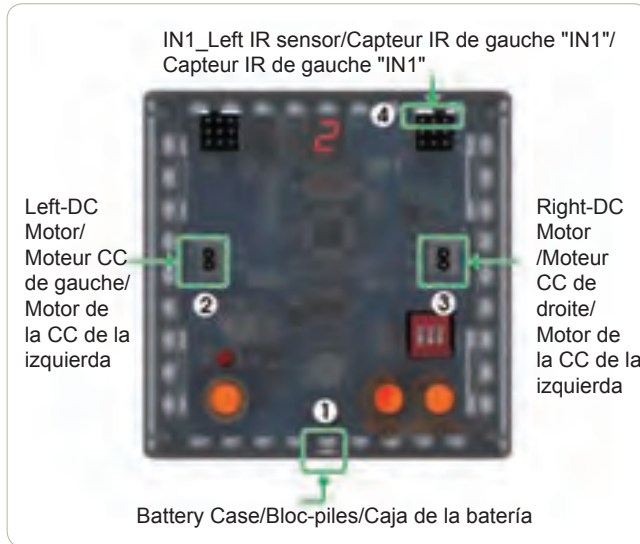


23



How to operate Bumper Car Comment faire fonctionner une auto tamponneuse Funcionamiento del coche de parachoques

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:



4. Press the START button.
5. Select Remote ID.

4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

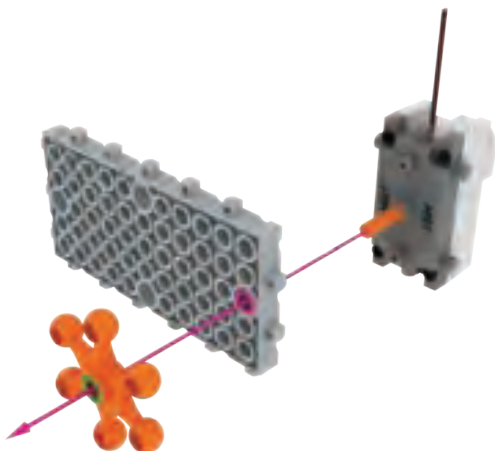
How to make it move? • Comment le faire bouger? • Cómo hacer que se mueva



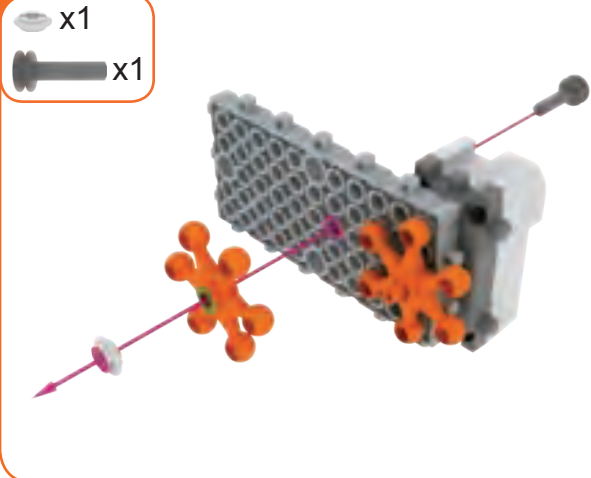
Robot 14: Boxing Robot
Robot 14 : Robot Boxeur
Robot 14: Boxeo Robot



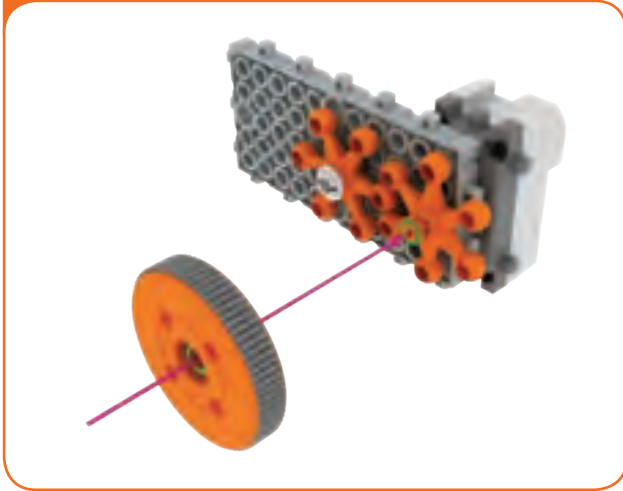
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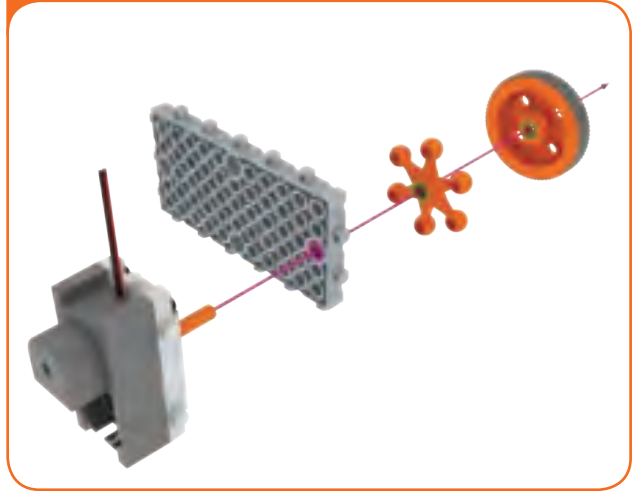
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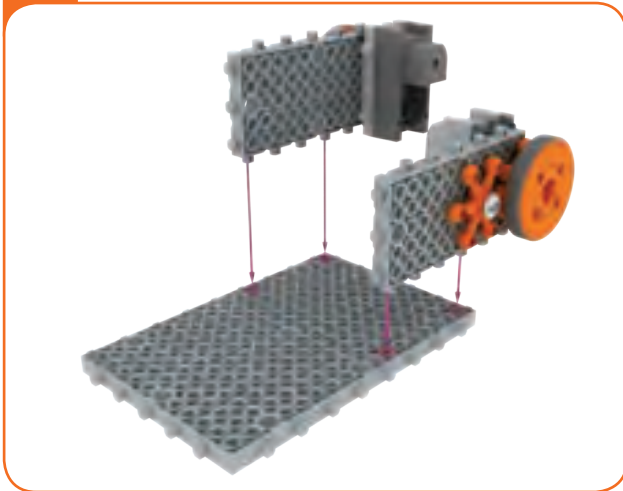
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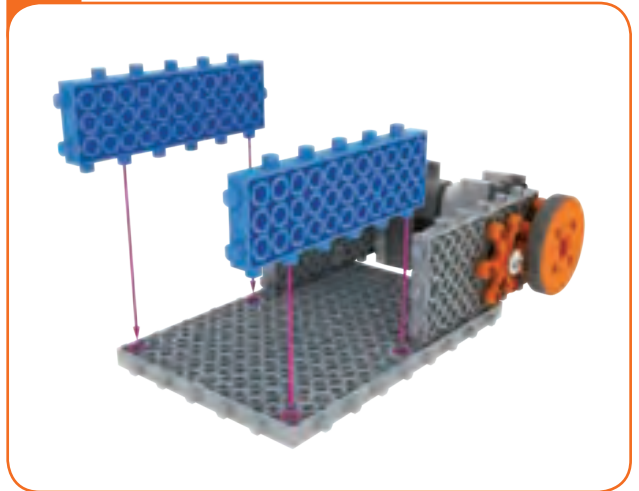
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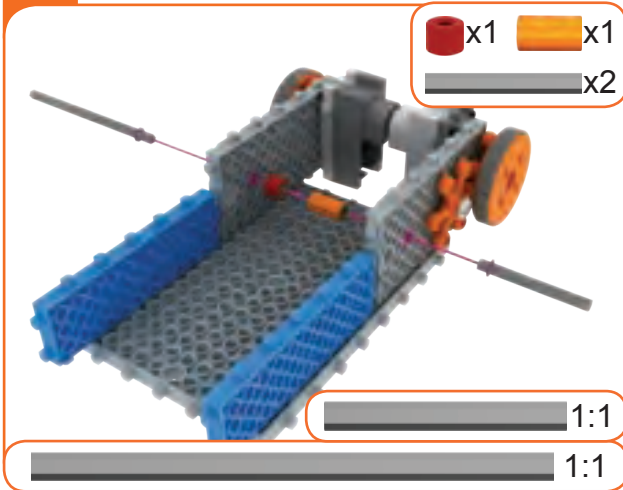
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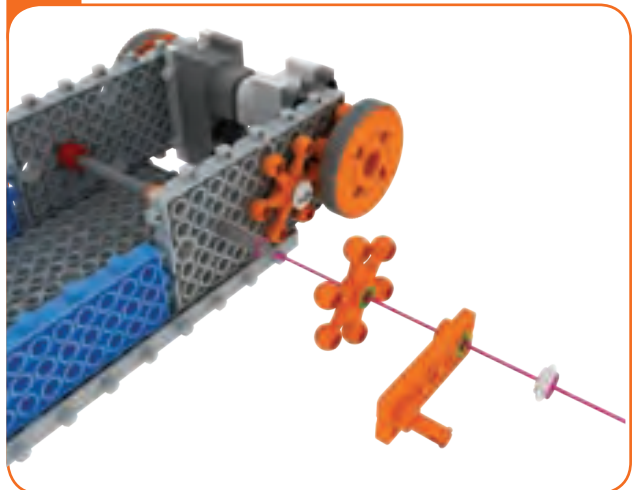
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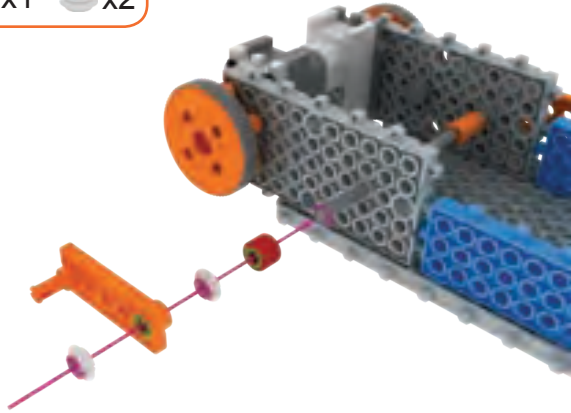


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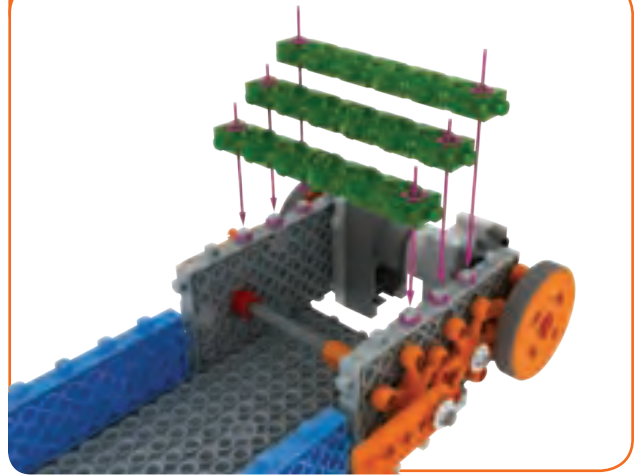


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x1 x2

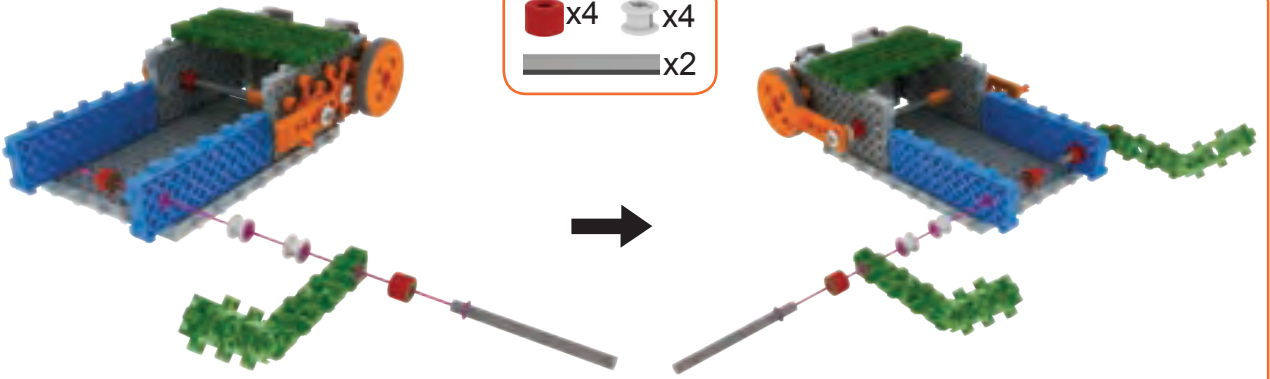


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11

x4 x4
x2

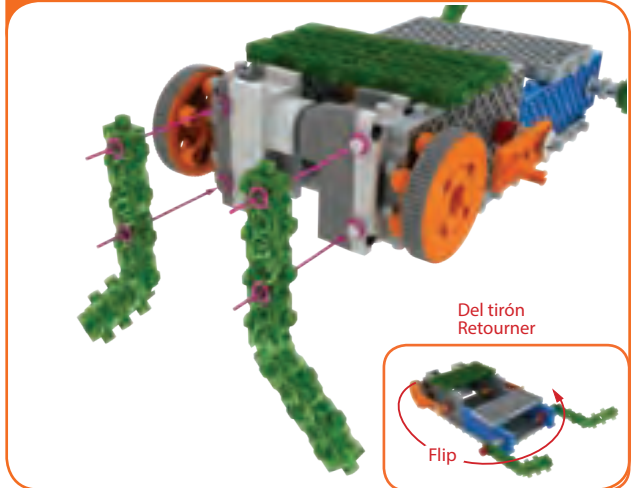


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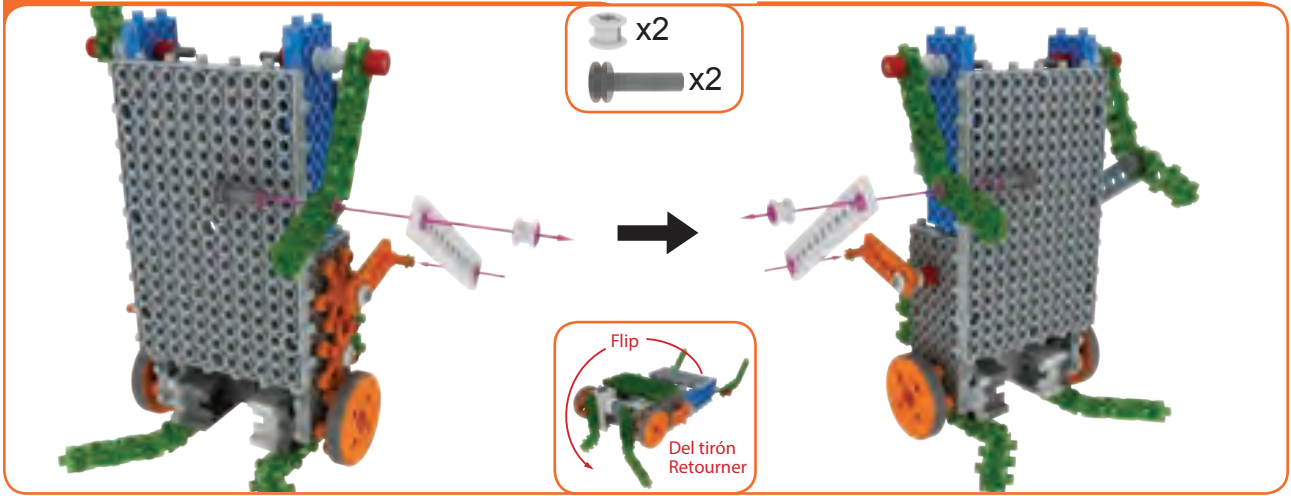
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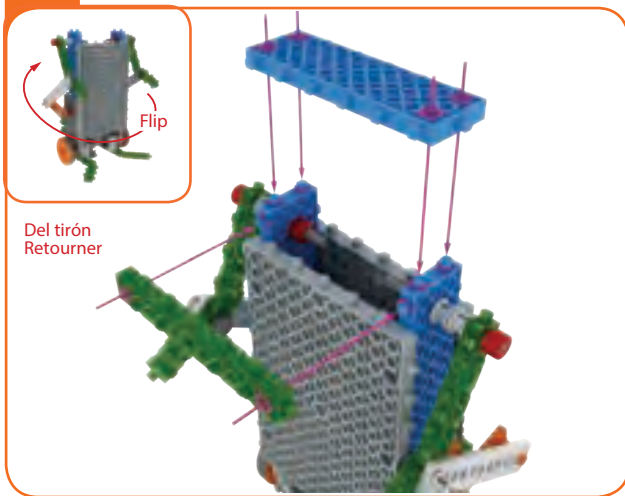
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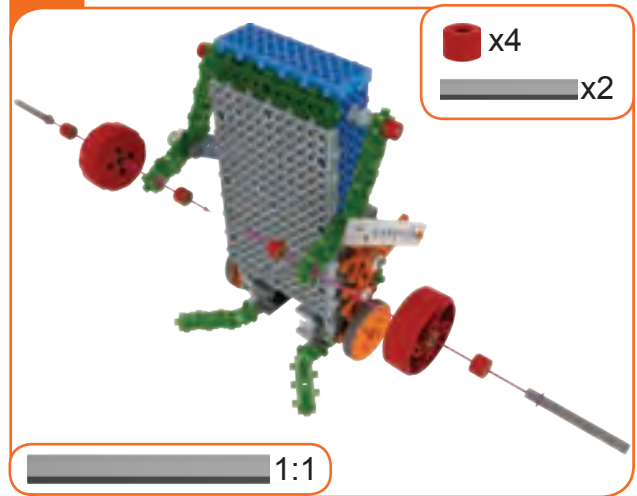
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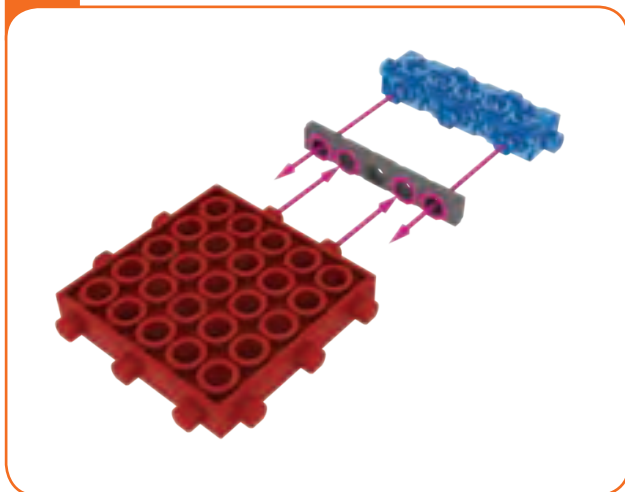
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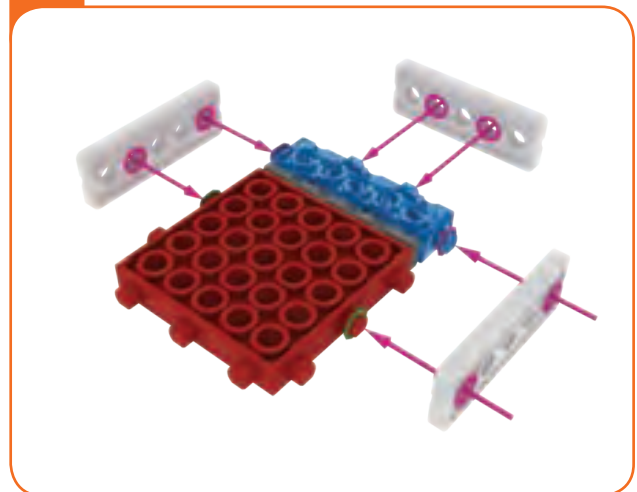
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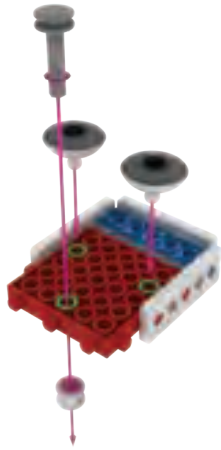


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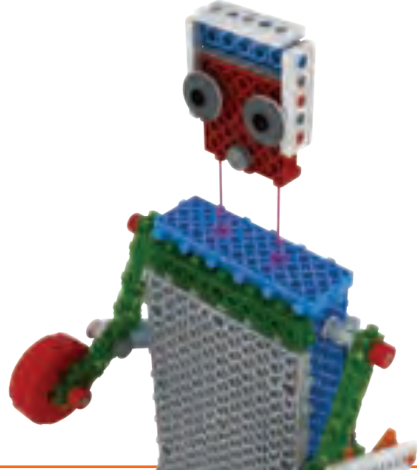


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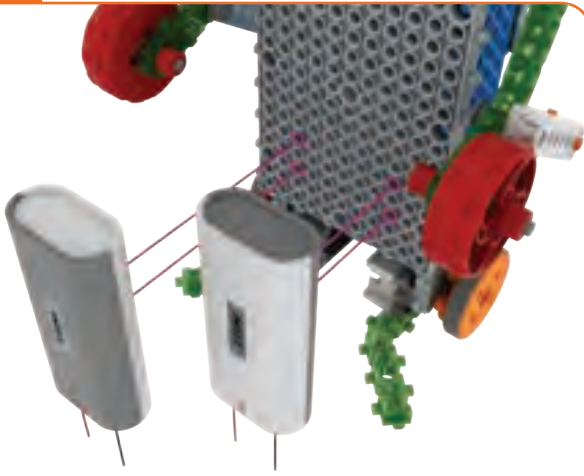
x1
x1



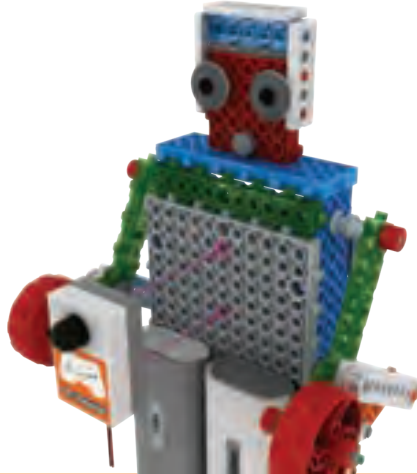
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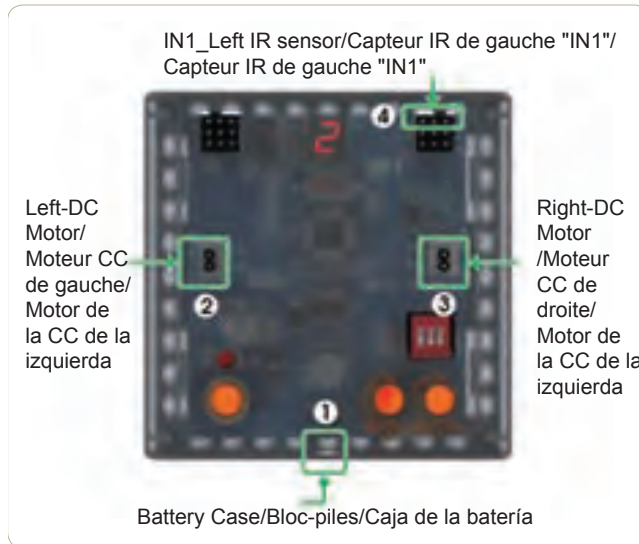
Del tirón
Retourner

24



How to operate Boxing Robot Comment faire fonctionner le robot boxeur Funcionamiento del Robot de boxeo

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:

MODE # 2



Remote control Mode

4. Press the START button.
5. Select Remote ID.

4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

How to make it move? • Comment le faire bouger? • Cómo hacer que se mueva

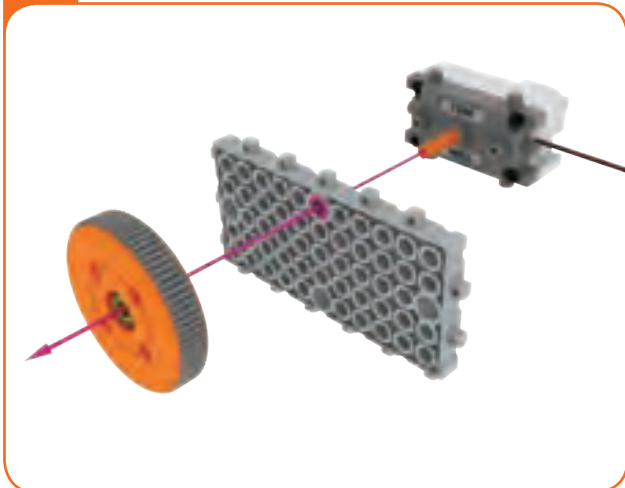
- ※ Play a boxing game with your friends.
- ※ Jouons un jeu de boxe en ami(e)s.
- ※ Jugar un juego de boxeo con tus amigos.



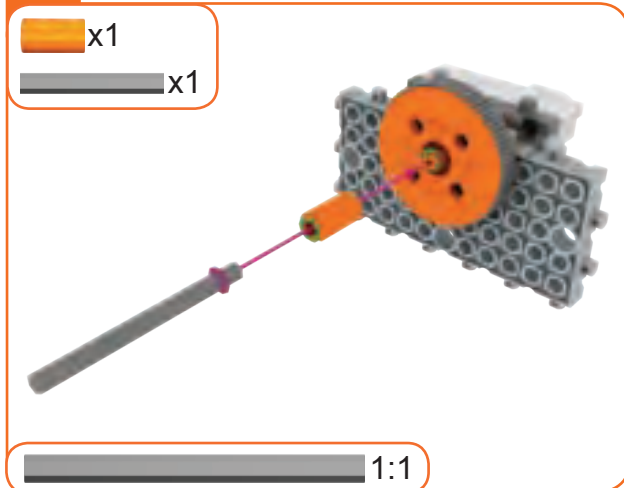
Robot 15: Battle Robot
Robot 15 : Bataille de robots
Robot 15: Robot de batalla



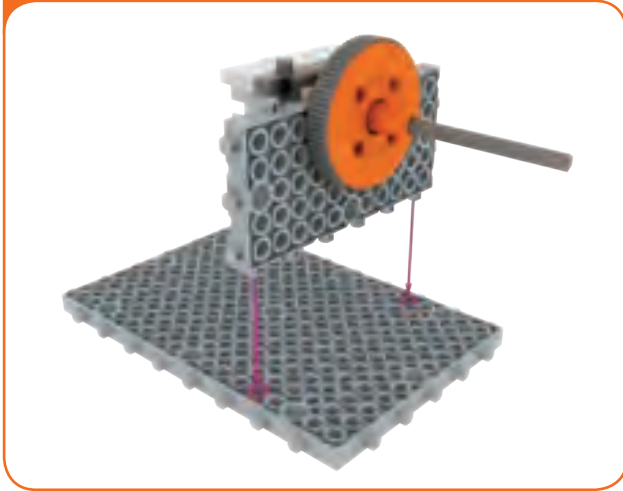
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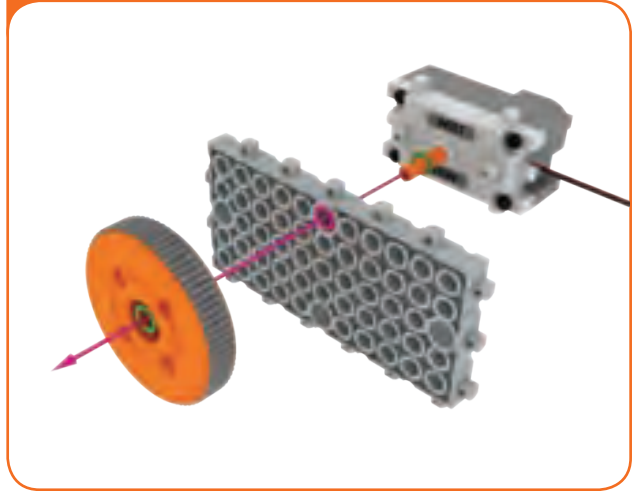
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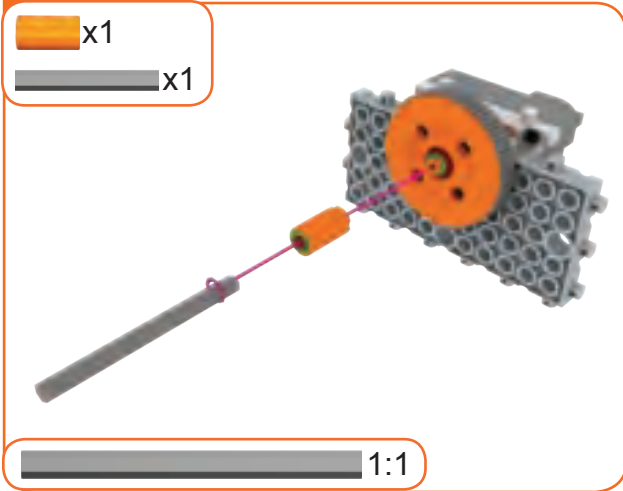
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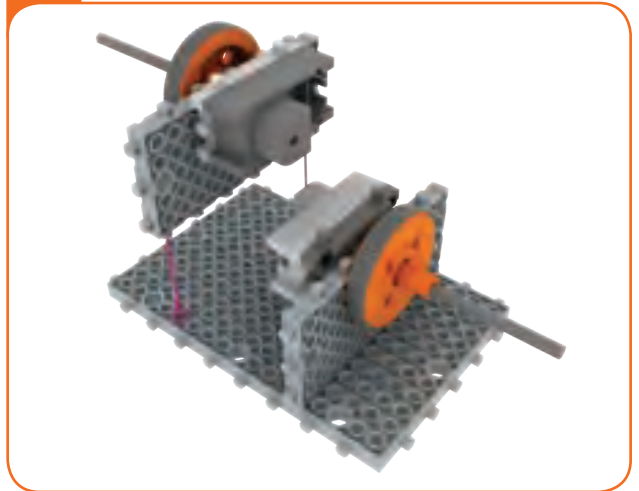
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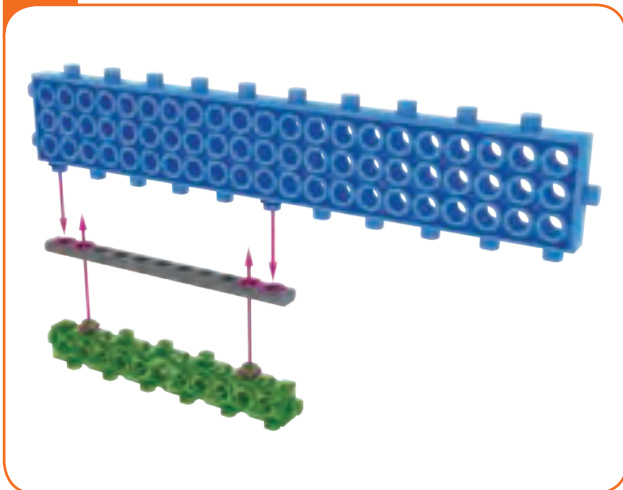
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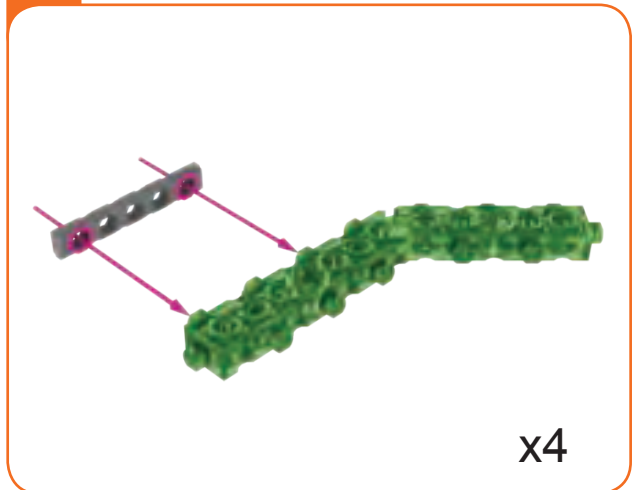
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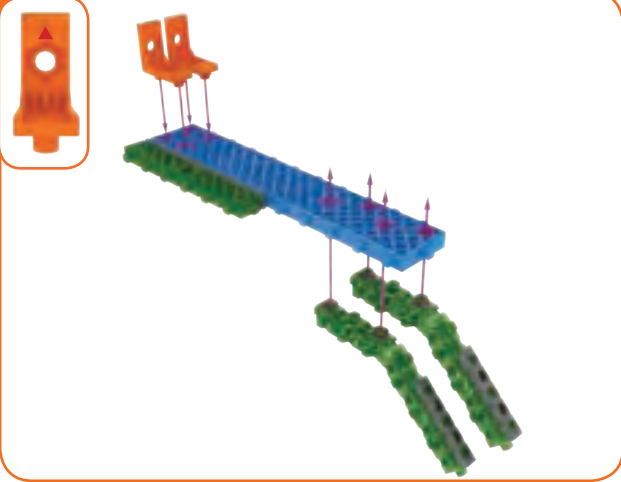
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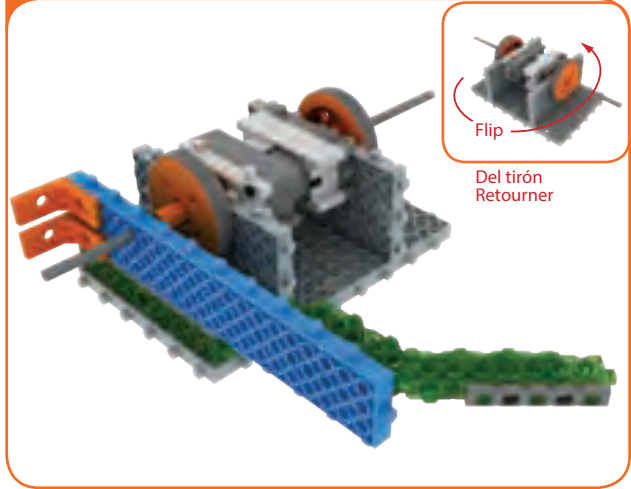
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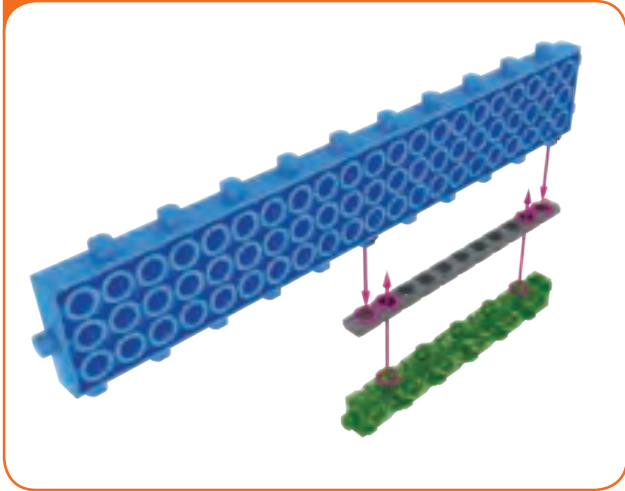
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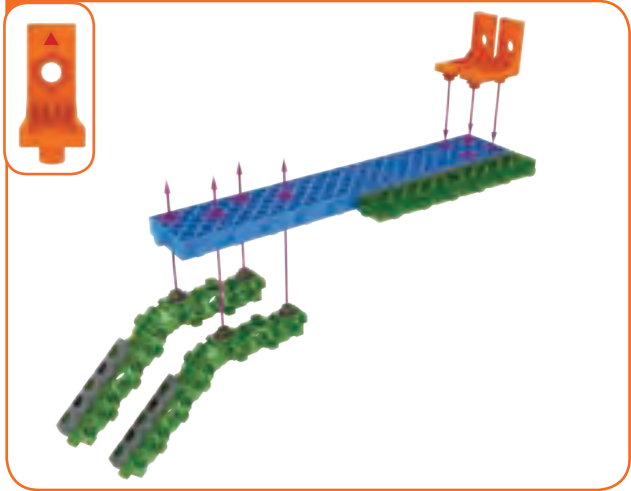
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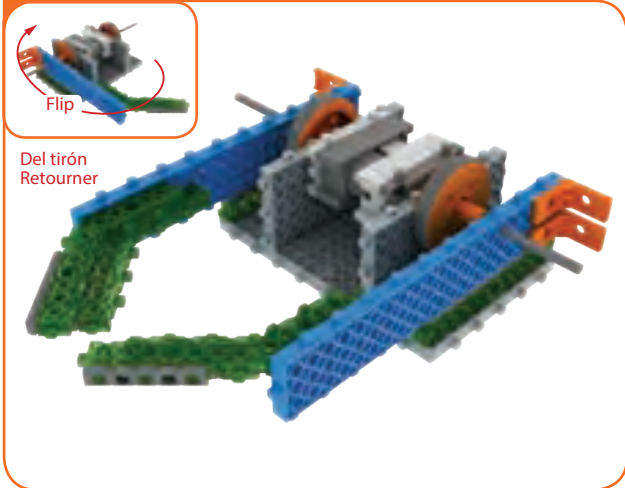
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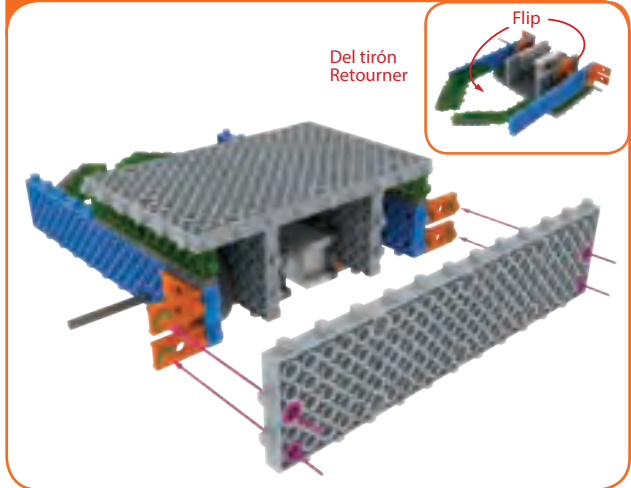
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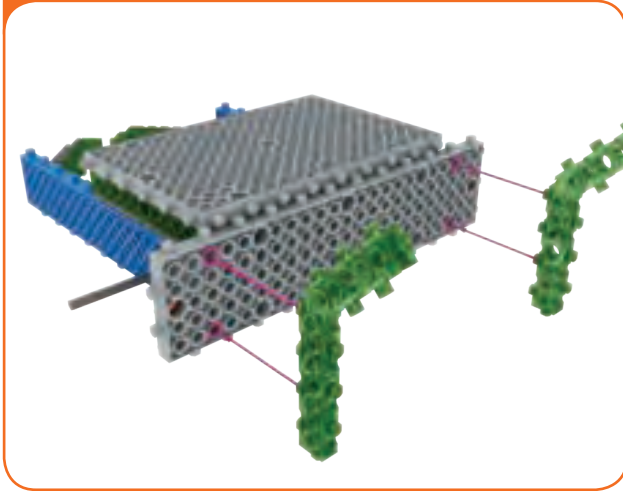
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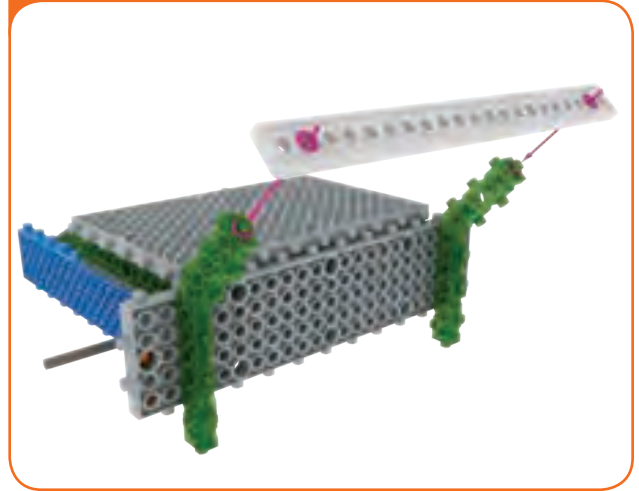
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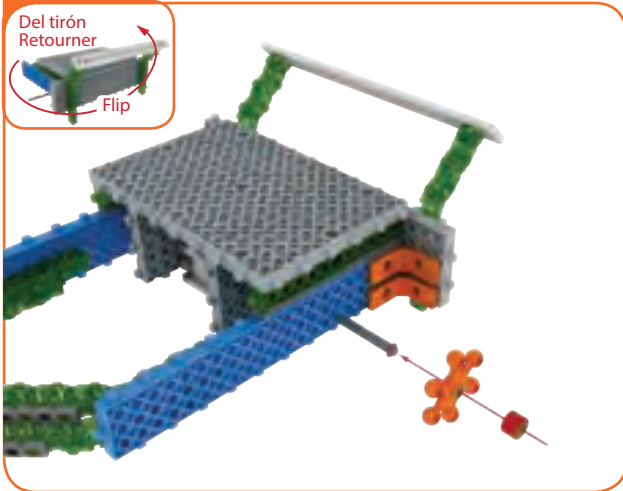
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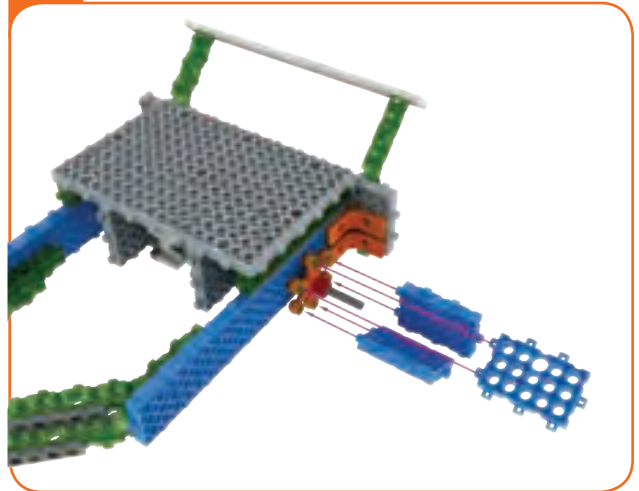
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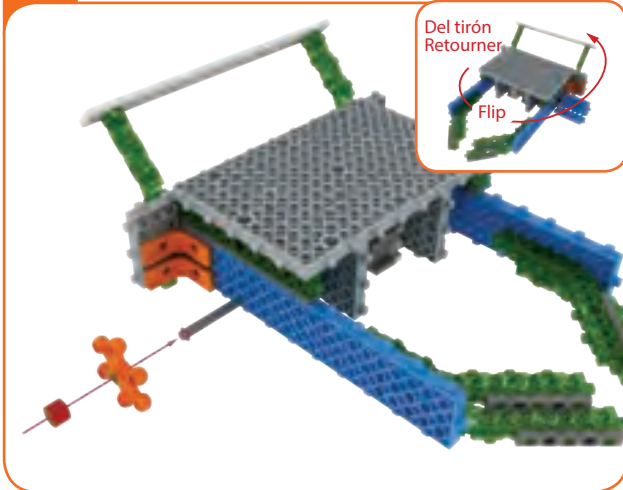
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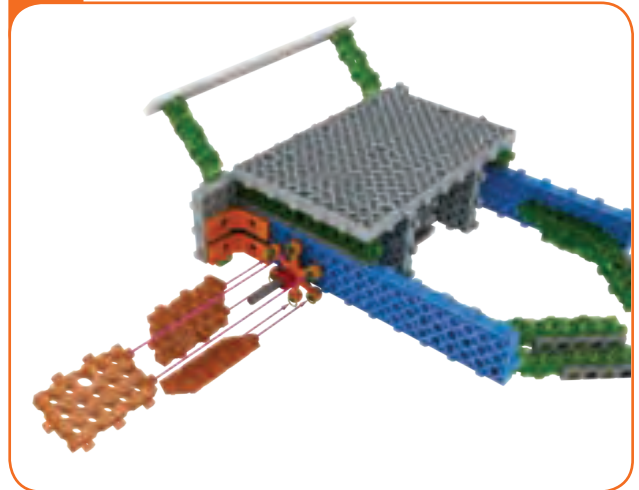
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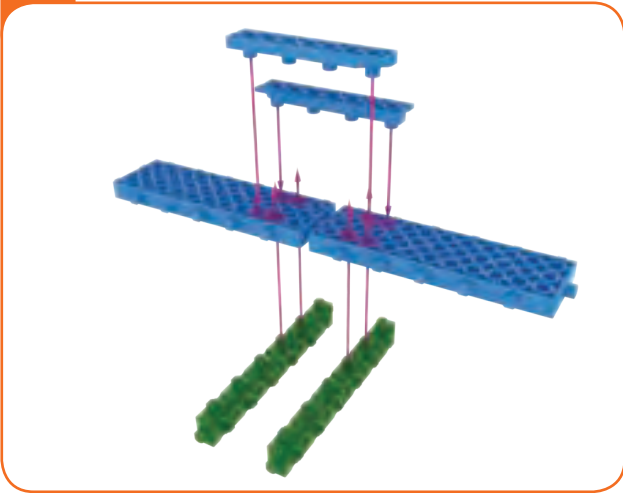
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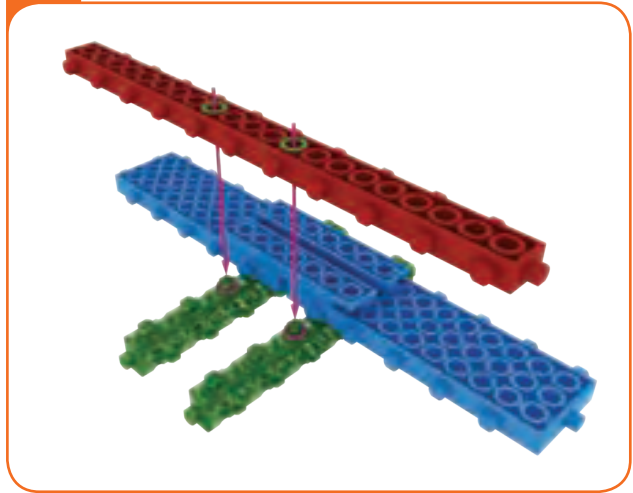
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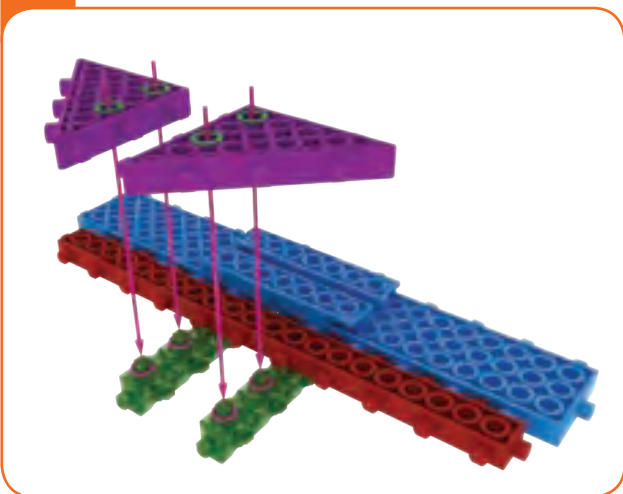
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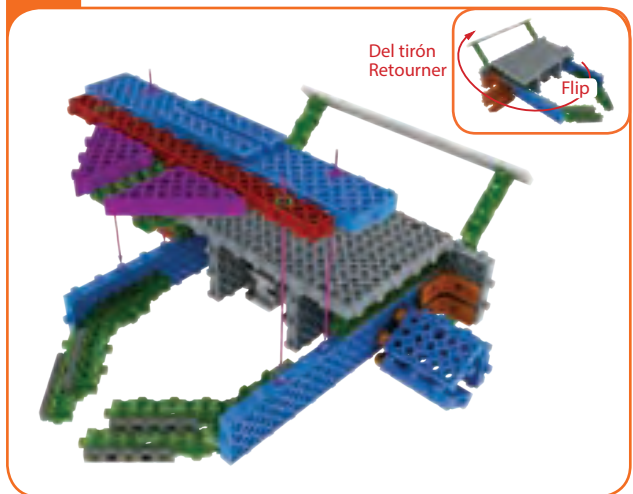
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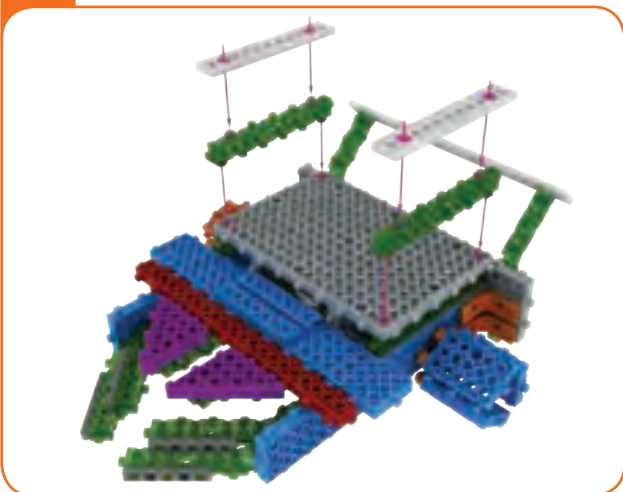
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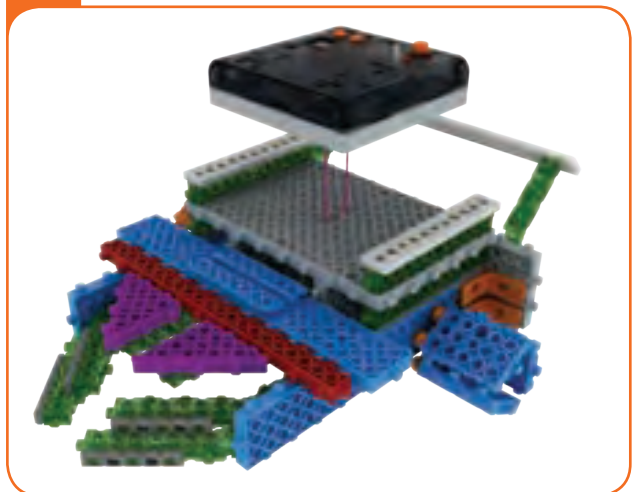
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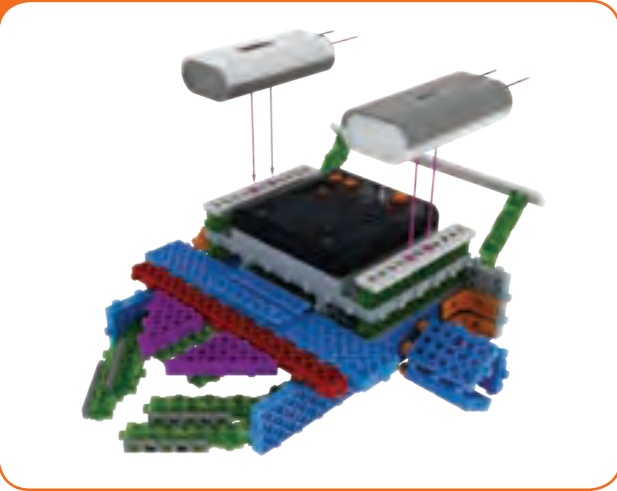
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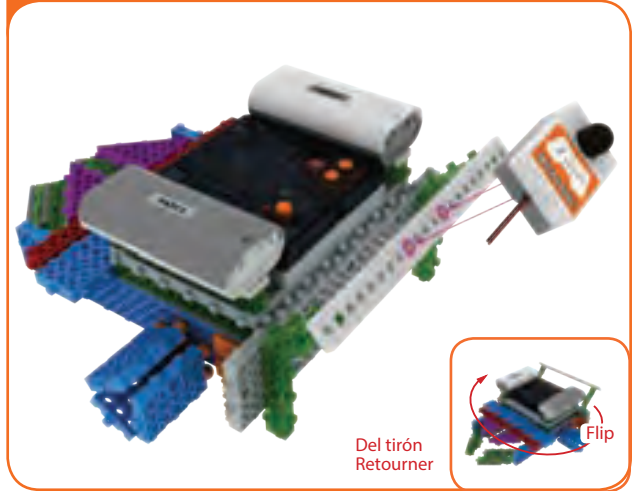
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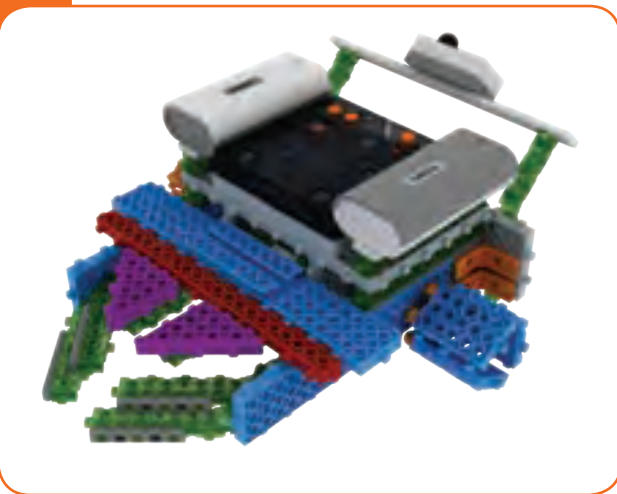
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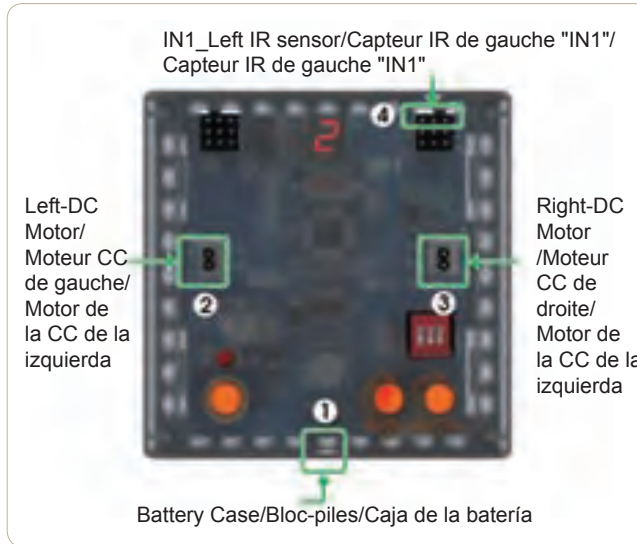


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How to operate Battle Robot Comment faire fonctionner le robot de combat Robot haciendo 15: Robot de batalla

Connecting the main board • Connexion au panneau principal • Conexión del panel principal



Connect in this order:

1. Connect Battery Cases to Power Connector.
2. Connect Left-DC Motor to Left-Motor Connector.
3. Connect Right-DC Motor to Right-Motor Connector.
4. Connect R/C Receiver Board to R/C Connector.

Effectuez les connexions dans l'ordre suivant :

1. Branchez le bloc-piles au connecteur d'alimentation.
2. Branchez le moteur CC de gauche à la prise du moteur CC de gauche.
3. Branchez le moteur CC de droite à la prise du moteur CC de droite.
4. Branchez le panneau récepteur pour la télécommande au connecteur du panneau récepteur pour la télécommande.

Conecte en este orden:

1. Conecte casos de batería al conector de alimentación.
2. Conectar el Motor de izquierda-CC al conector del Motor de la izquierda.
3. Conecte el Motor derecho-CC al conector derecho de Motor.
4. Conecte la tarjeta de R/C receptora al conector R/C.

Setting mode • Mode des réglages • Modo de ajuste

1. Ensure Battery Case/DC Motor Connector are connected.
2. Turn on the power.
3. Press the mode button and select the following:

1. Assurez-vous que les connecteurs du bloc-piles/moteur CC sont connectés.
2. Mettez l'alimentation en fonction.
3. Appuyez sur le bouton Mode et sélectionnez ce qui suit :

1. Asegúrese de que la batería caso/DC conector del Motor están conectados.
2. Encienda la alimentación.
3. Pulse el botón mode y seleccione los siguientes:

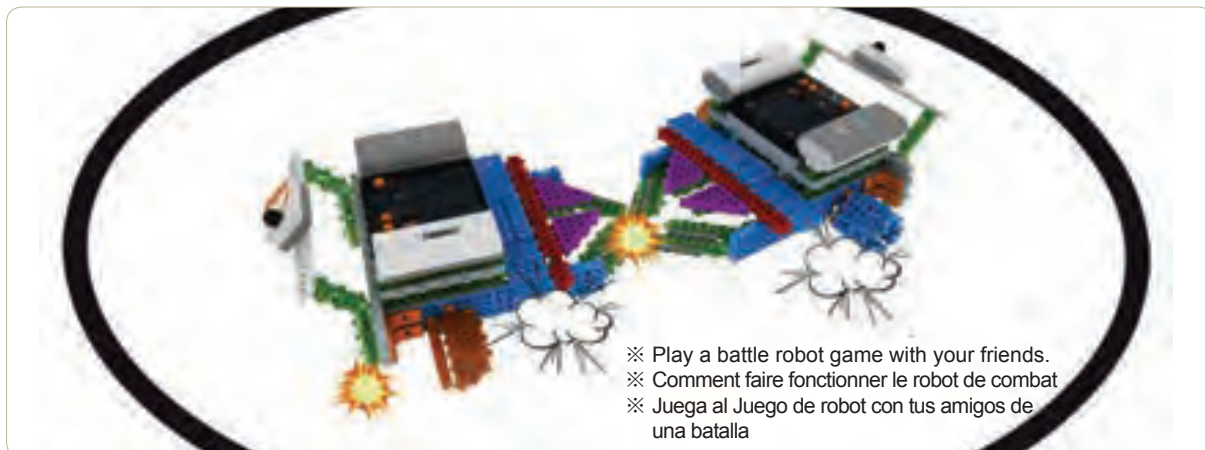


4. Press the START button.
5. Select Remote ID.

4. Sélectionnez l'identification de la télécommande.
5. Appuyez sur le bouton START.

4. Seleccione control remoto ID.
5. Presione el botón de inicio START.

How to make it move? • Comment le faire bouger? • Cómo hacer que se mueva



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